

# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES: CASE STUDIES

INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 2 – MAY 7, 2014



# ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs  
April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies  
May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ Critical Infrastructure Elements for SPMs  
June 11, 2014, 12:00 pm to 1:30 pm. Eastern

# Automated Traffic Signal Performance Measures

## Technology Implementation Group: 2013 Focus Technology

<http://tig.transportation.org>

Mission: Investing time and money to accelerate technology adoption by agencies nationwide



# Your Speakers Today



Jamie Mackey, UDOT



Amanda Stevens, INDOT



Alex Hainen, Purdue



Steve Misgen, MnDOT



Rick Denney, FHWA



Moderator



# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: UDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014

PRESENTED BY JAMIE MACKEY, UDOT

# Automated Signal Performance Measures Goals

- ▶ Operate & optimize system without field data collection
- ▶ Catch problems as they happen
- ▶ Retime signals as needed, not on a schedule
- ▶ Communicate signal/corridor/system performance to public & agency leaders


->Signal Metrics

Selected Signal  
 No Signal Selected

Signals  
Region   
Metric Type   
Filter

**Signal List**

**Map**



Metric Settings

Metric Type

☐ Approach Delay ☐ Purdue Phase Termination  
☐ Approach Volume ☐ Speed  
☐ Arrivals On Red ☐ Split Monitor  
☒ Purdue Coordination Diagram ☐ Turning Movement Counts

Time Y Axis Maximum   
Volume Y Axis Maximum   
Volume Bin Size   
Dot Size   
☒ Show Plan Statistics  
☒ Show Volumes  
[Export Data](#)  
☐ Upload Current Data

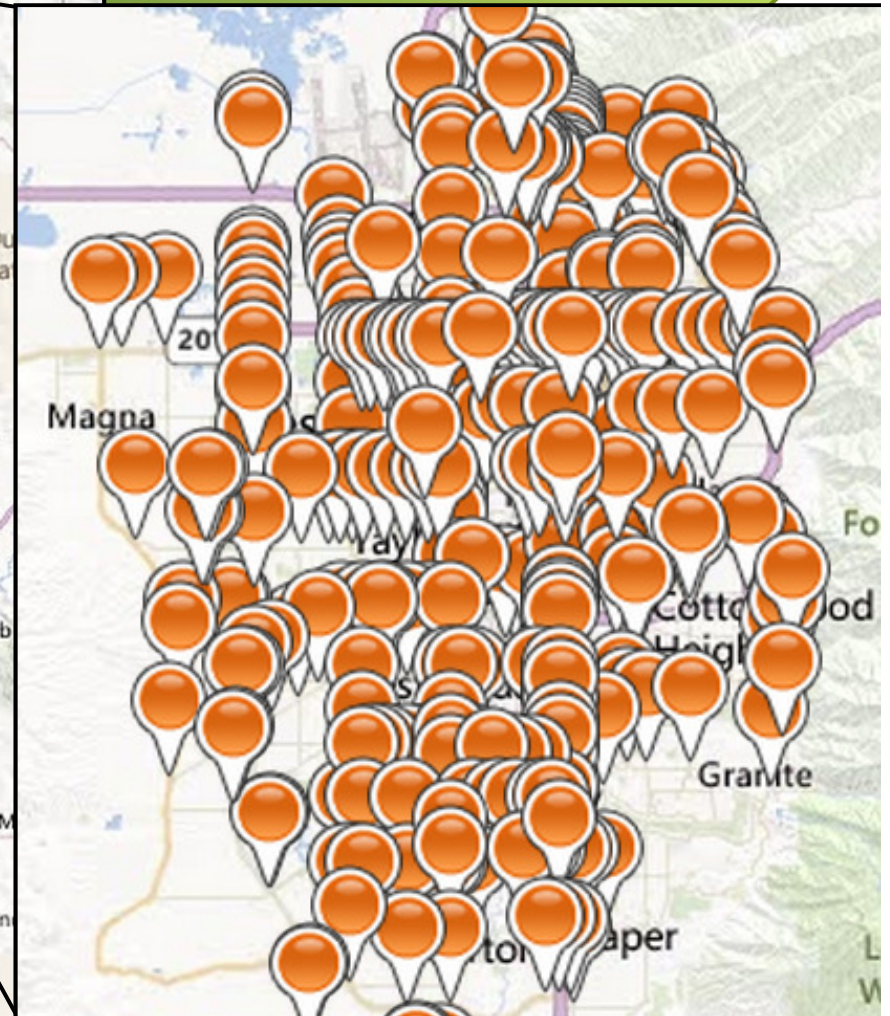
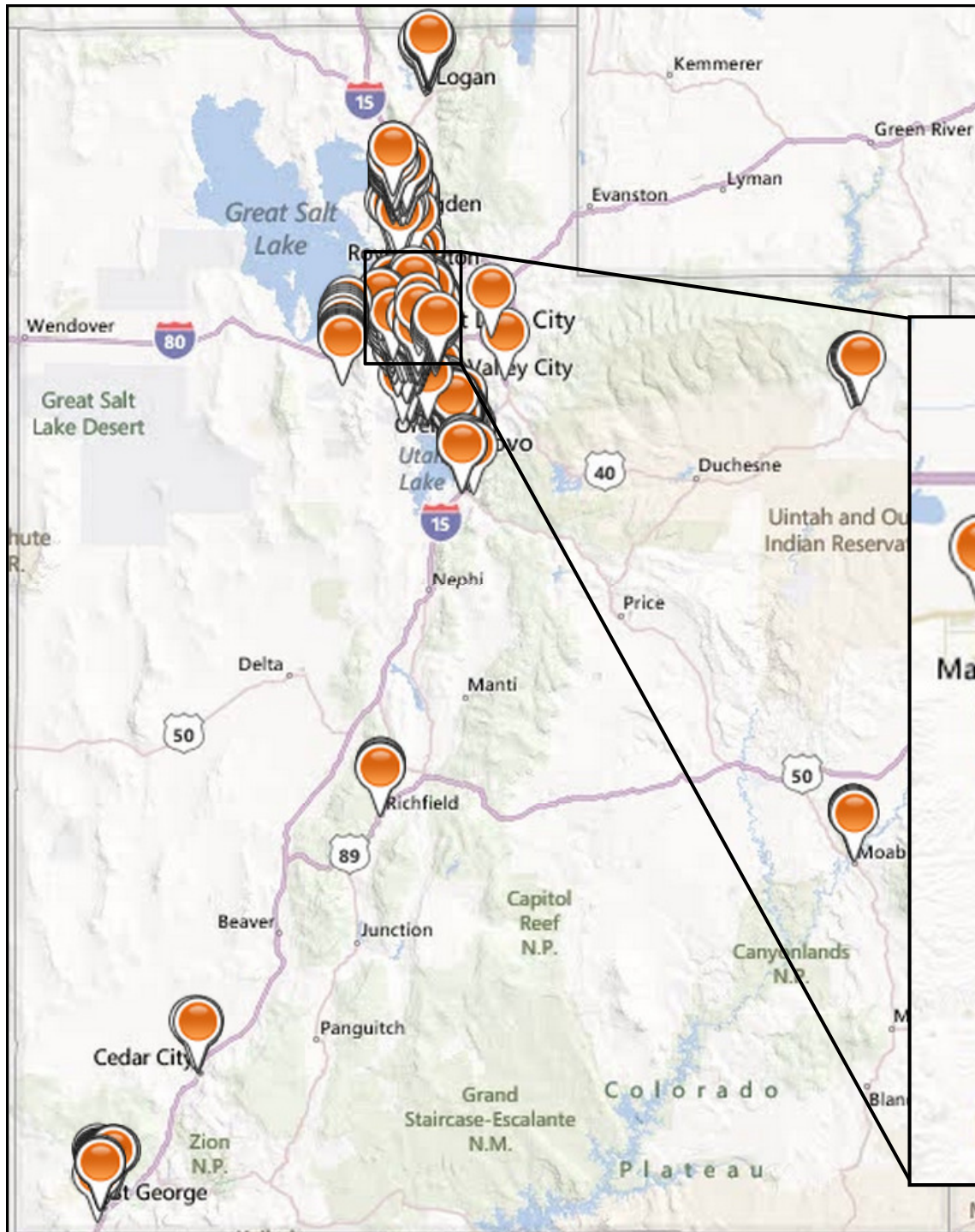
Dates  
Start Date   AM  
End Date   PM  
  January 2014

Sun	Mon	Tue	Wed	Thu	Fri	Sat
29	30	31	1	2	3	4
5	6	7	8	9	10	11
12	13	14	15	16	17	18
19	20	21	22	23	24	25
26	27	28	29	30	31	1
2	3	4	5	6	7	8

<http://udottraffic.utah.gov/signalperformancemetrics>



# Salt Lake Valley



# Metrics & Detection Requirements



## Controller high-resolution data only

Purdue Phase Termination

Split Monitor

## Advanced Count Detection (~400 ft behind stop bar)

Purdue Coordination Diagram & Arrivals on Red

Approach Volume

Approach Delay

Executive Summary Reports

## Advanced Detection with Speed

Approach Speed

## Lane-by-lane Presence Detection

Split Failure (future)

## Lane-by-lane Count Detection

Turning Movement Counts

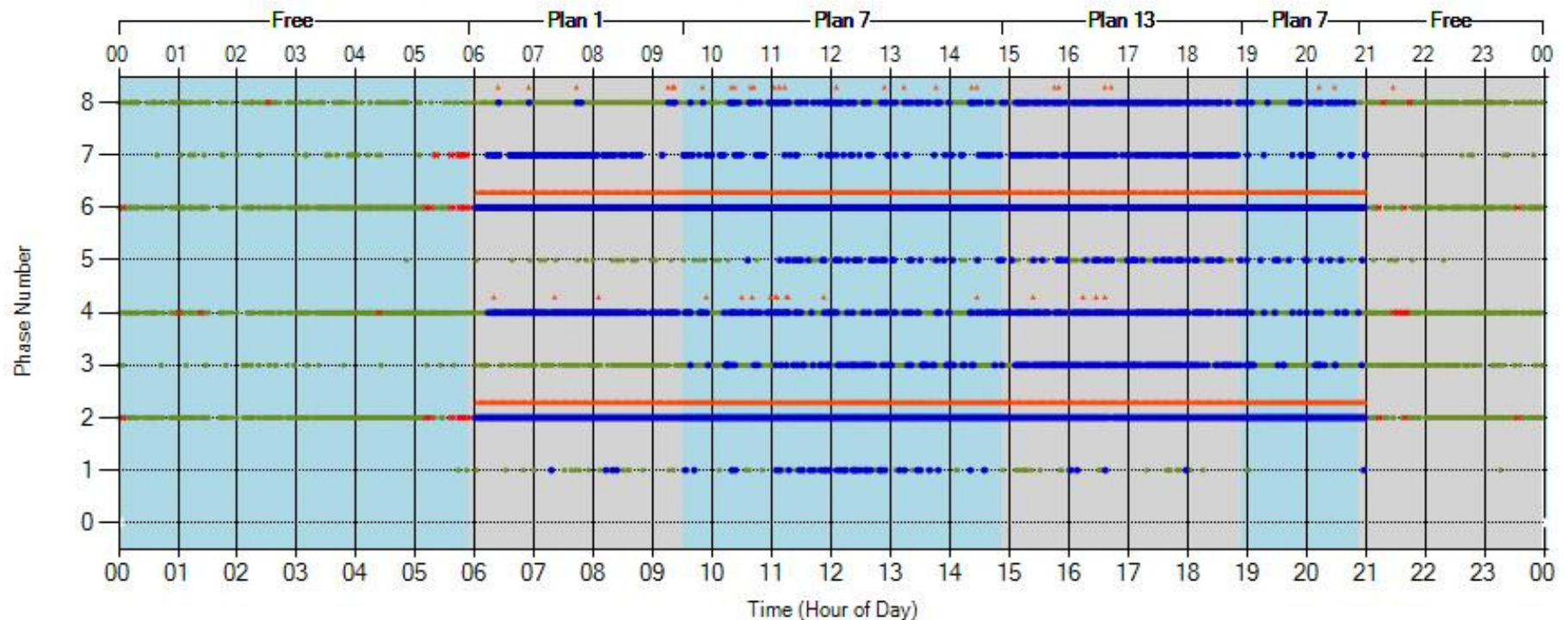
## Probe Travel Time Data (GPS or Bluetooth)

Purdue Travel Time Diagram



# Normal Intersection Example: Phase Termination Chart

- 24-hours of phase data at an 8-phase signal with working detection



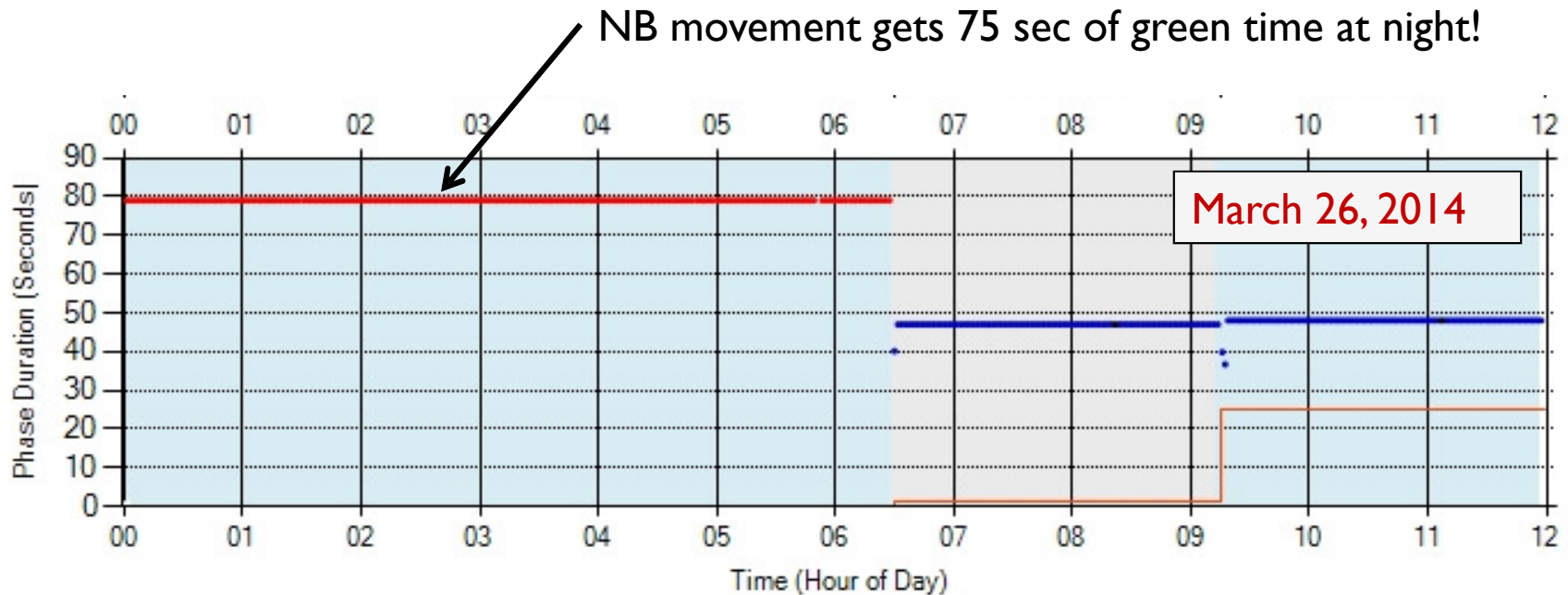
- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**



# Complaint Example: Red light too long

- Max recall was placed for broken NB detection

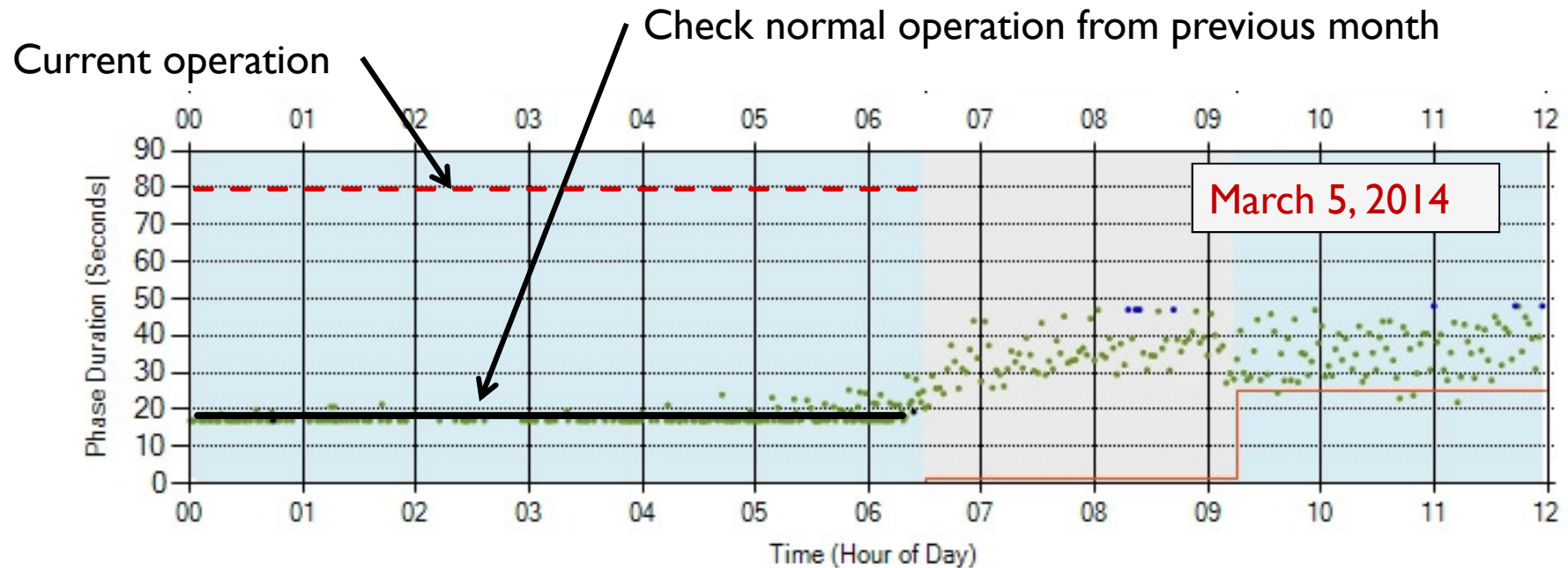


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

# Complaint Example: Red light too long

- Max recall was placed for broken NB detection

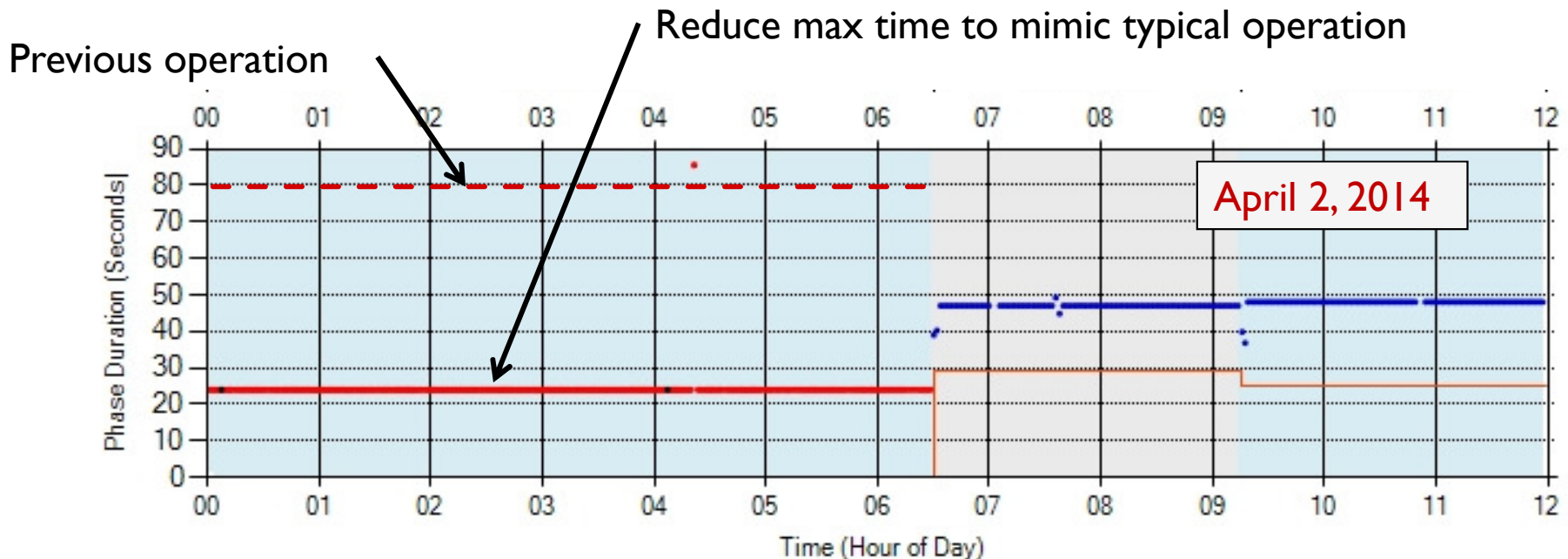


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

# Complaint Example: Red light too long

- Max recall was placed for broken NB detection



- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

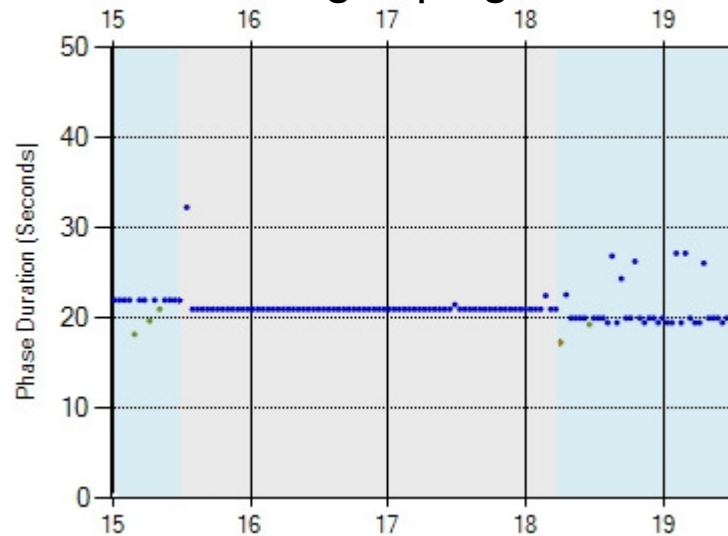
# Complaint Example: Split too short

► Is this a timing or a maintenance issue?

Timing Issue:

Phase always forces off

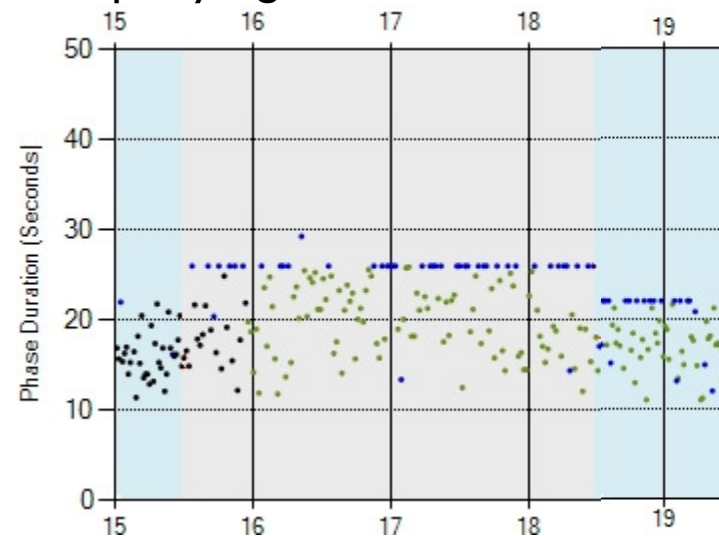
=> Phase is using all programmed time



Maintenance Issue:

Phase often gaps out

=> Spotty right-turn lane detection

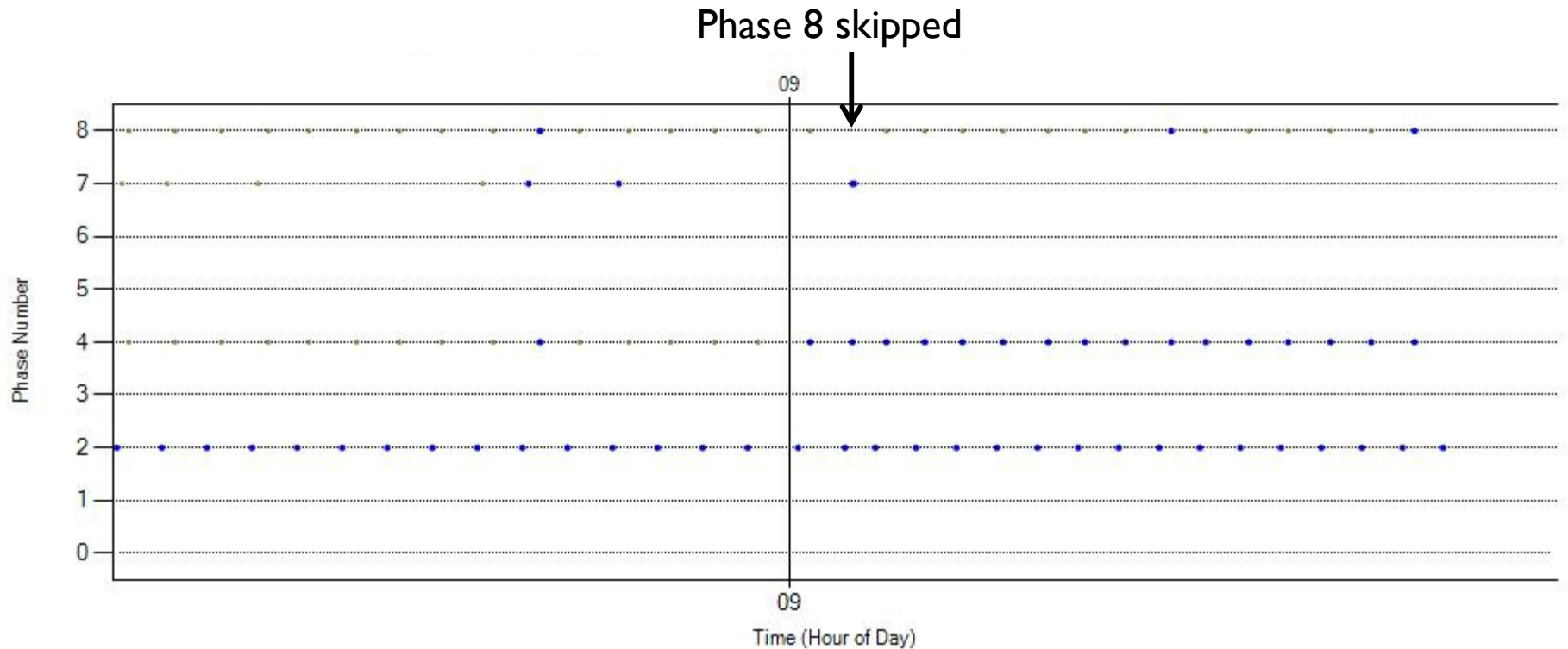


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

# Complaint Example: Phase skipped

- SPMs confirm it was a fluke

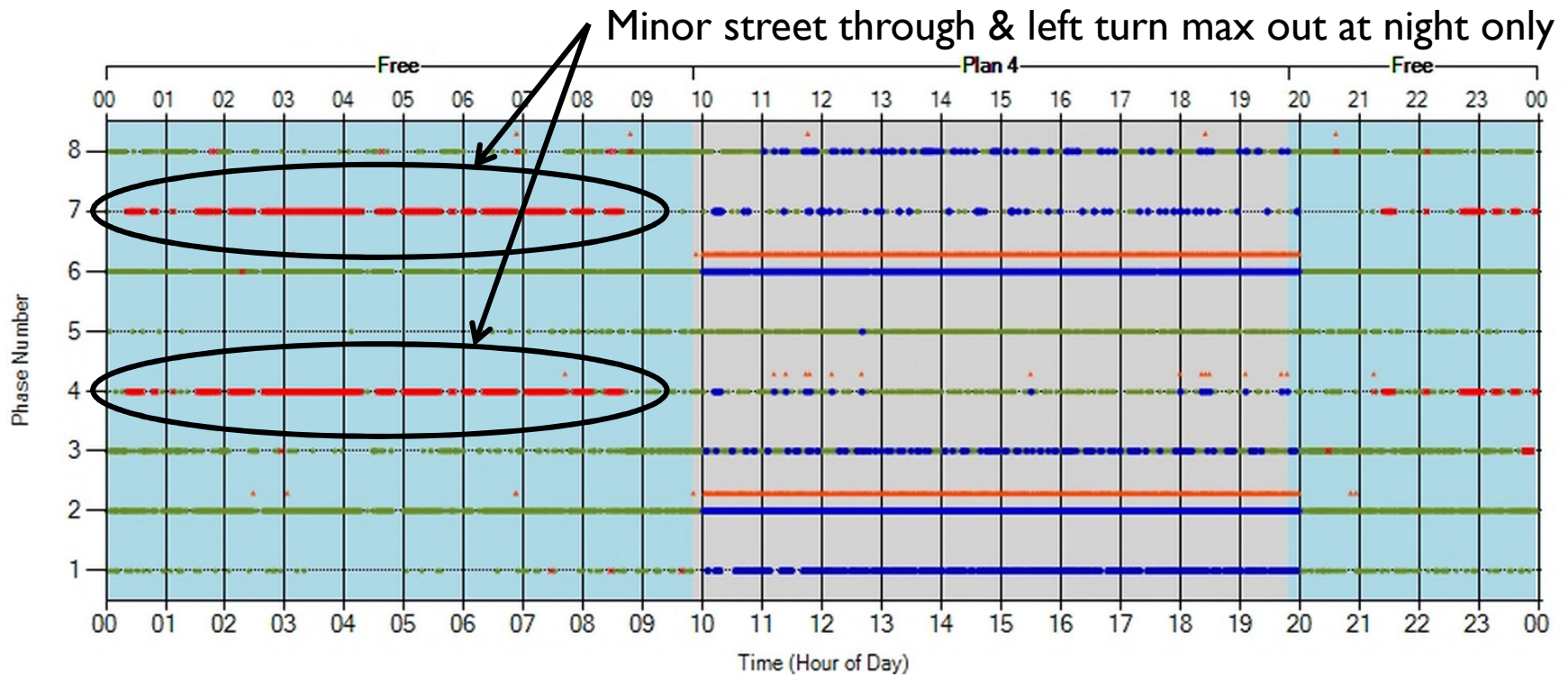


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Nighttime detection problem

- BEFORE: Video detection not working at night



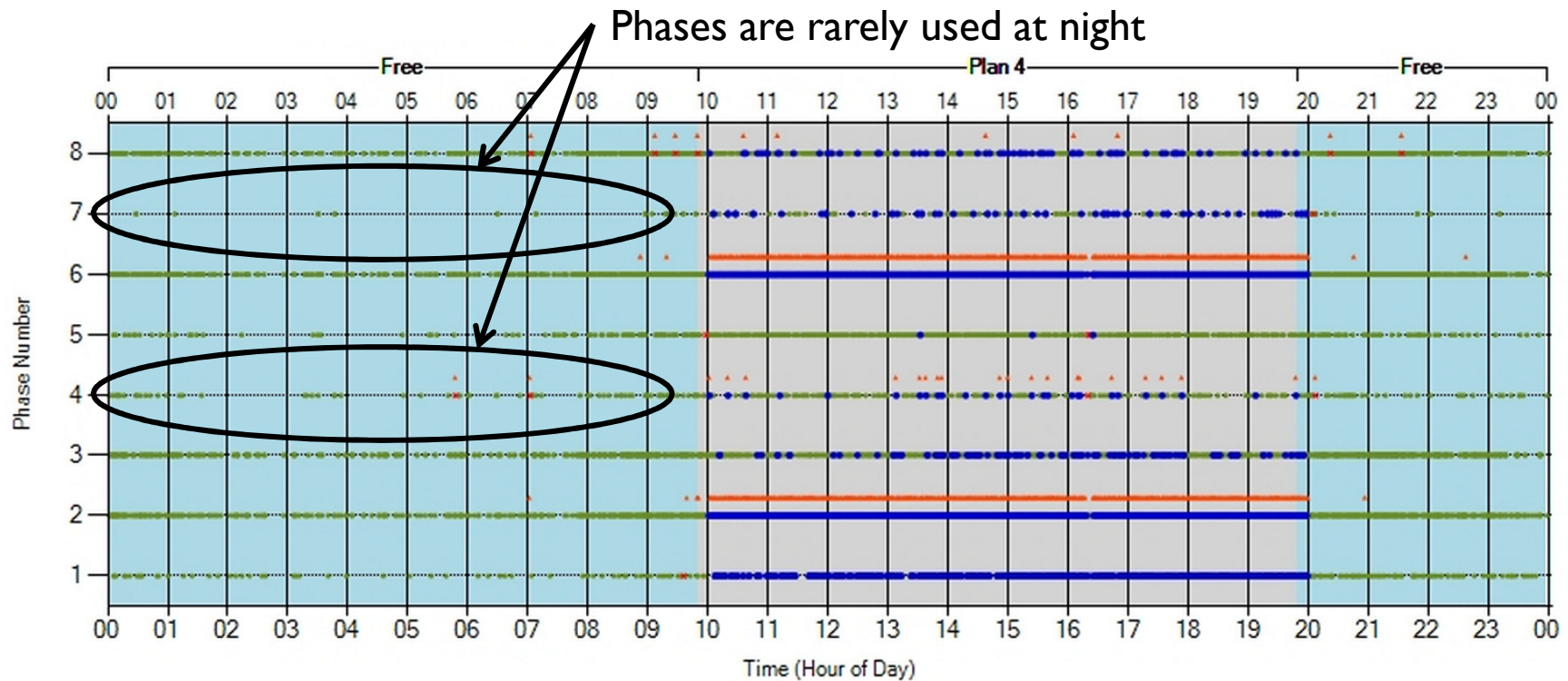
- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**



# Maintenance Example: Nighttime detection problem

- AFTER: New detection technology installed

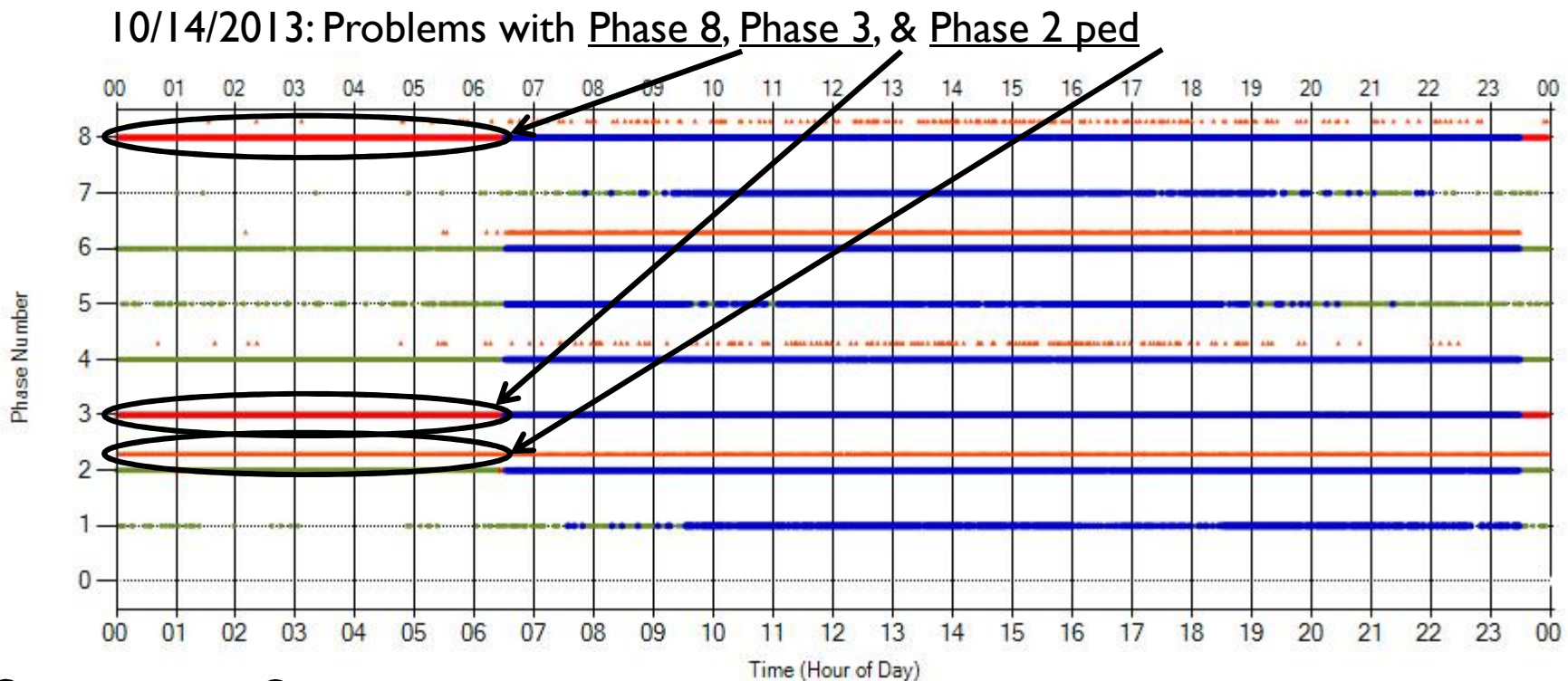


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Check for additional problems

- Phase 2 ped problem was not noticed at field visit



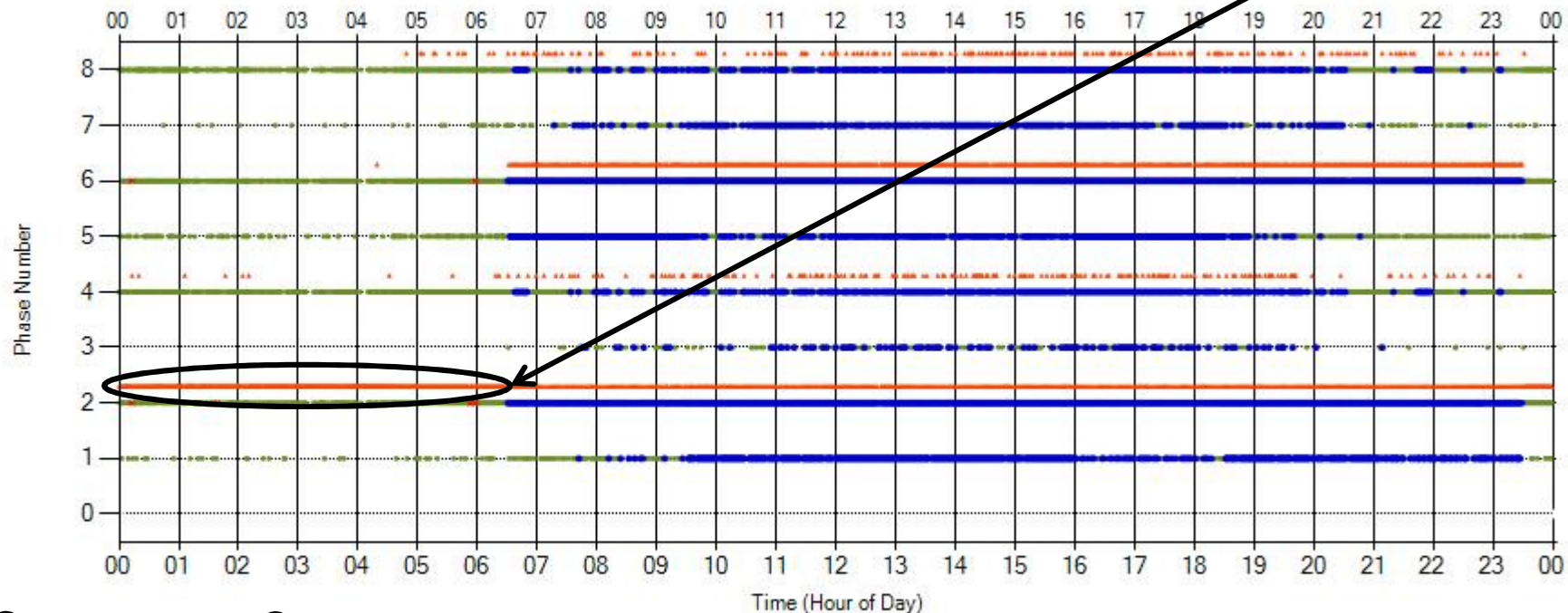
- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Check for additional problems

- Phase 2 ped problem was not noticed at field visit

10/21/2013: Phase 3 & 8 problems were fixed, but not Phase 2 ped

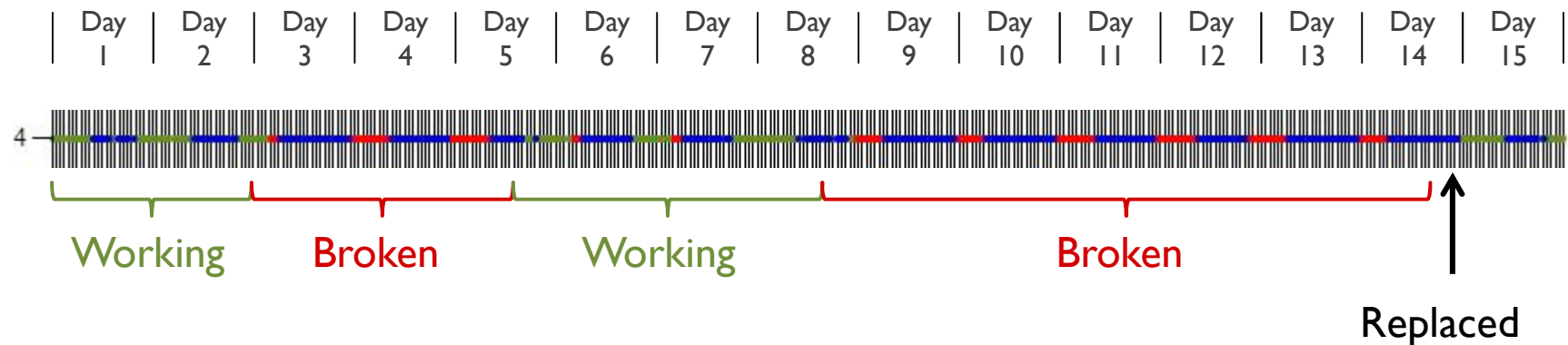


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Detection Upgrade Justification

- Document recurring detection problems




- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**

# Alert Example: 100% Max Out



SPM Alerts for 4/9/2014

 SPMWatchDog@utah.gov

- 5092 - SR-126 (1900 W) & Riverdale (5300 S) (Roy) - Phase: 1
- 5105 - Antelope (SR-108/2000 N) & I-15 NB (Layton) - Phase: 4
- 6022 - US-89 & Pacific Dr (American Fork) - Phase: 3
- 6305 - 400 East & 800 North - Phase: 4 ← Example
- 6310 - Center Street (Orem) & I-15 SPUI - Phase: 8
- 7055 - Bangerter Hwy (SR-154) & SR-201 DDI - Phase: 5
- 7062 - Bangerter Hwy (SR-154) & 4700 South - Phase: 11
- 7613 - 10600 South & 700 West - Phase: 8
- 8114 - Bluff Street & I-15 NB Ramps - Phase: 4

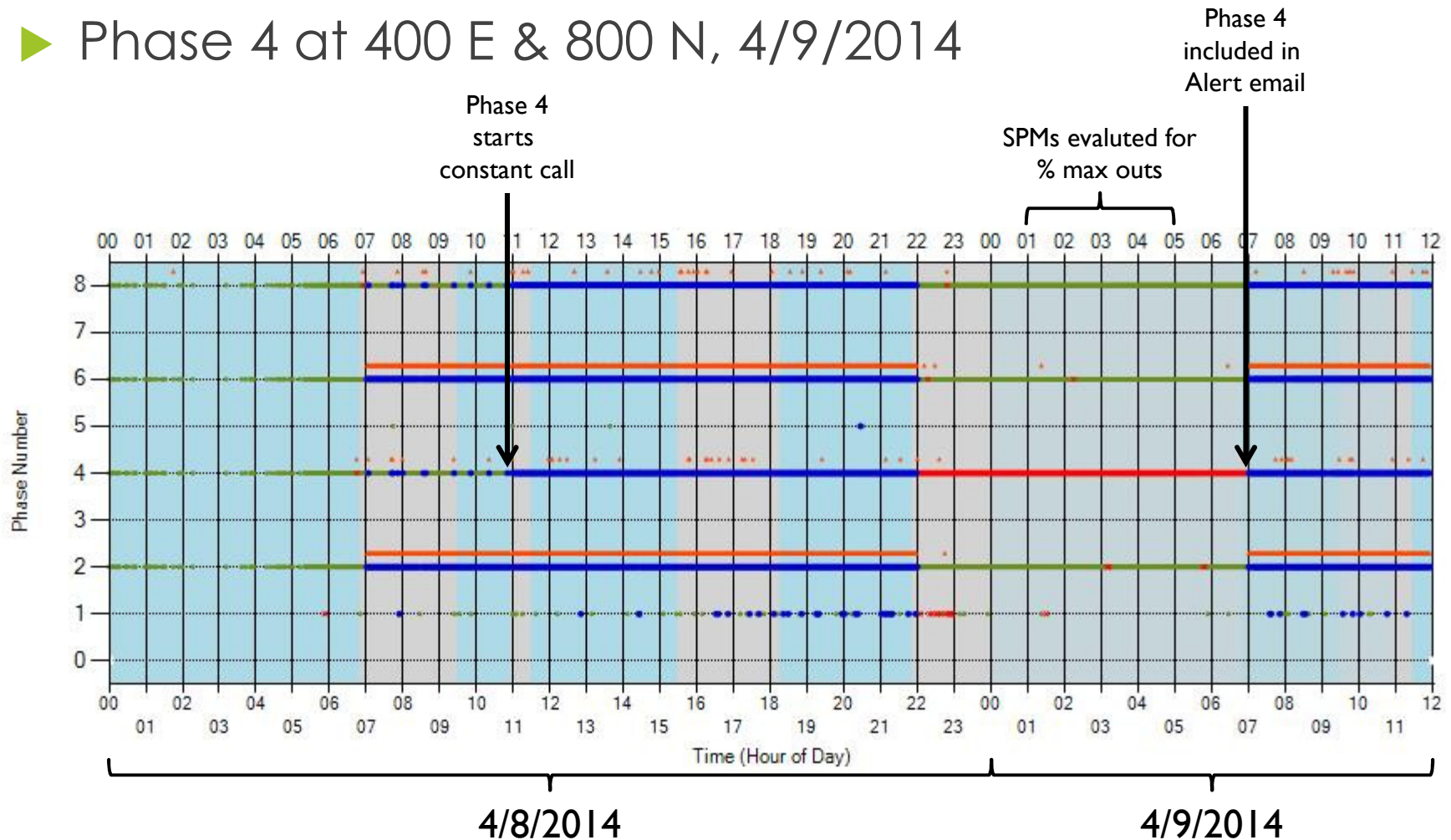
- ▶ Daily email at 7 a.m.
- ▶ Uses Purdue Phase Termination chart data
- ▶ Flags phases with >90% max-outs on each phase between 1 a.m. and 5 a.m.
- ▶ Compare to previous day's list. Only phases with new flags are sent in the email.

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**



# Alert Example: 100% Max Out

## ► Phase 4 at 400 E & 800 N, 4/9/2014



- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**



# Operations Example: Oversize Peds

## ► Check frequency of ped calls

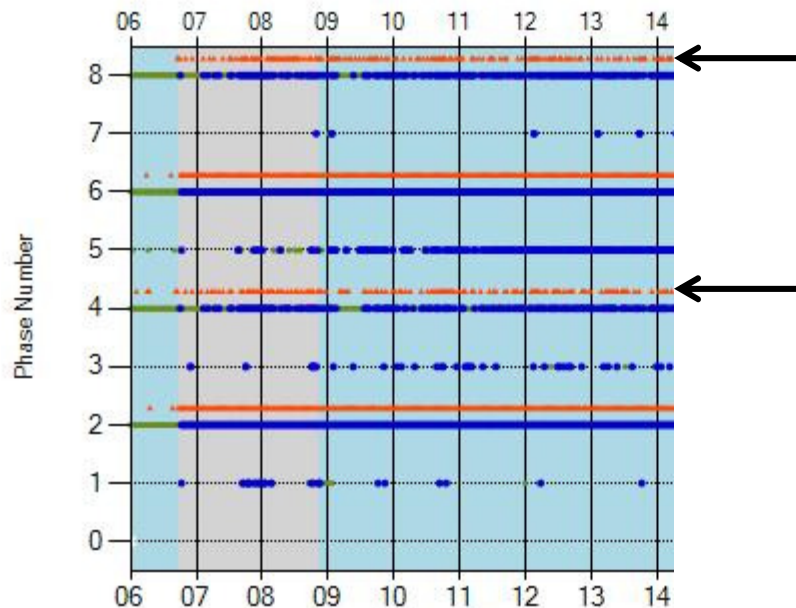
← Ped buttons for Phase 4  
is rarely pushed

Recommendation:  
Oversize peds, if needed

Peds for Phases 4 & 8 are called **frequently**

Recommendation:

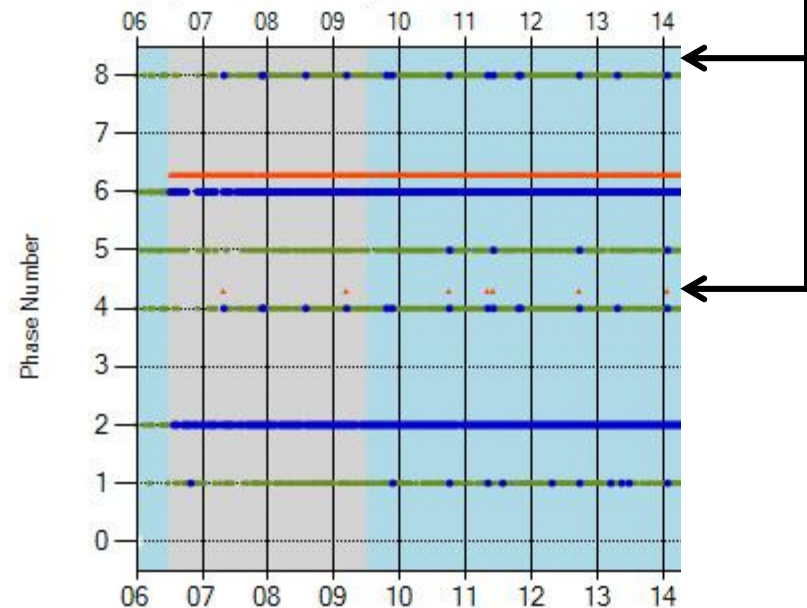
Do not oversize peds



Peds for Phases 4 & 8 are **rarely** called

Recommendation:

Oversize peds, if needed

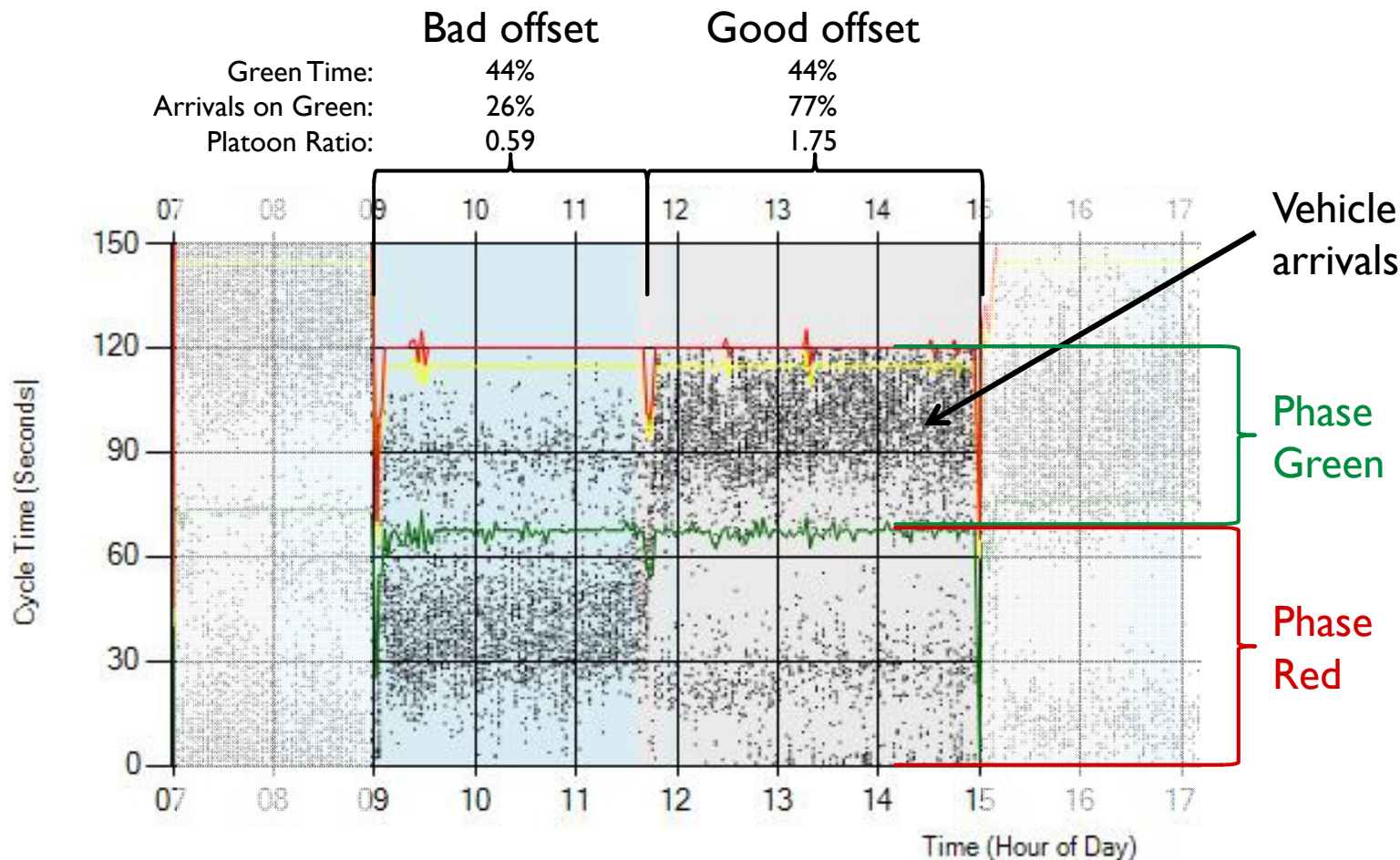


- Gapout
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Optimization Example: Progression Quality

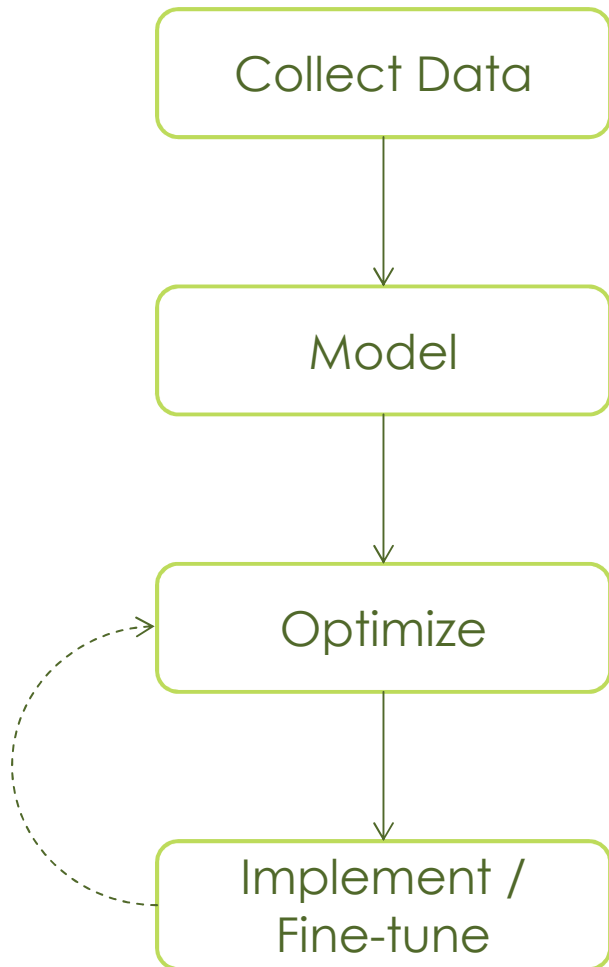
- Fine-tuning new coordination plans



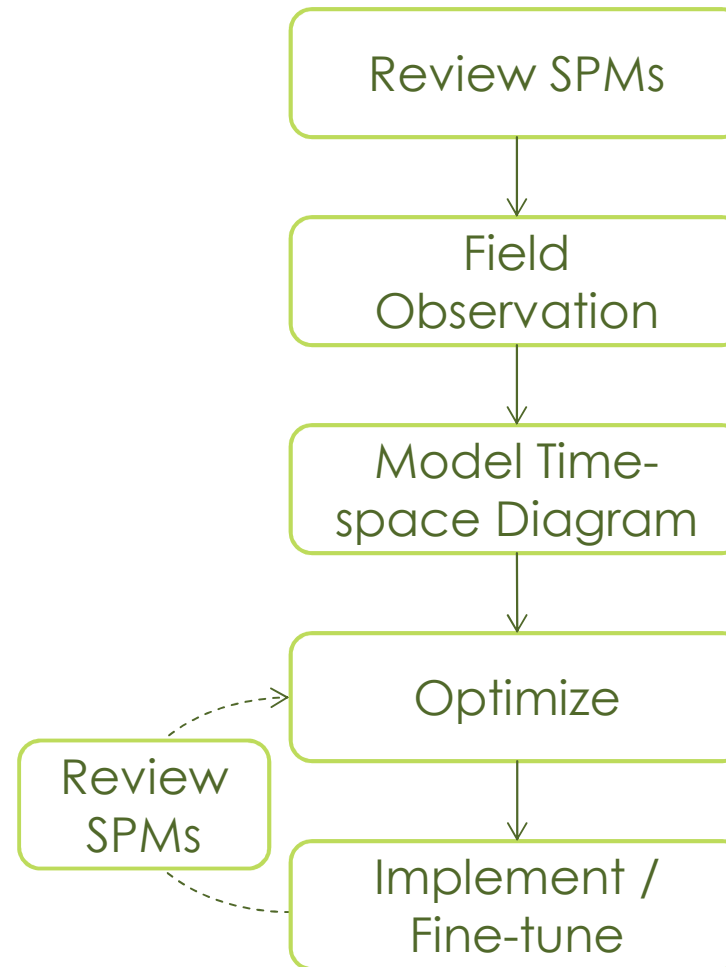
**Metric: Purdue Coordination Diagram**  
**Detection Requirements: Advance**

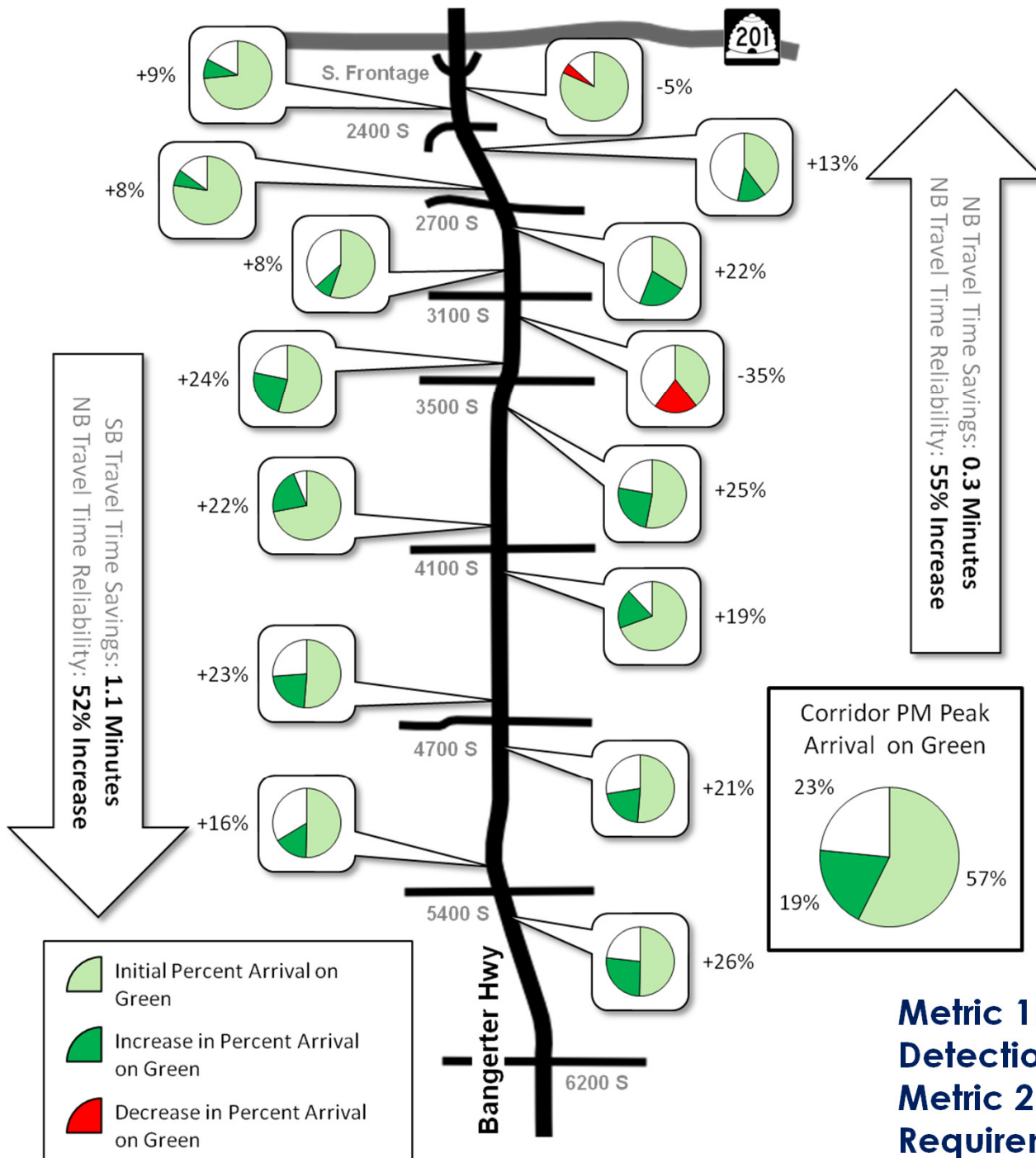
# Optimization with SPMs

## Traditional Process



## Modified Process with SPMs





## Before and After Coordination Results

Corridor: Bangerter Hwy, SLC

To/From: SR-201 - 6200 South

Date: March 2013

Time Period: PM Peak

### Results:

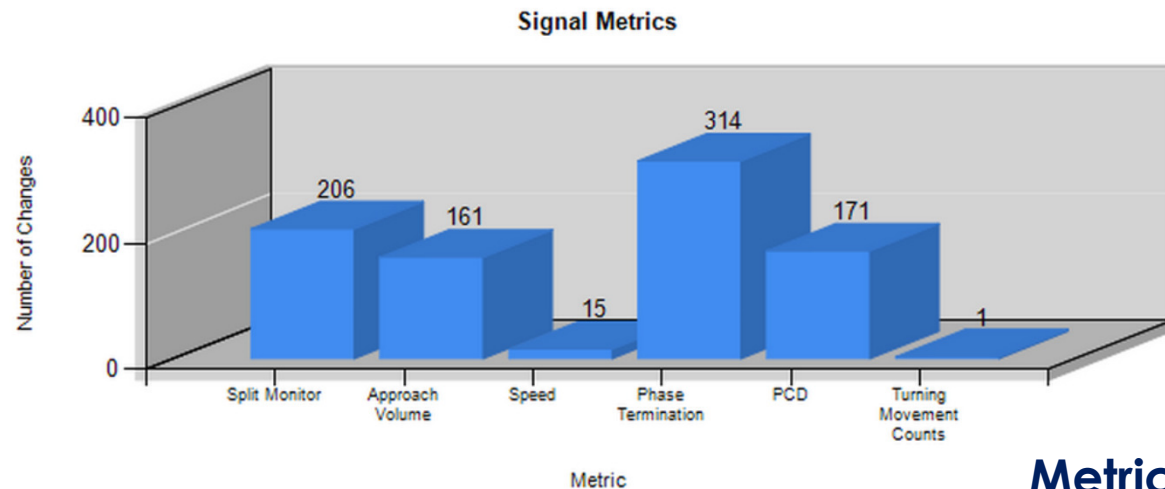
- Arrivals on Green: 19% Increase
- NB TT Savings: 0.3 Minutes
- NB Reliability: 55% Increase
- SB TT Savings: 1.1 Minute
- SB Reliability: 52% Increase

**Metric 1: Purdue Coordination Diagram**  
**Detection Requirements: Advance**  
**Metric 2: Purdue Travel Time Diagram**  
**Requirements: Probe data set**

# Intersection Adjustments using SPMs

January 1, 2013 to December 31, 2013

- ▶ Adjustments made at 325+ intersections
  - ▶ 185 work orders for detector problems
  - ▶ 40 offset adjustments
  - ▶ 5 time-of-day corrections



**Metric: Usage Reports**

# System Requirements

1. Traffic signal controllers with 1/10<sup>th</sup> s. data logger
  - Econolite (ASC/3; Cobalt)      -- Intelight ATC      -- Naztec (Beta)
  - PEEK ATC      -- Siemens Linux / ATC
2. Communications or storage memory on controllers
3. FTP connection to signal
4. Server to store controller logs
5. Enumerations analyzed and graphed (INDOT & UDOT software developed in-house)

**Can be done independent of a Central System!**



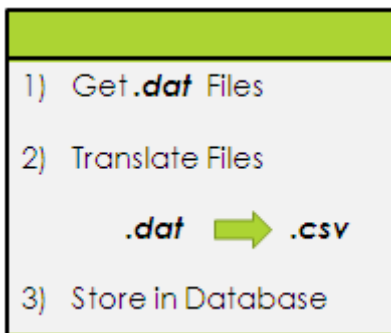
# System Requirements



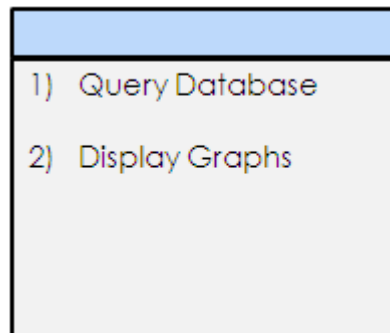
**High-resolution Controller**



**Communications**



**Server**



**Website**



**Detection**

Photo courtesy of the Indiana Department of Transportation

# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: INDOT

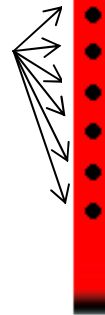


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PRESENTED BY AMANDA STEVENS, INDOT AND ALEX HAINEN, PURDUE

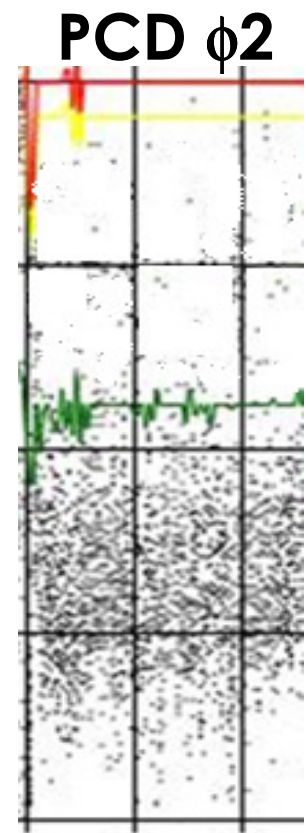


Detection  
ON



Single Instance  $\phi 2$

Time  
in Cycle (s)



Time of Day (hr)

PCD: Red Arrival



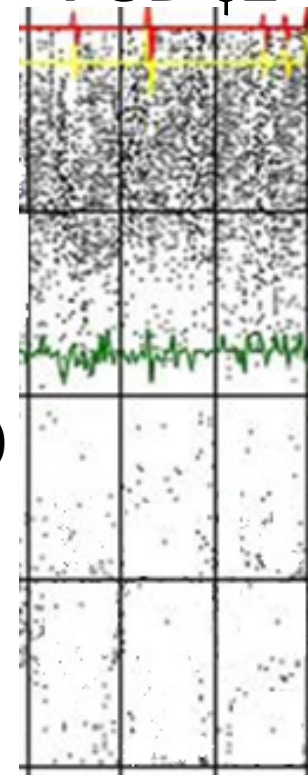
Detection  
ON



Single Instance  $\phi 2$

Time  
in Cycle (s)

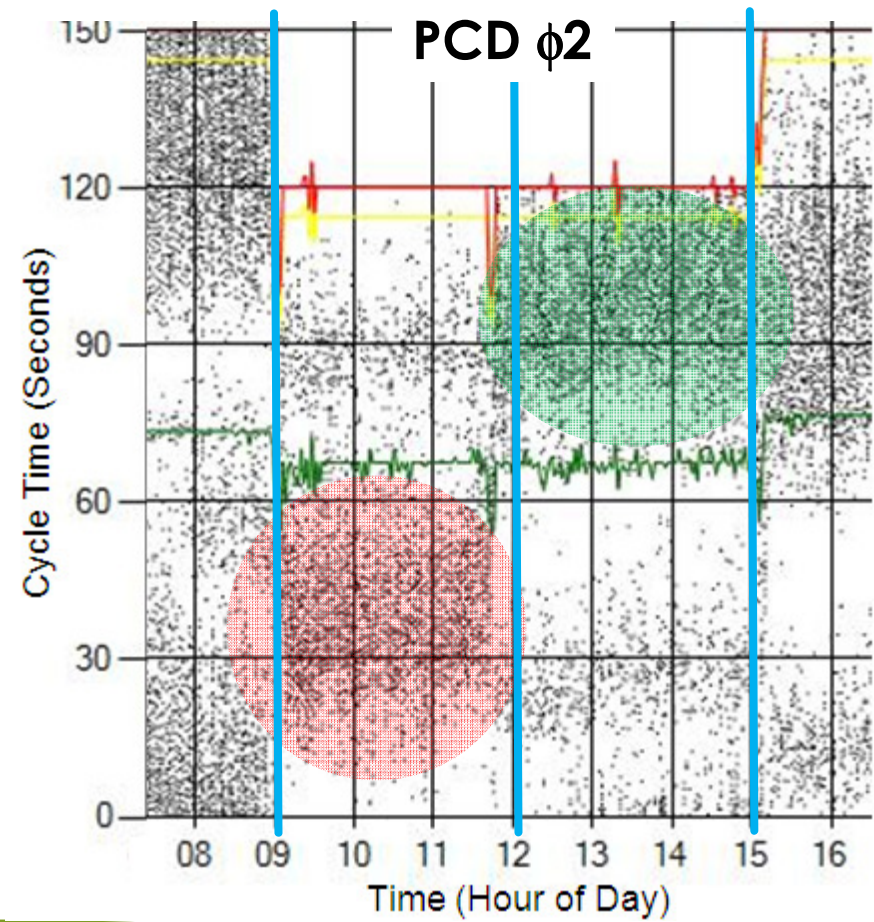
PCD  $\phi 2$



Time of Day (hr)

PCD: Green Arrival

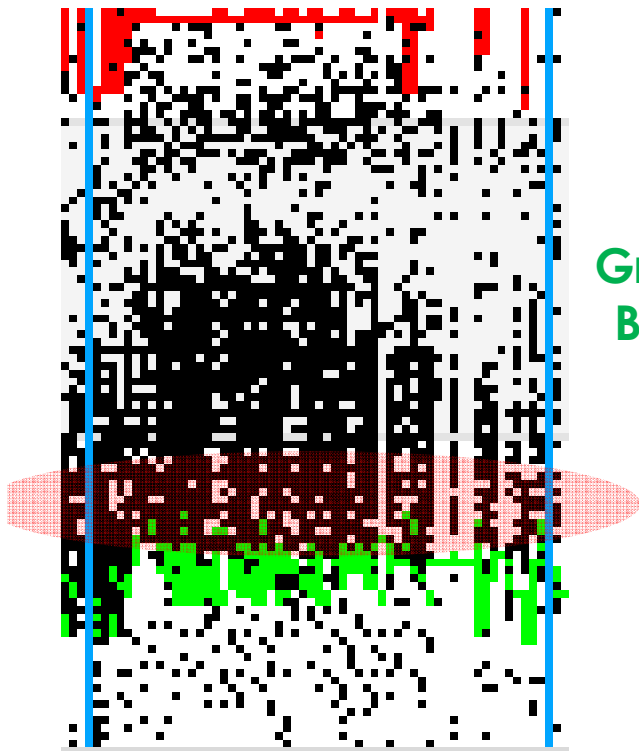




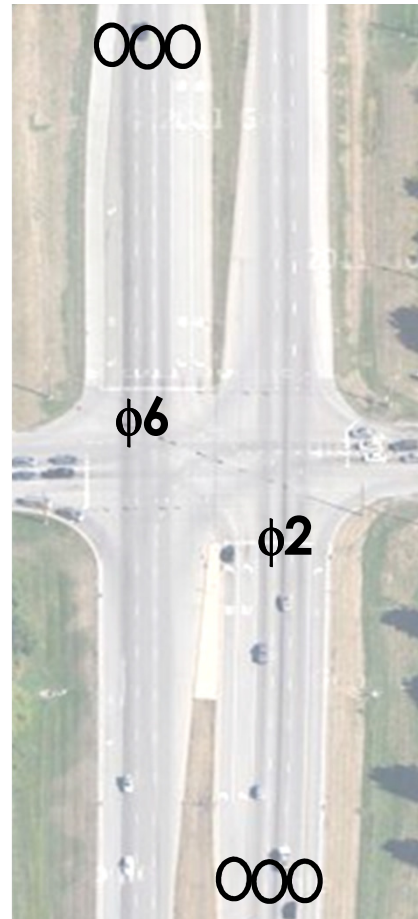
**PCD: Platoon Arrival by  
TOD**



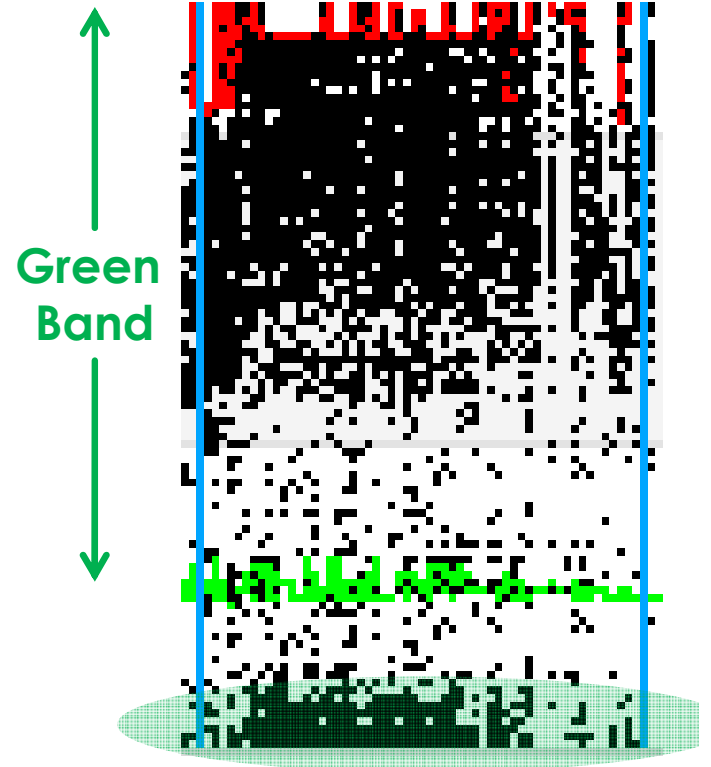
PCD  $\phi 6$



Green  
Band



PCD  $\phi 2$



Green  
Band

PCD: Adjust Offsets

# INDOT System



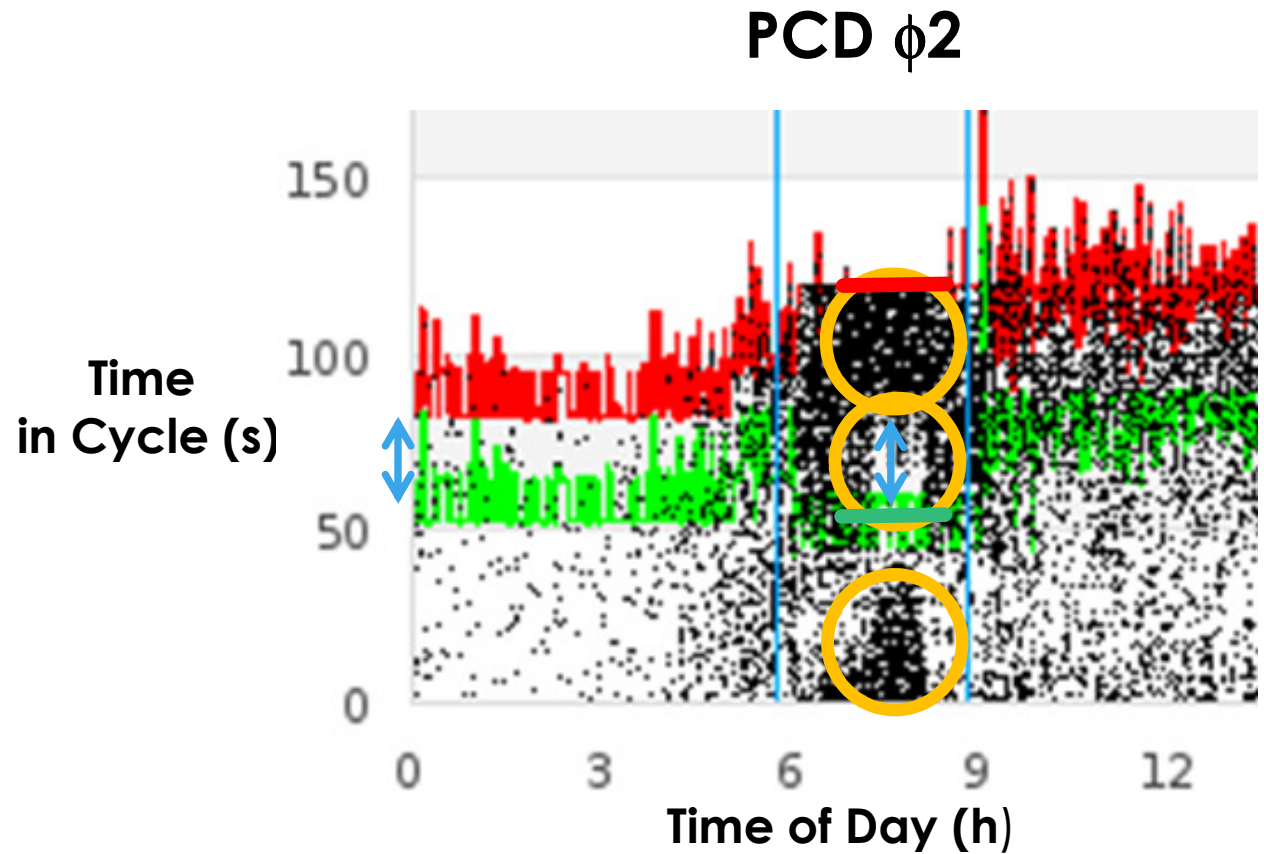
- **# SIGNALS TOTAL**
- **# SIGNALS ONLINE,  
AUTOMATICALLY  
STORING DATA &  
GENERATING  
PERFORMANCE  
MEASURE GRAPHS**
- **PEEK ATC, ECONOLITE  
ASC/3, SIEMENS M50  
SERIES...**

# “Human-in-the-Loop-Adaptive”

- WEEKENDS & OFF-PEAKS
- ROUTINE RETIMINGS
- CONSTRUCTION SEASON:
  - You cannot be everywhere at once!
  - Could take Months for traffic to settle
  - Project in Flux:
    - Detection
    - Phases
    - Approaches / Lanes
    - Adjacent construction detours

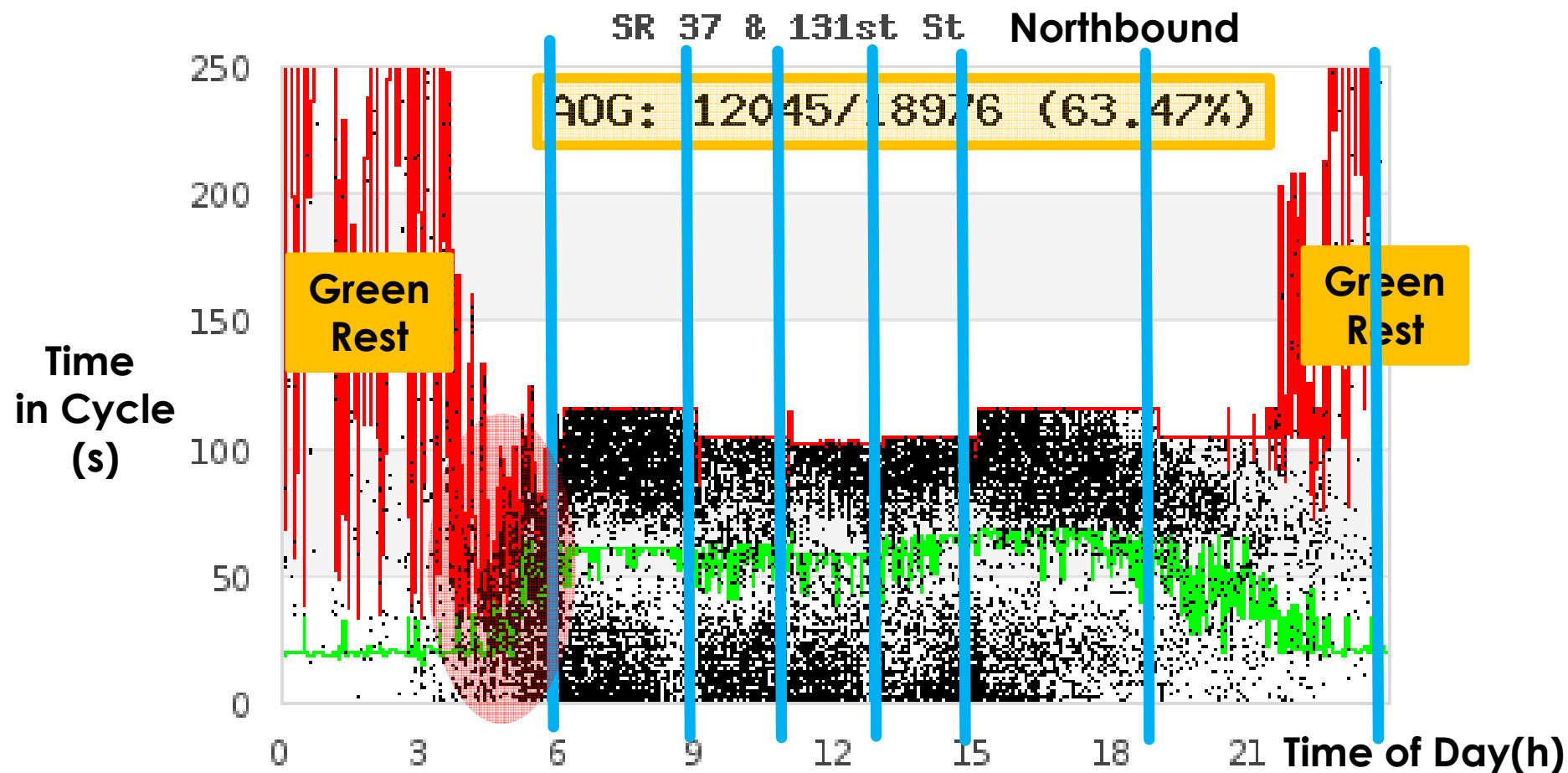
# Moving Forward:

- **CLOSELY-SPACED SIGNALS ALSO NEED ADVANCED DETECTION ON LEFT TURNS**
- **SEPARATE DETECTION CHANNELS FOR EACH LANE**



PCD: Cycle Failure





**PCD: Pattern Start & End Times**



# Hi-resolution Event-based Data for Diamond Interchange Operations

ALEX HAINEN

JIM STURDEVANT

AMANDA STEVENS

DARCY BULLOCK

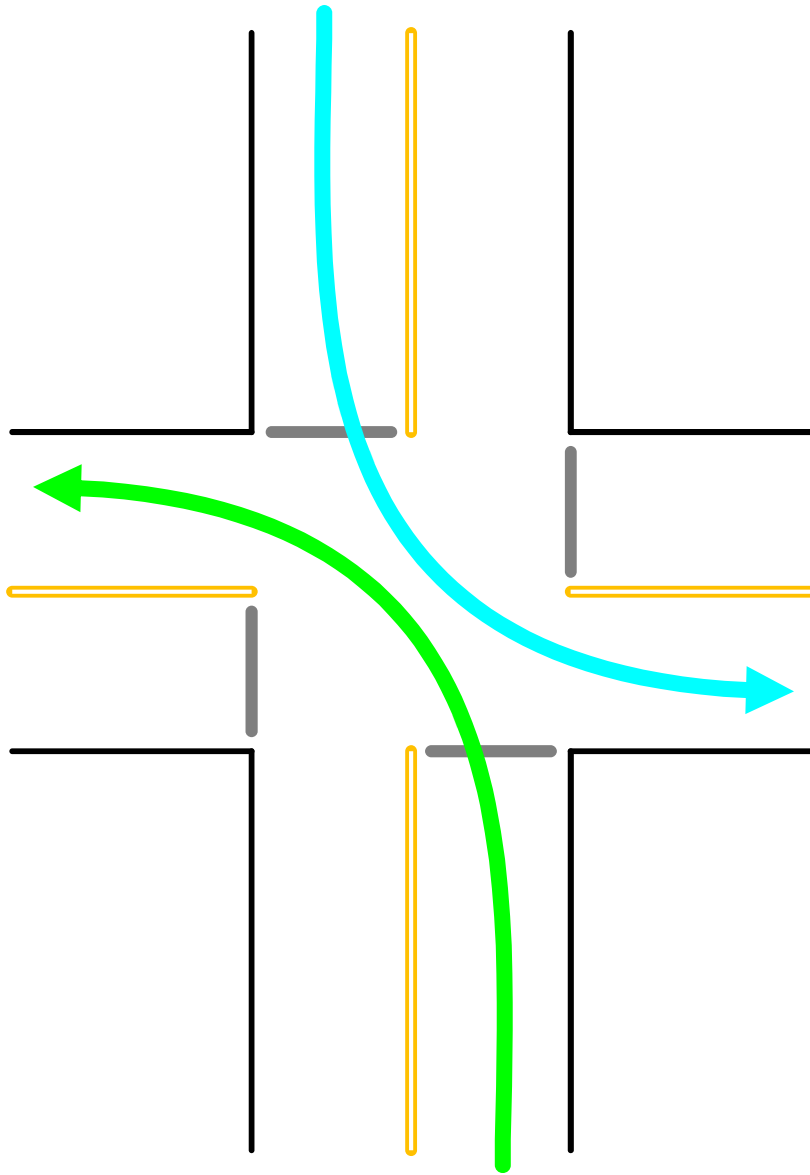
CHRIS DAY

HOWELL LI

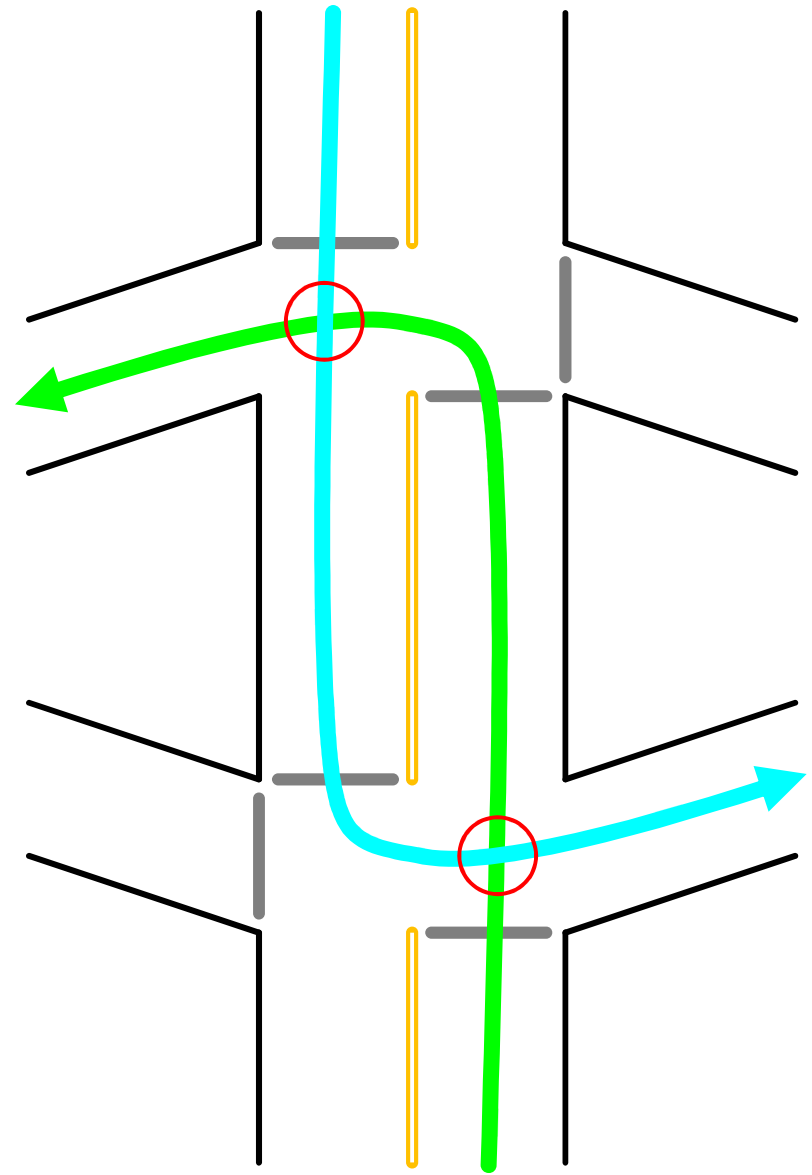
RICK FREIJE

# Diamond Interchanges

*What are they and why do they matter?*



Normal Intersection

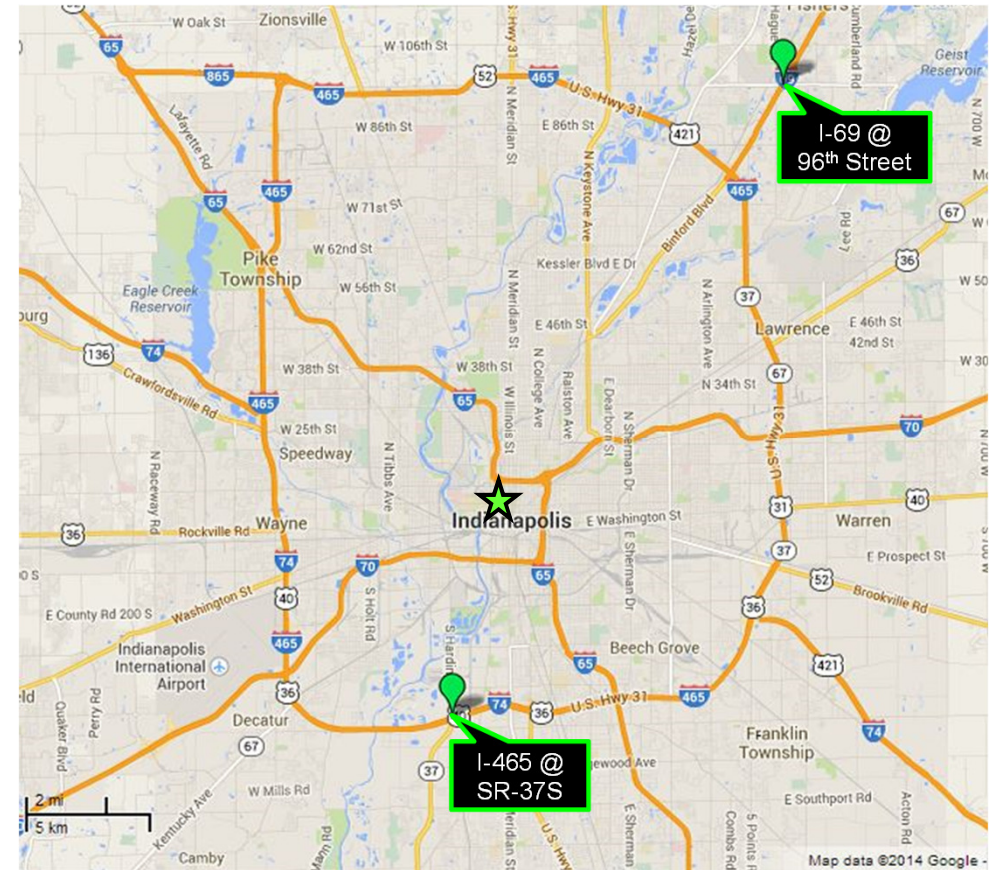
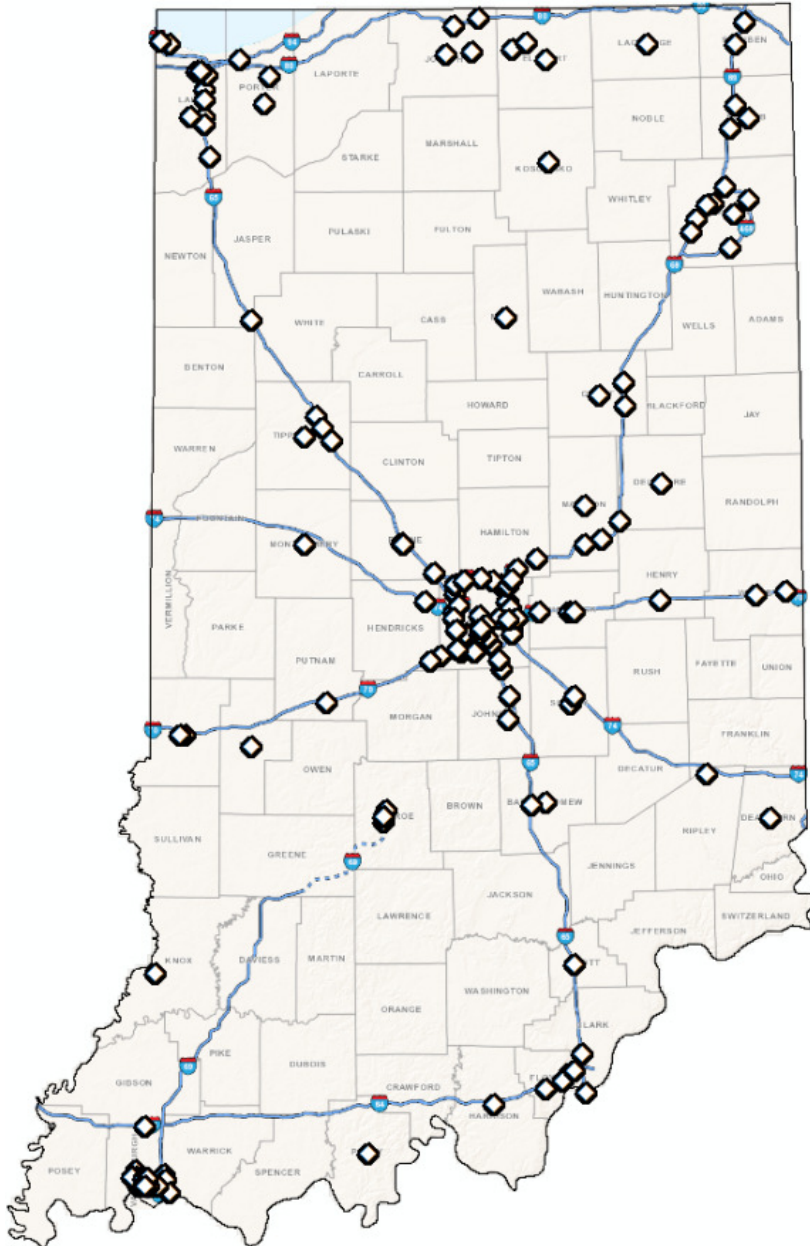


Diamond Interchange

# Diamond Interchanges

Indiana = 161 Interchanges

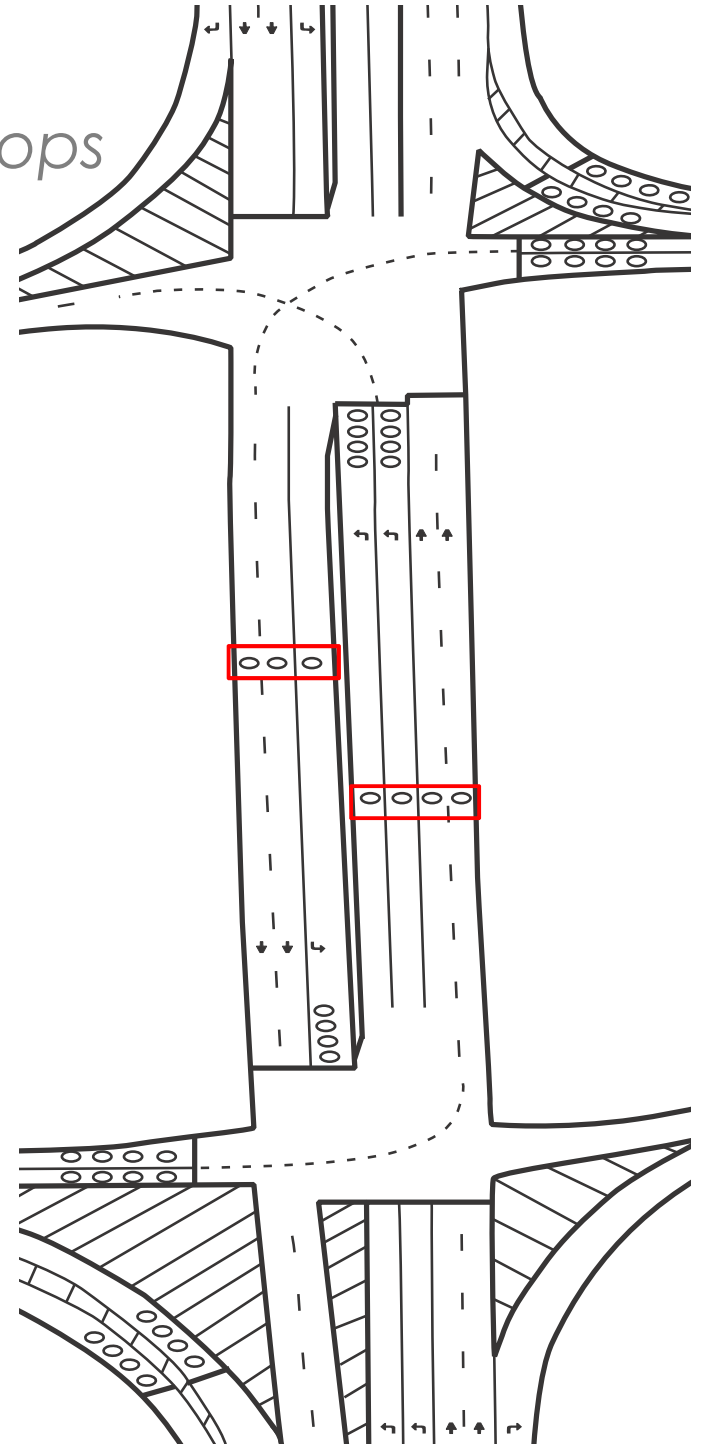
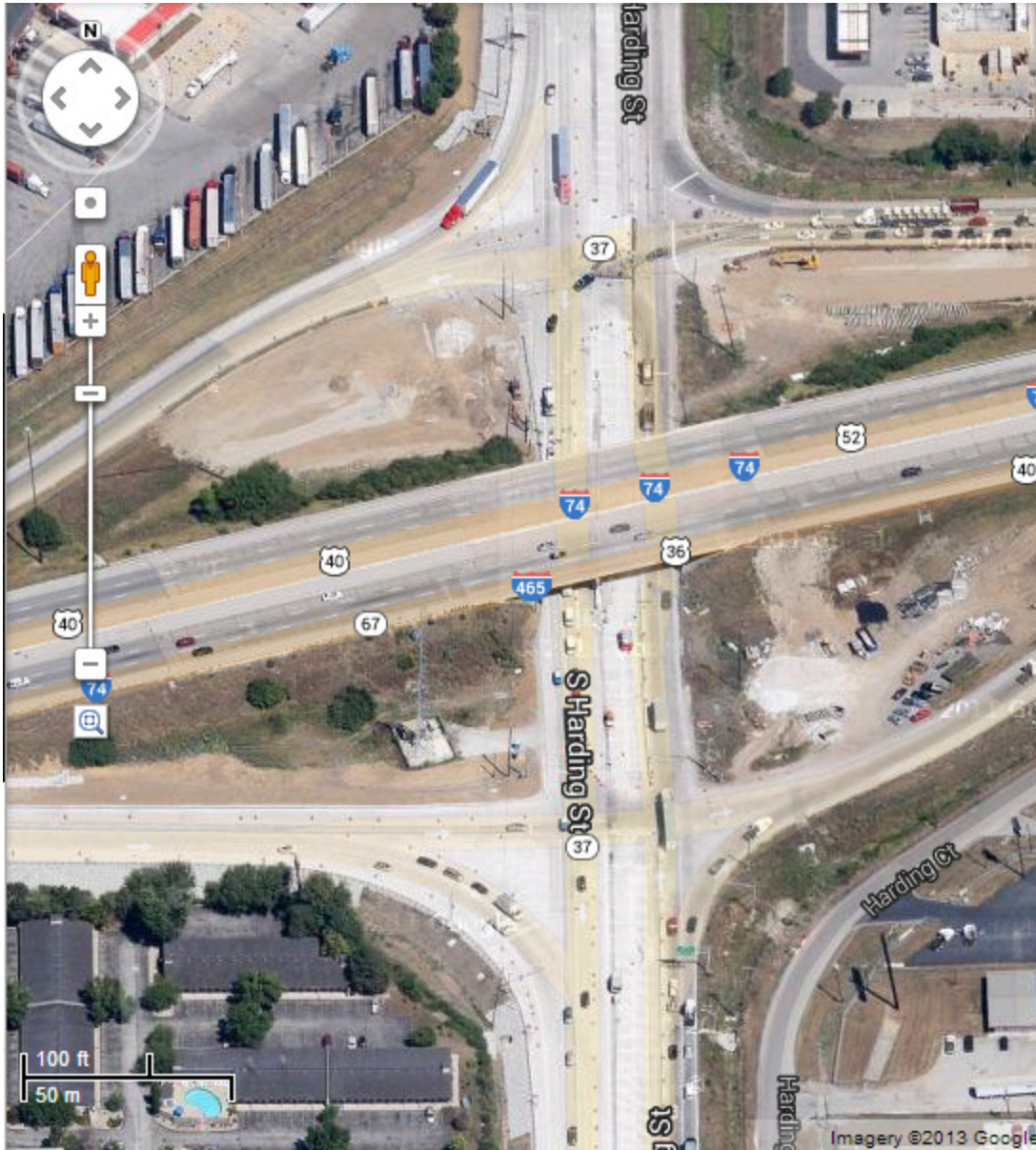
Nationally  $\geq 10,000$





# I-465 @ SR-37

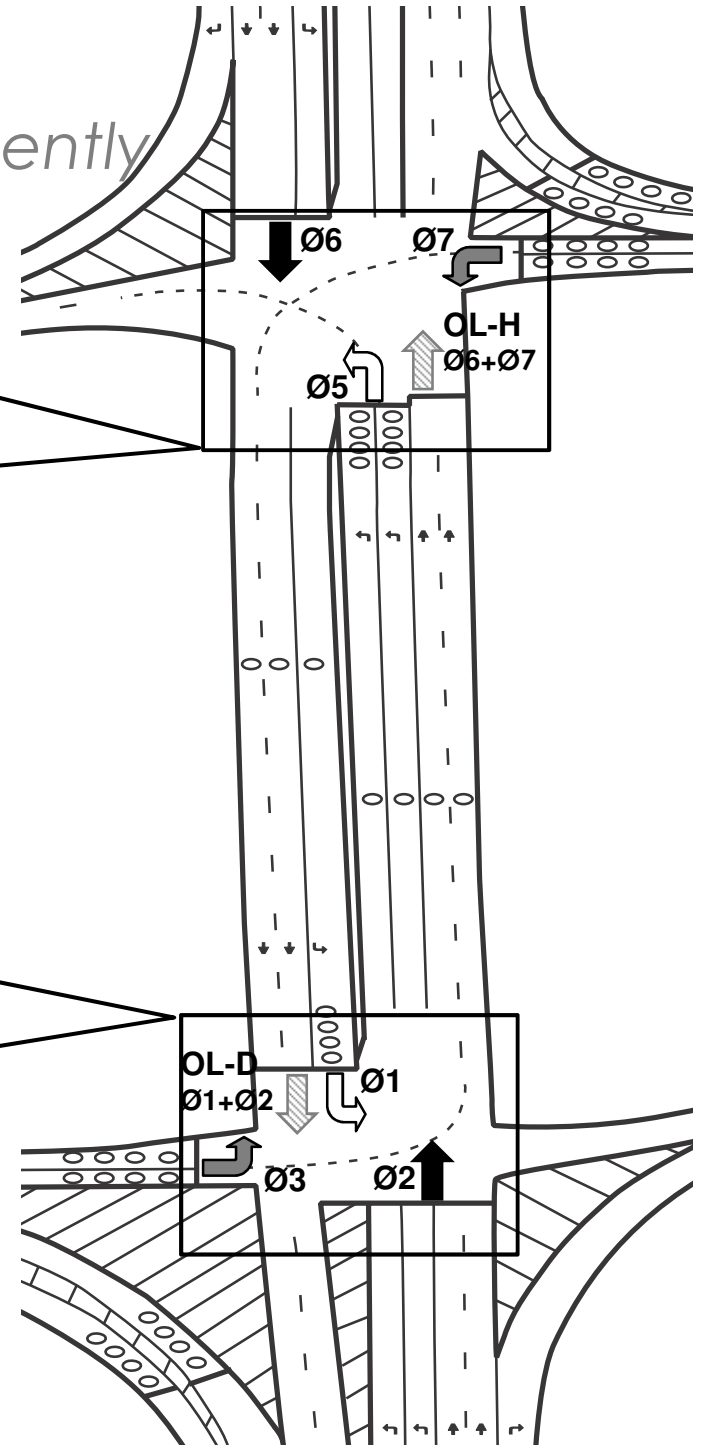
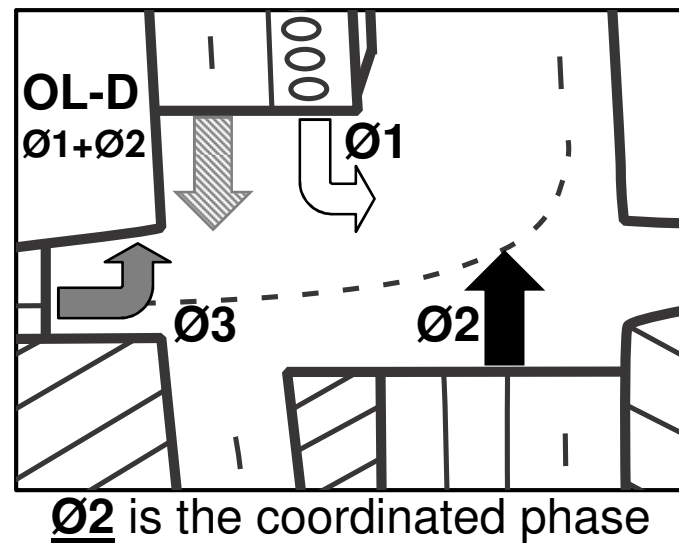
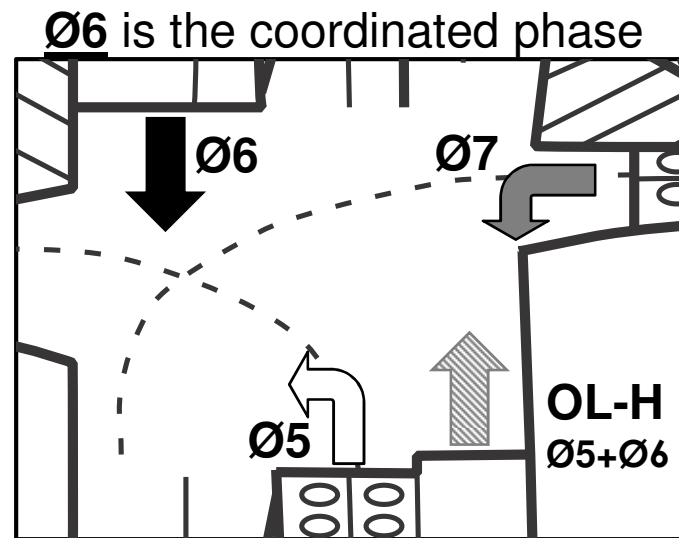
*Diamond Interchange w/Advanced Loops*





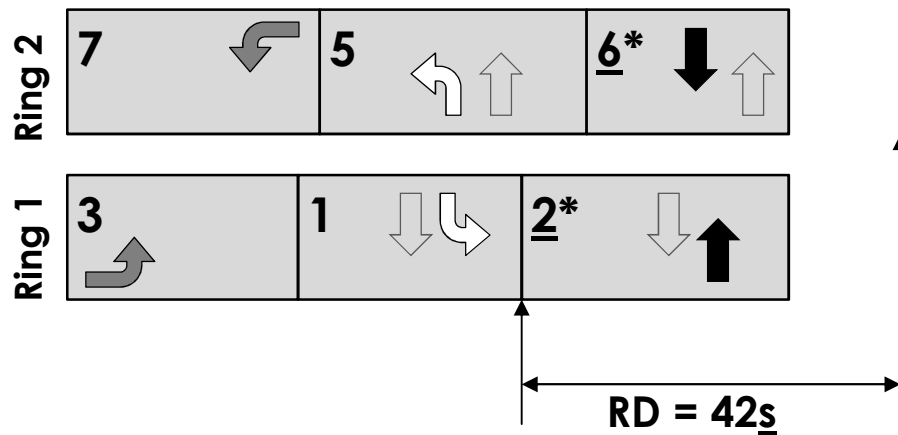
# Phasing

## Two "T"-Intersections Treated Independently



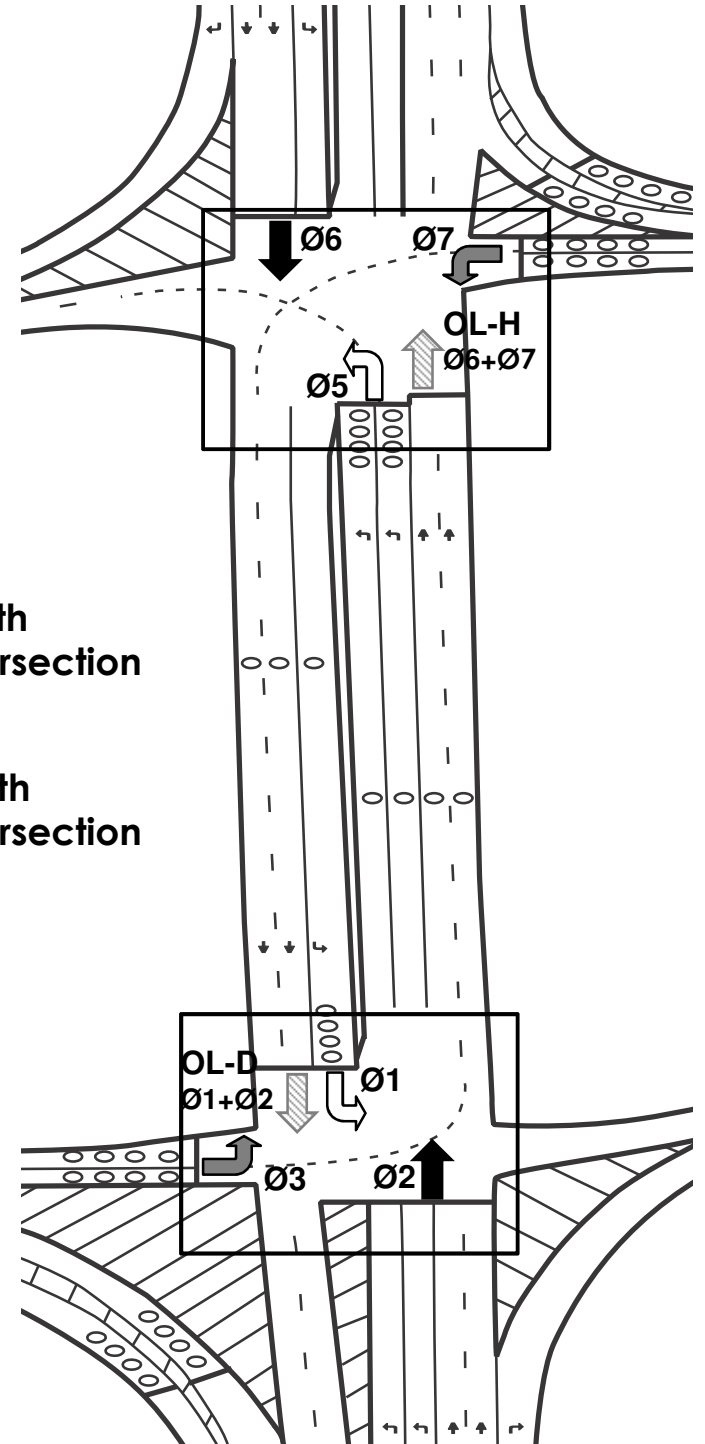
# Ring Displacement

*Offset Between Coordinated Phases*



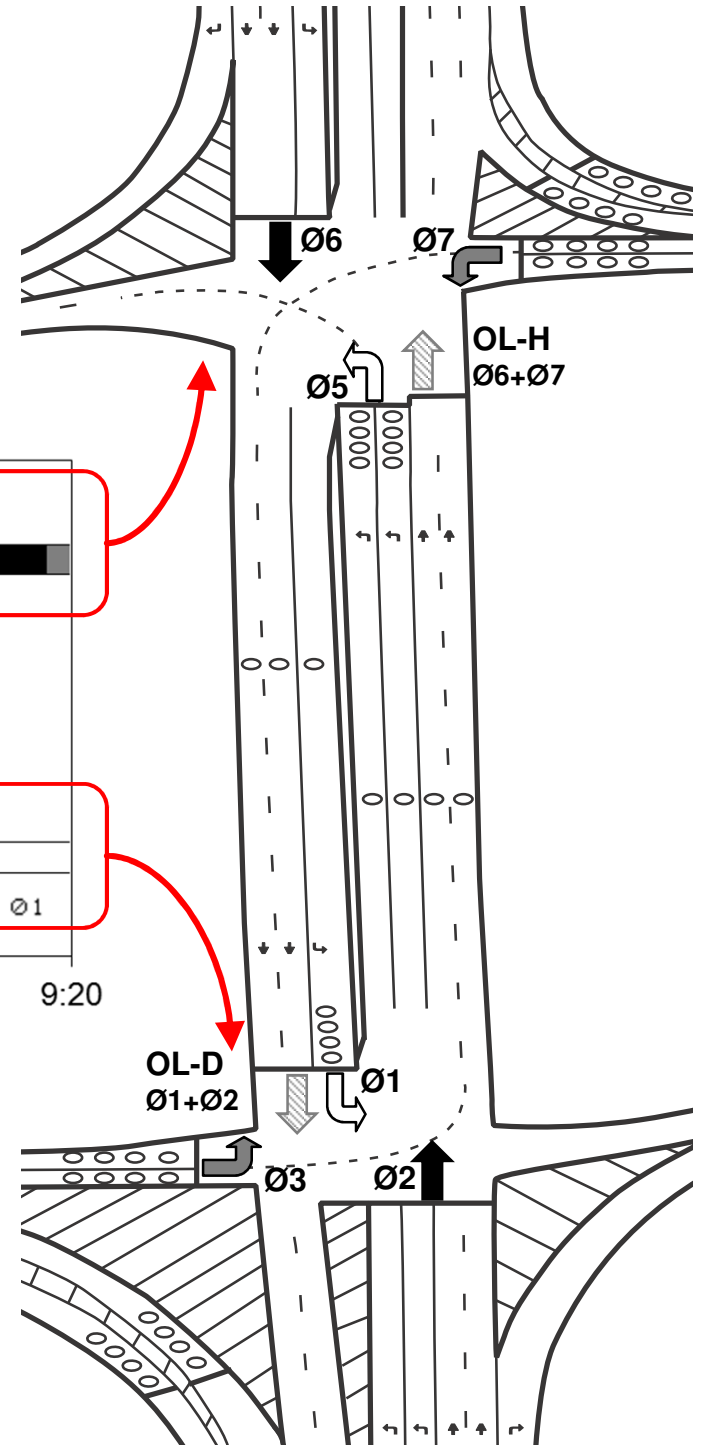
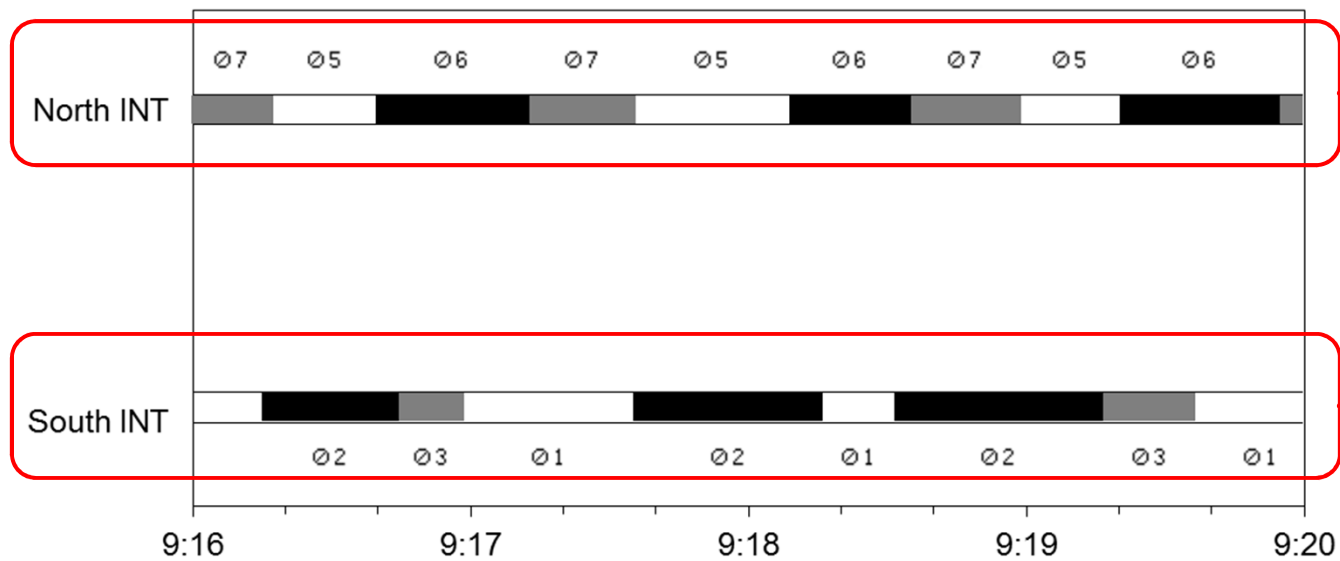
North  
Intersection

South  
Intersection



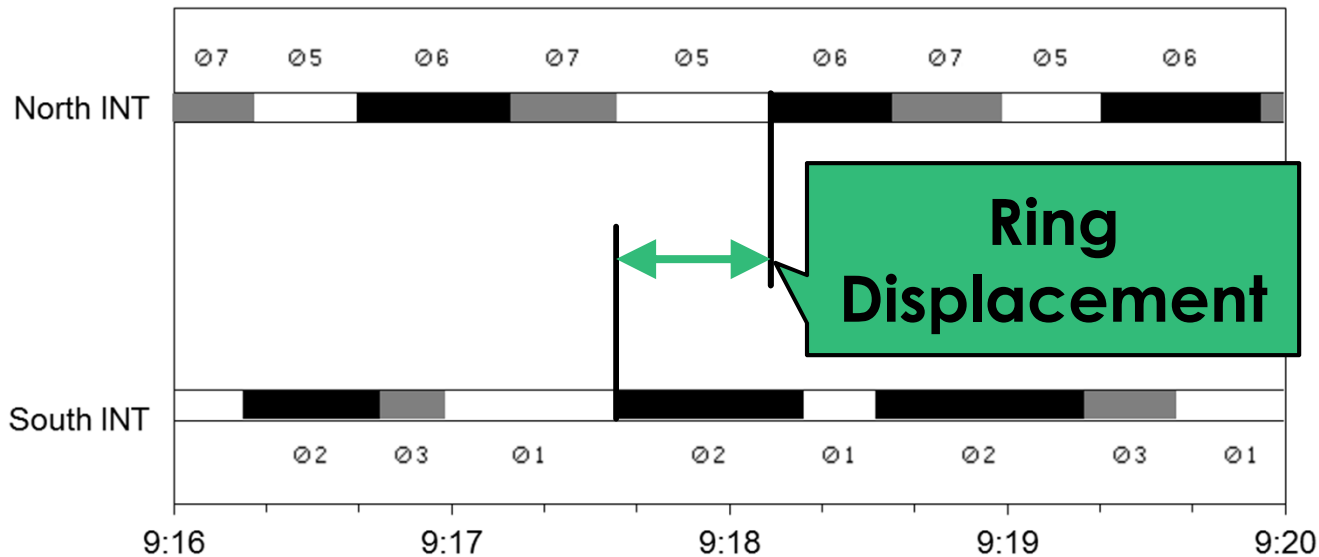
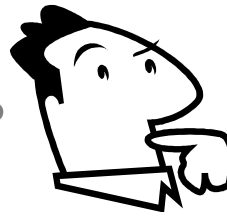
# Ring Structure

*From the HiRes Data, Plot the Rings*



# Ring Displacement

*How is this parameter set?*

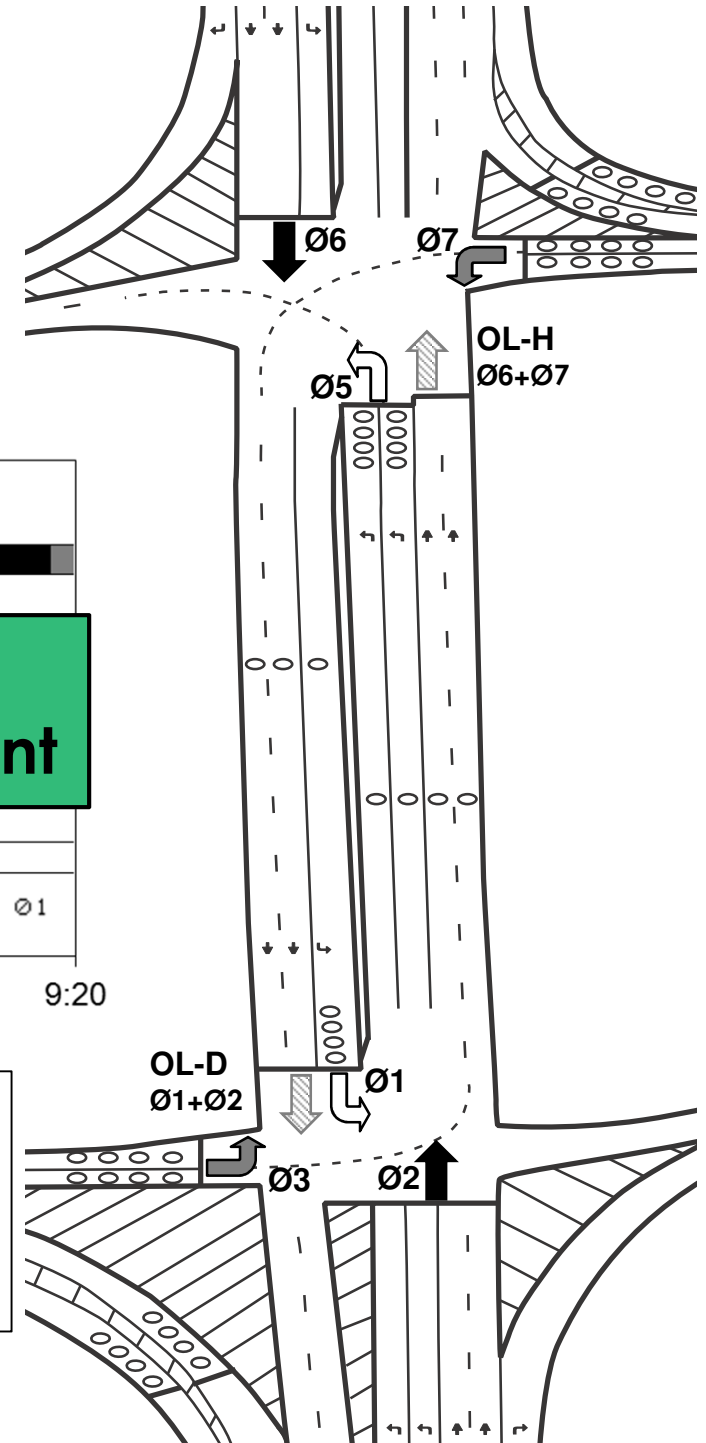


```

COORDINATOR PATTERN [ 1 ]
TS2 (PAT-OFF)... 0-1
CYCLE..... 0s STD (COS).....111
OFFSET VAL.... 0s DWELL/ADD TIME. 0
ACTUATED COORD... NO TIMING PLAN... 0
ACT WALK REST... NO SEQUENCE..... 0
PHASE RESRUCE... NO ACTION PLAN... 0
MAX SELECT.... NONE FORCE OFF.... NONE
SPLIT PREFERENCE PHASES
PHASE[s] 1 2 3 4 5 6 7 8
SPT[ 1] 0 0 0 0 0 0 0 0
PREF 1... 0 0 0 0 0 0 0 0
PREF 2... 0 0 0 0 0 0 0 0
SPLT EXT...0s 0s 0s 0s
VEH PERM. 0s 0s 0s DISP
RING DISP - 0s 0s 0s (RING 2-4)
    
```

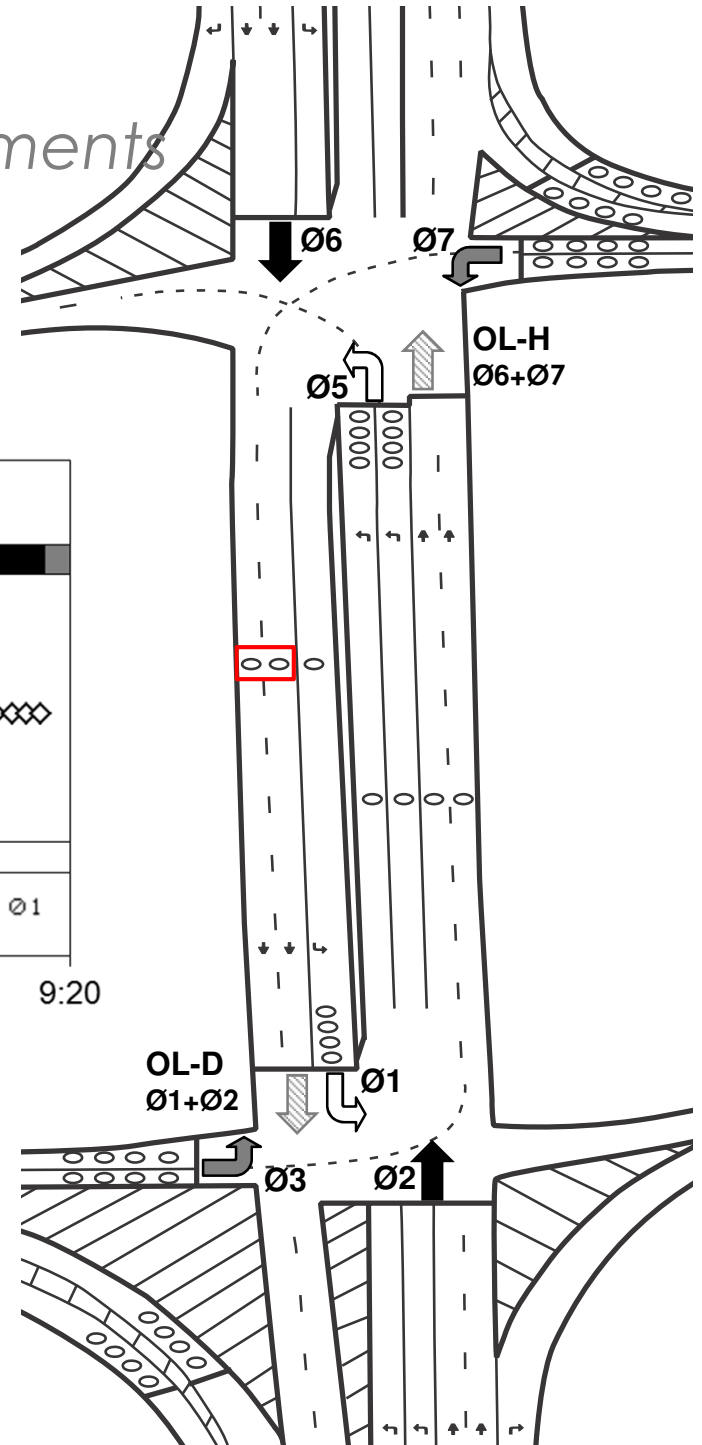
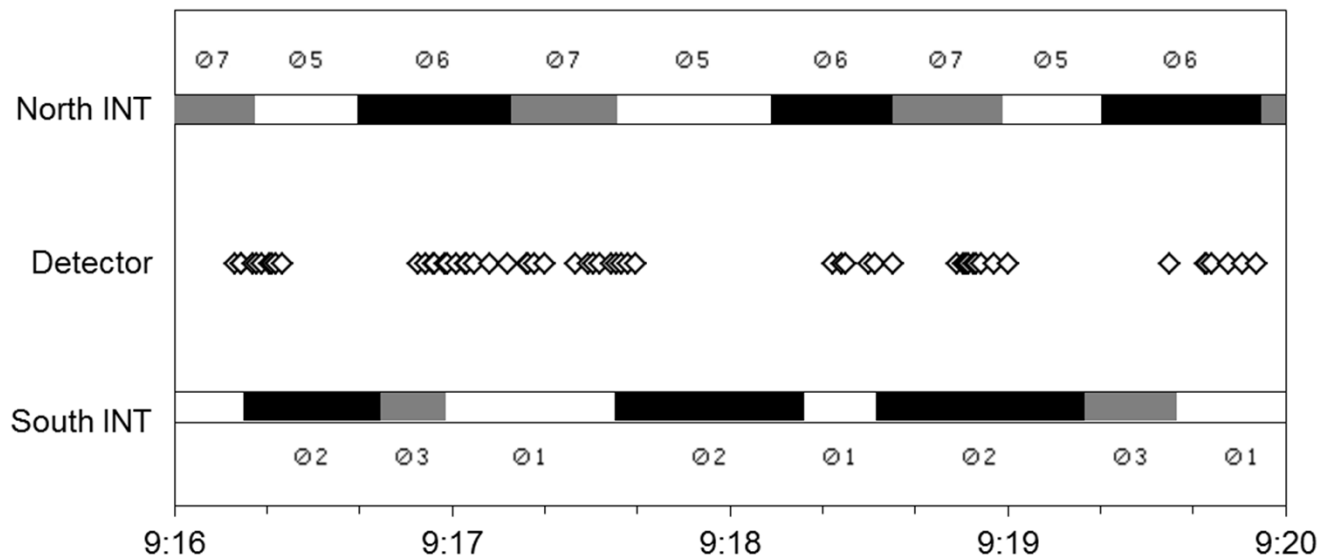
```

DIAL 1 SPLIT 1 PARAMETERS
OFFSET TIME ALT PATN R2 R3 R4
# SEC SEQ MODE LAG LAG LAG
1 0 0 0
2 0 0 0
3 0 0 0
MODE (0-6) : NRM/PRM/YLD/PYL/POM/SOM/FAC
A-UP B-DN C-LT D-RT E-ENTER F-PRIOR MENU
    
```



# SB Thru Detectors

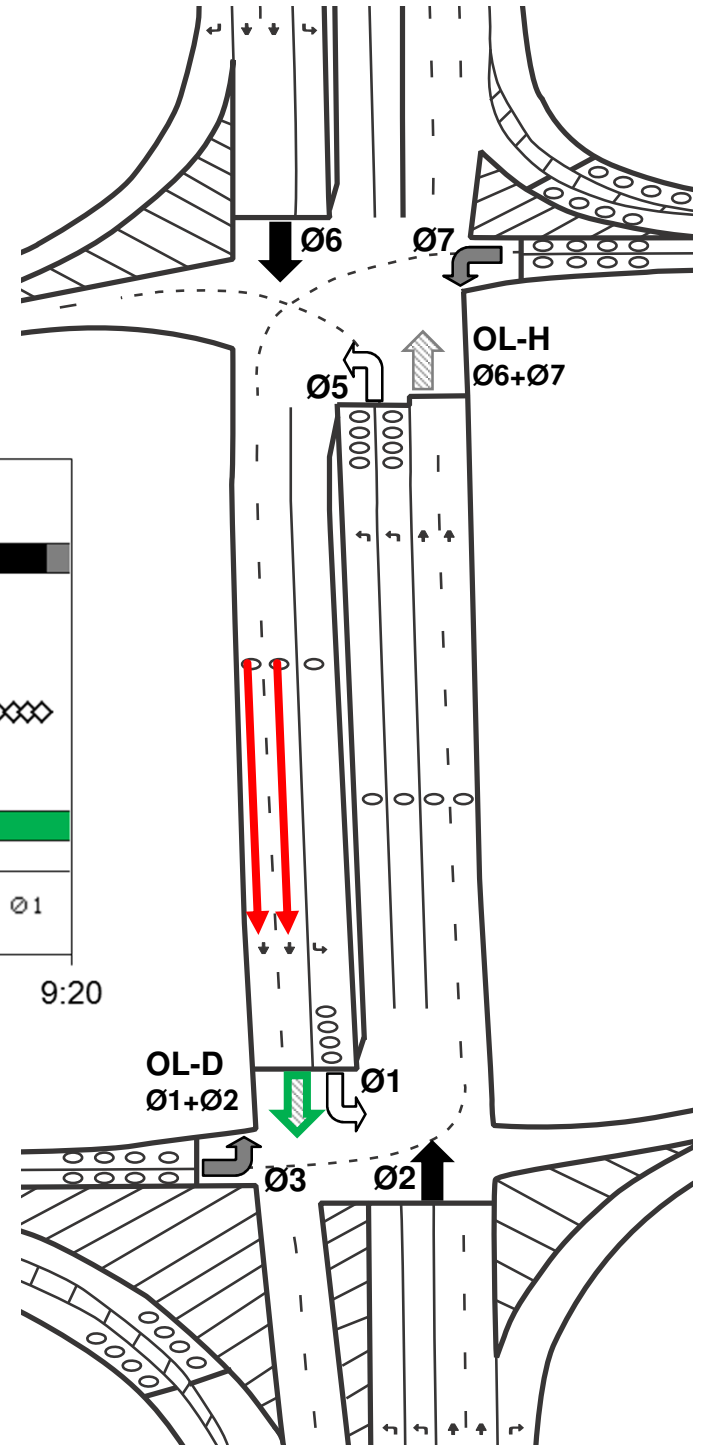
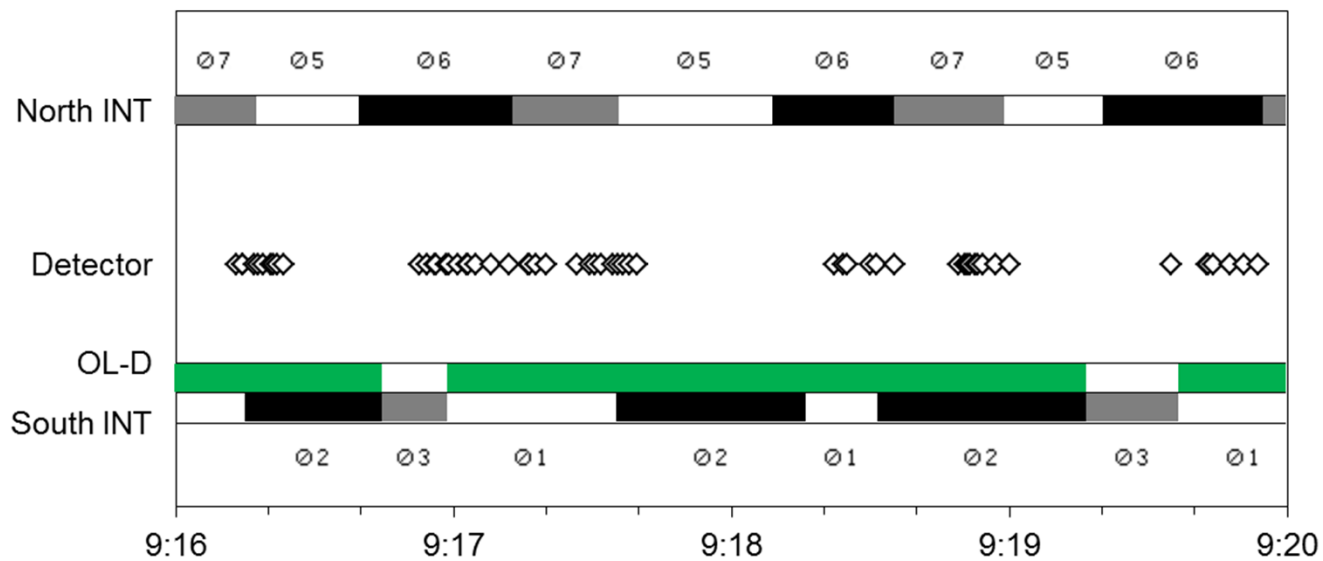
*Consider one of the four internal movements*





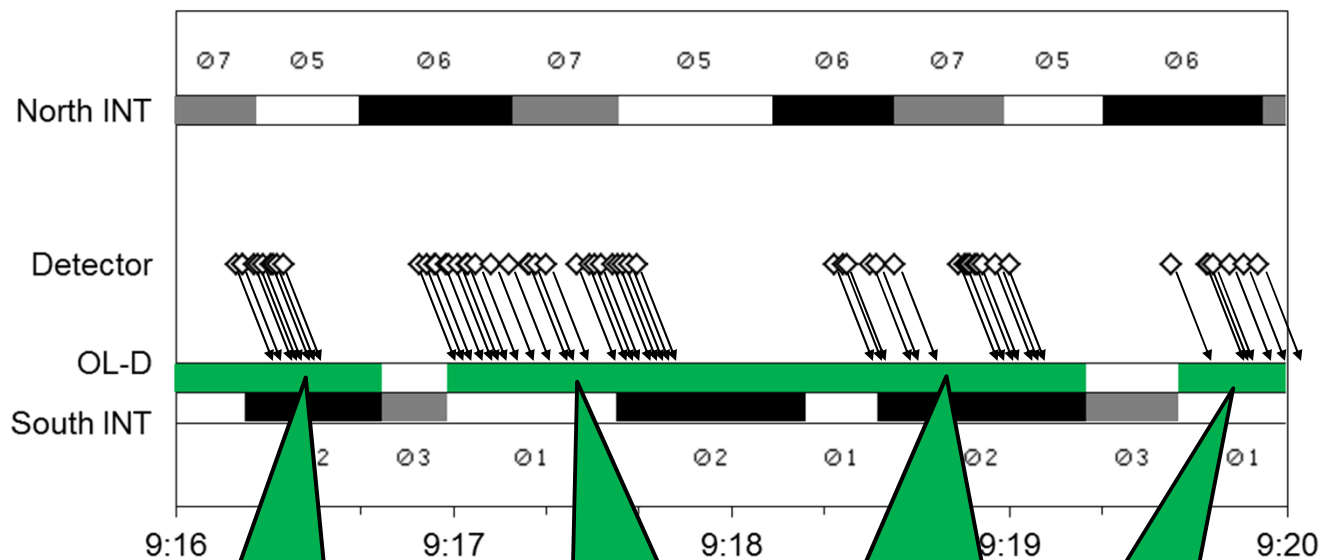
# Arrival on Green?

*Plot the green status of the overlap*

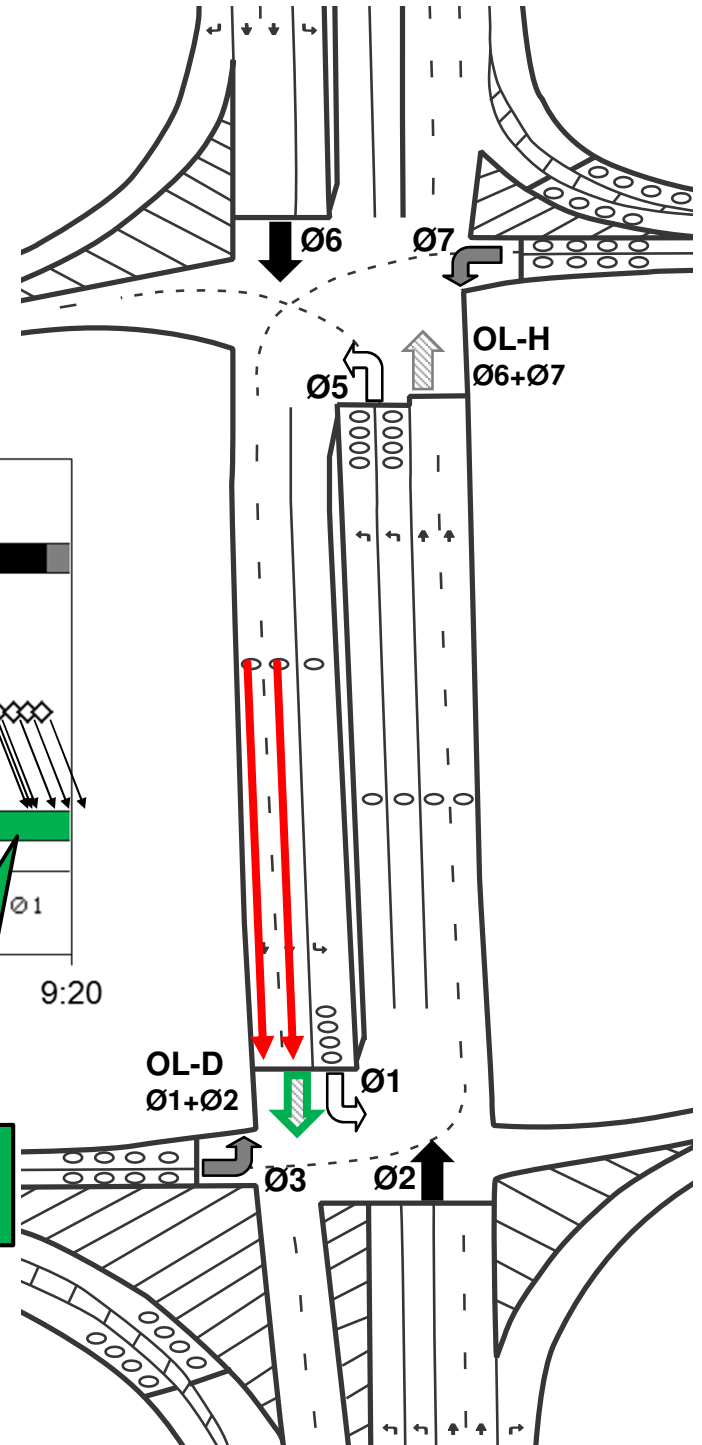


# Project the Detector Data

*295' upstream  $\approx$  5 seconds @ 40 MPH*

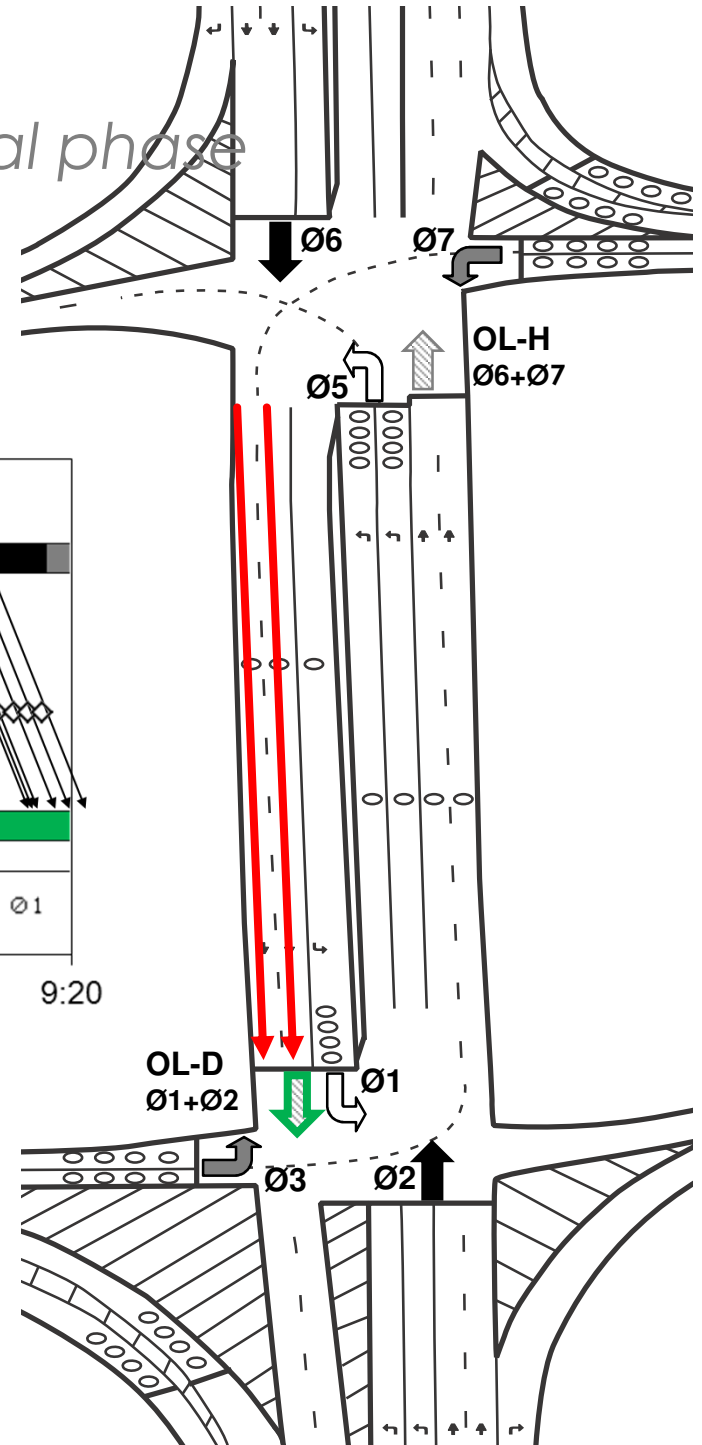
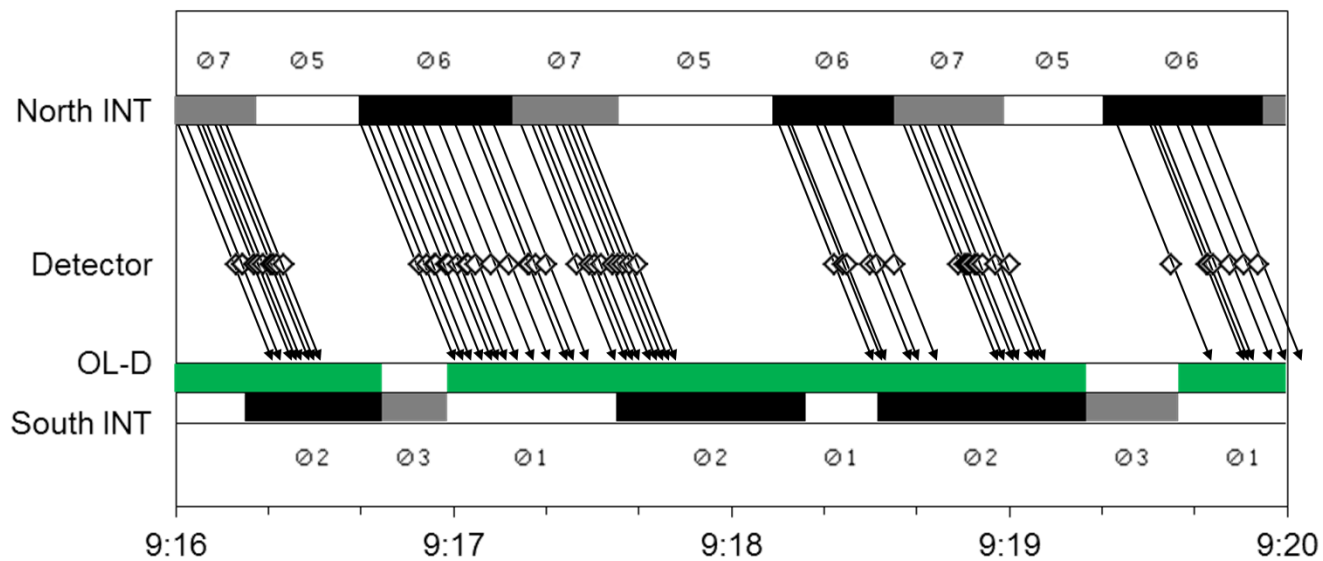


**The engineer who set the ring displacement did a fantastic job at arrivals on green for this movement!**



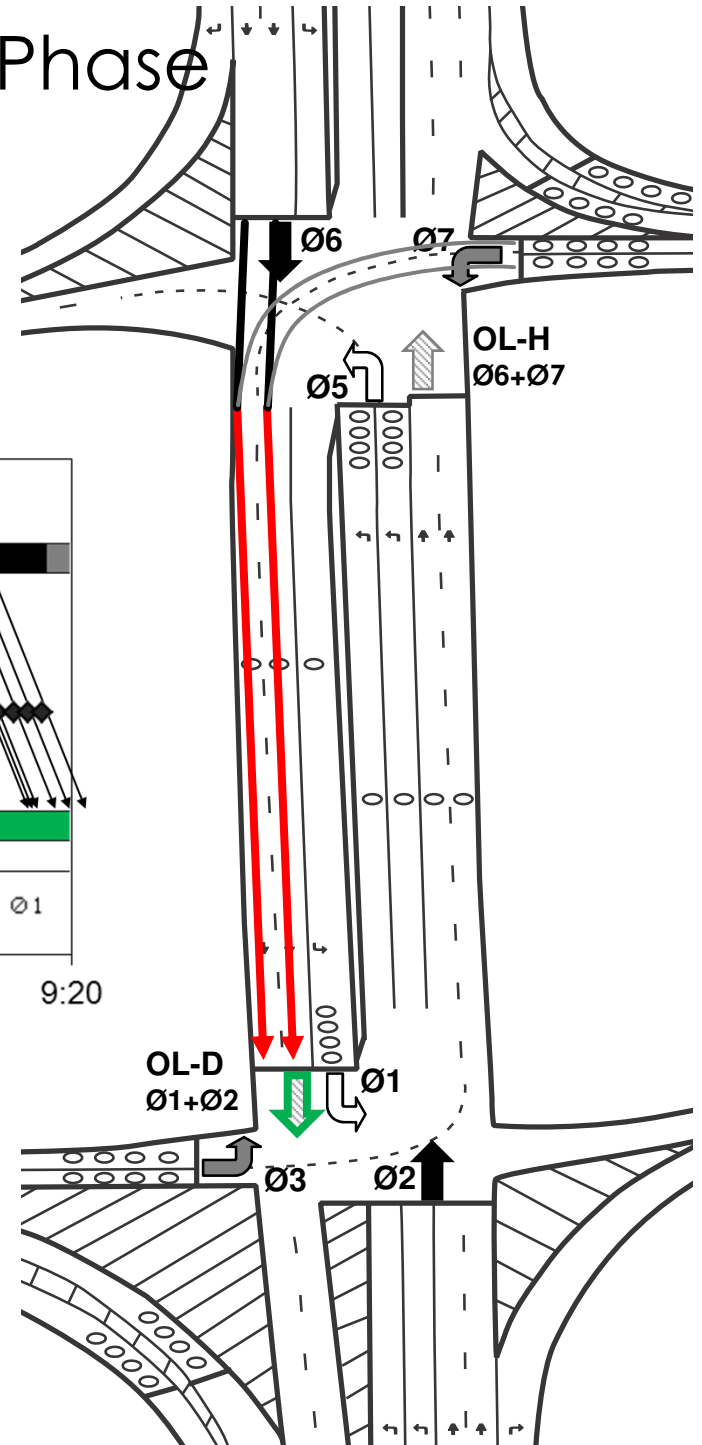
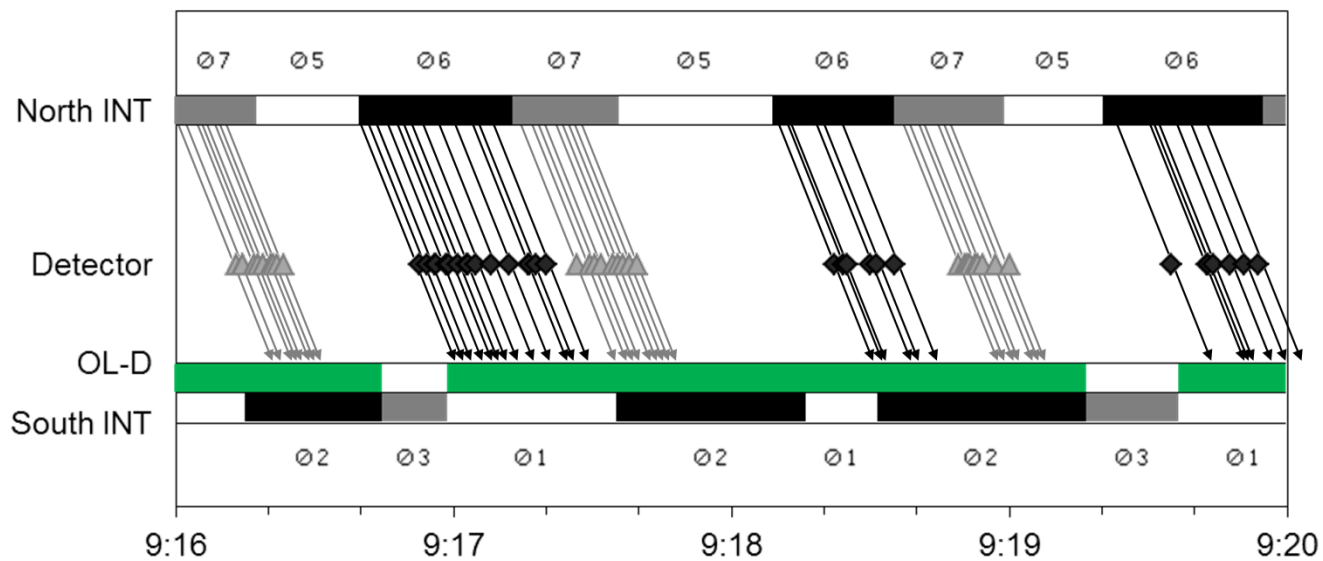
# Upstream Source Phase?

*Look upstream ~10 seconds at the signal phase*



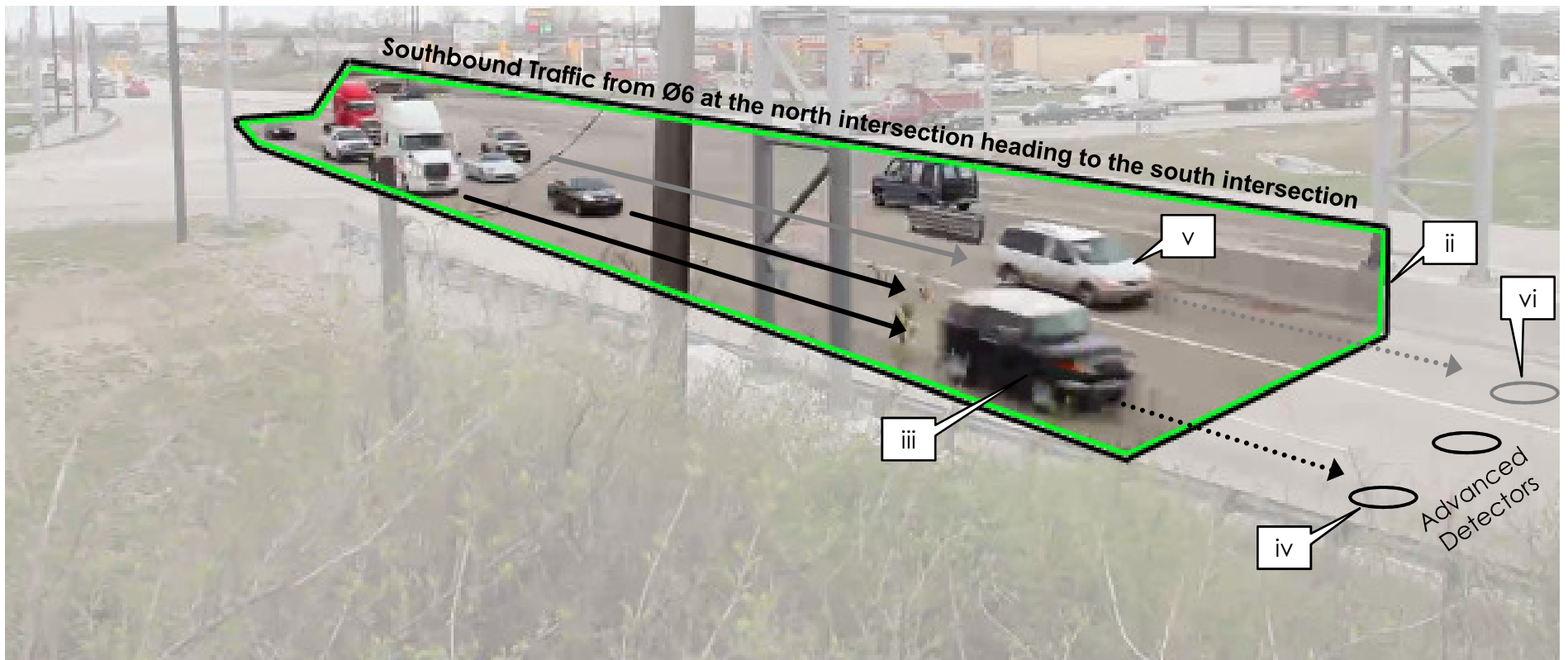
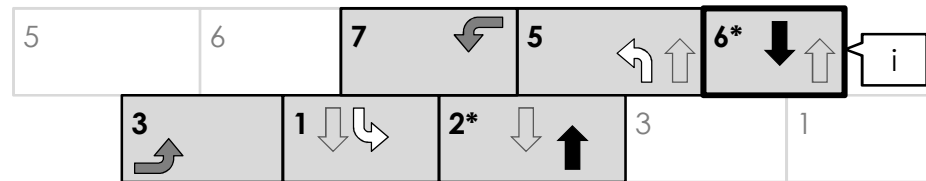
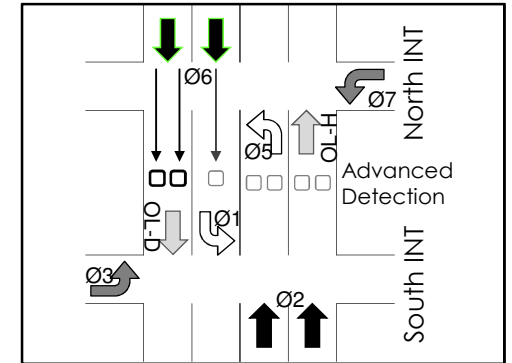
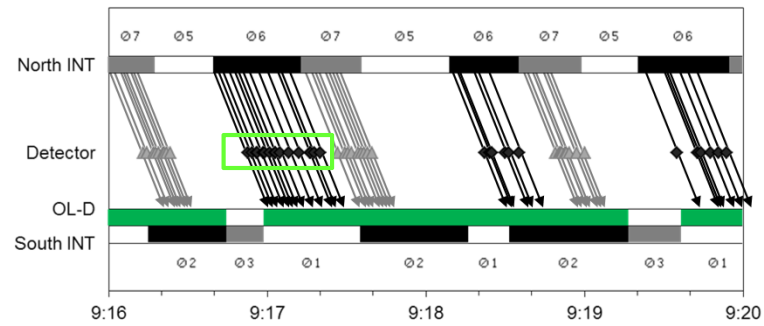
# Now Platoons are Attributed to a Phase

*The vehicles' sources are known*



# Traffic from SBT

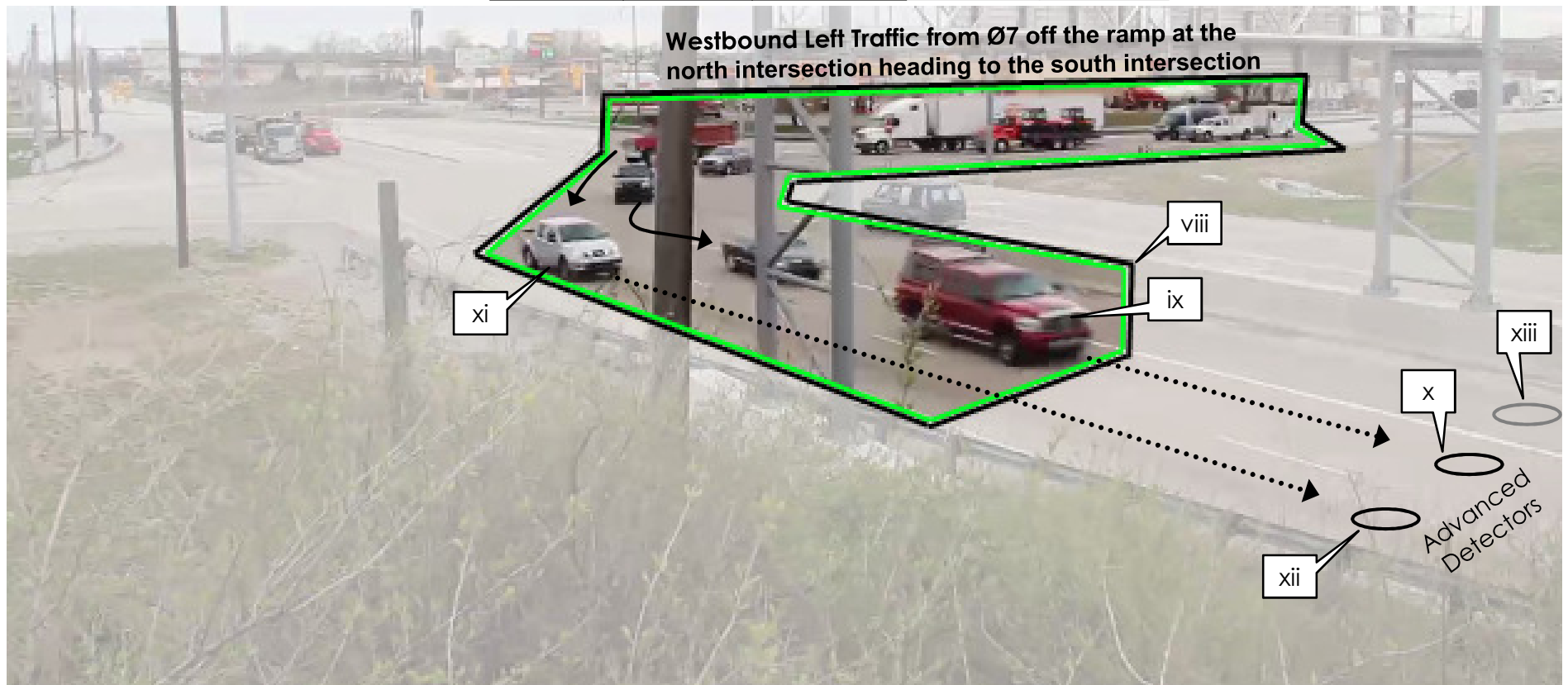
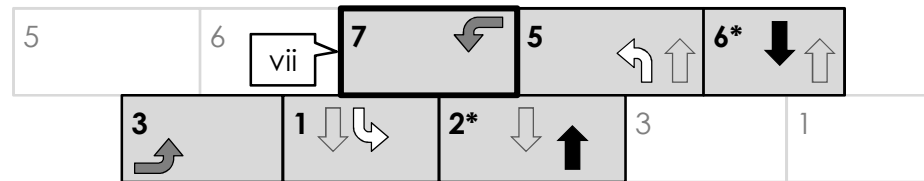
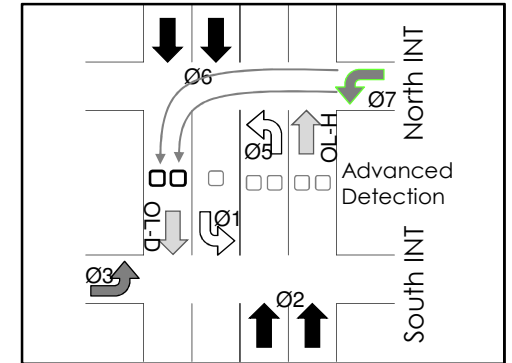
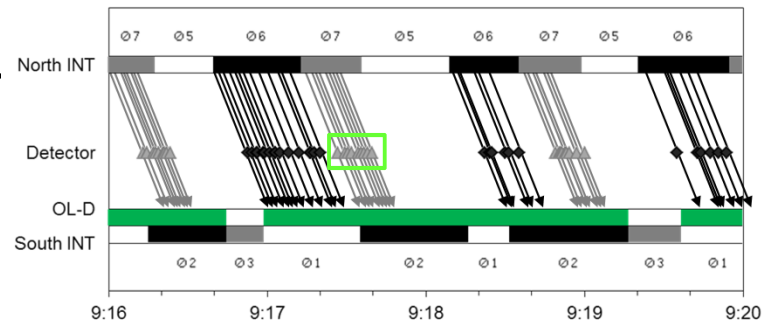
## *Vehicles from Ø6*





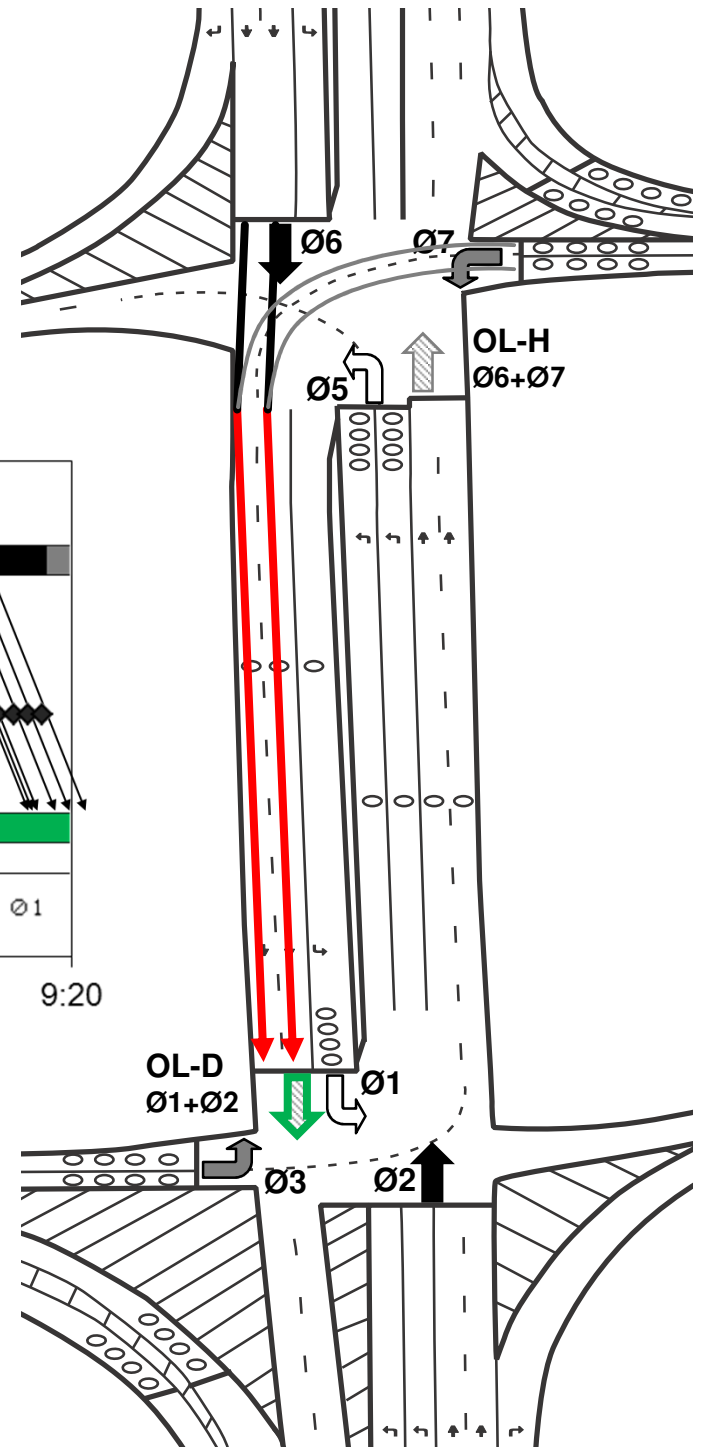
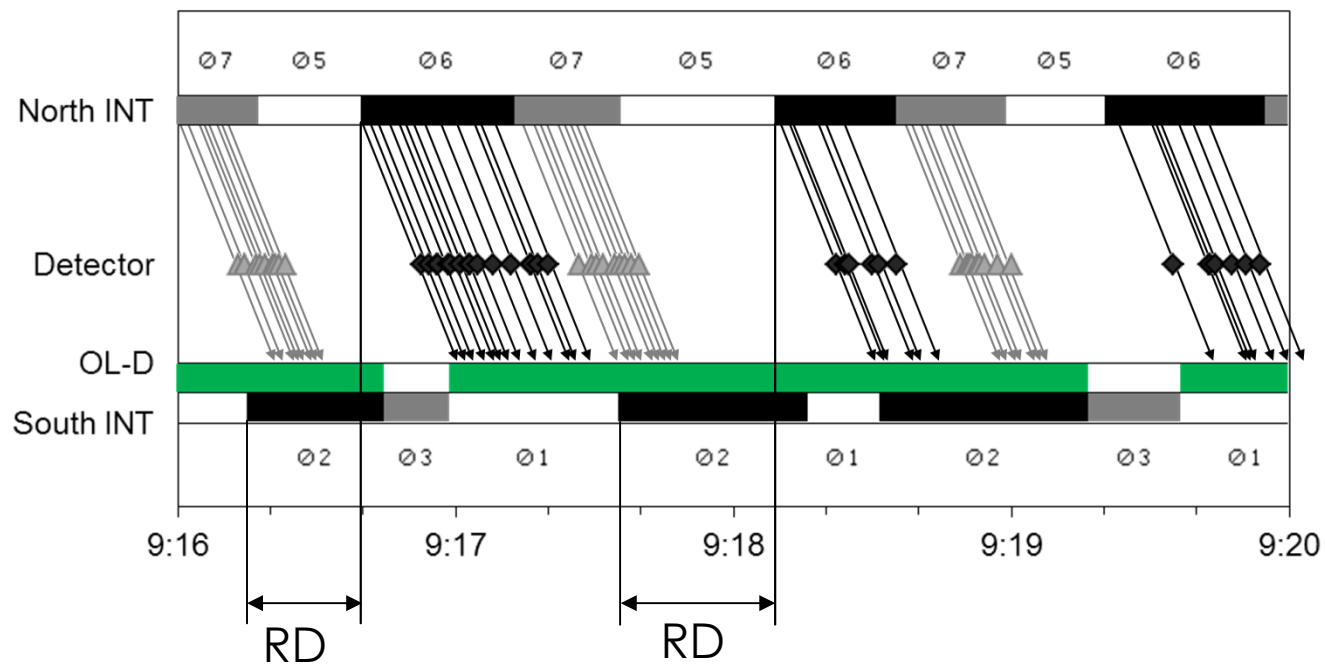
# Traffic from WBL

## *Vehicles from Ø7*



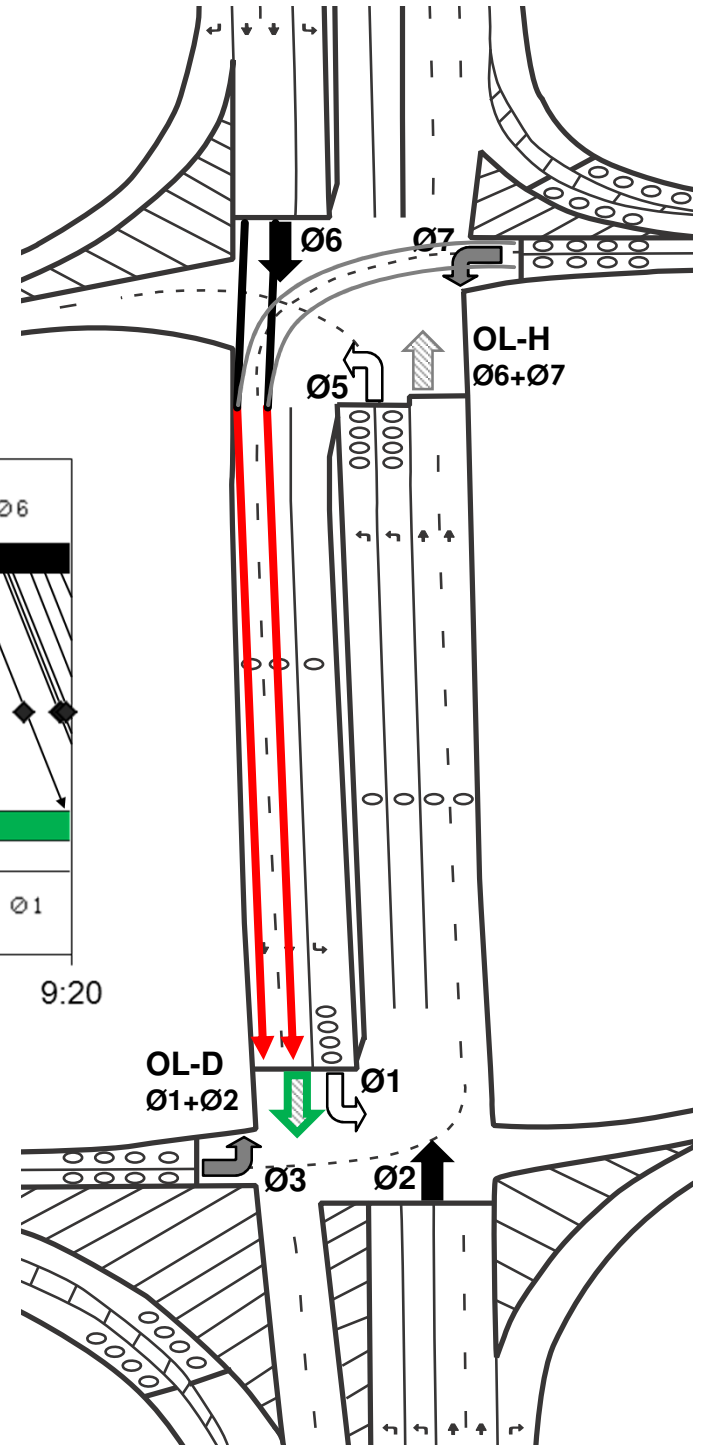
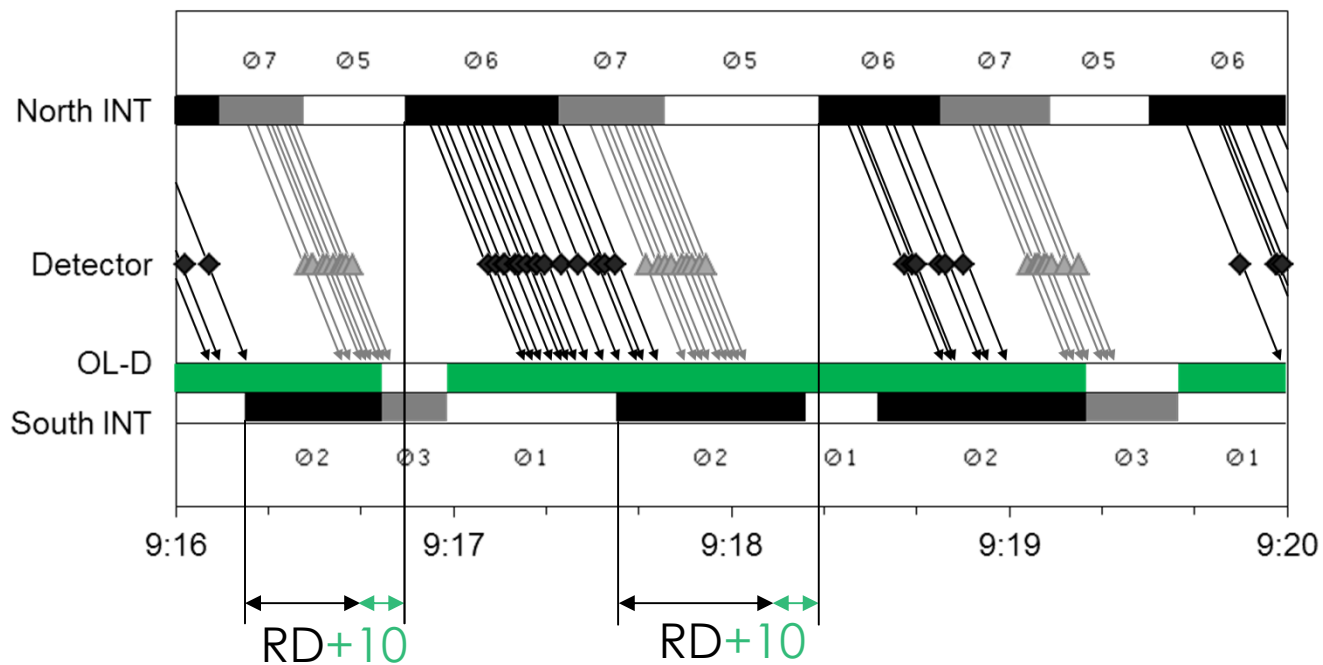
# Adjusting the ring displacement

*What effect would it have?*



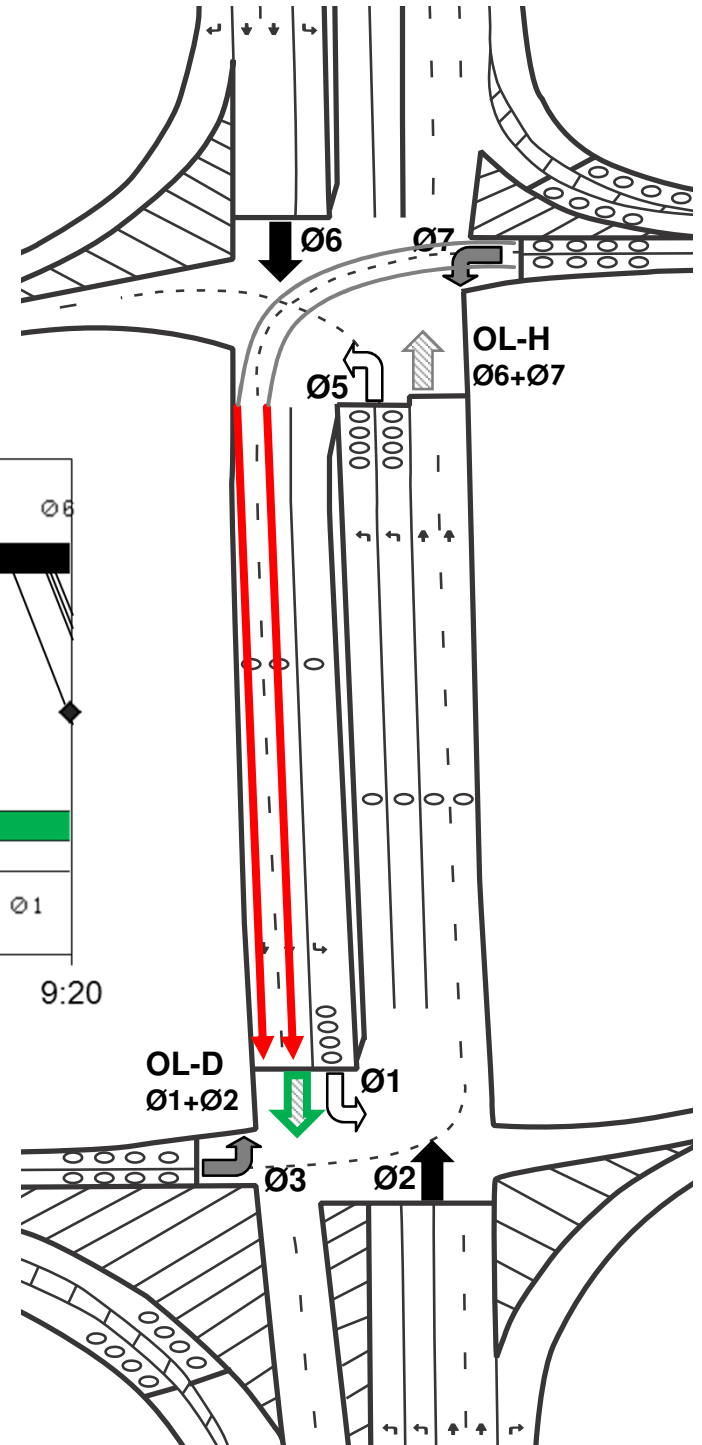
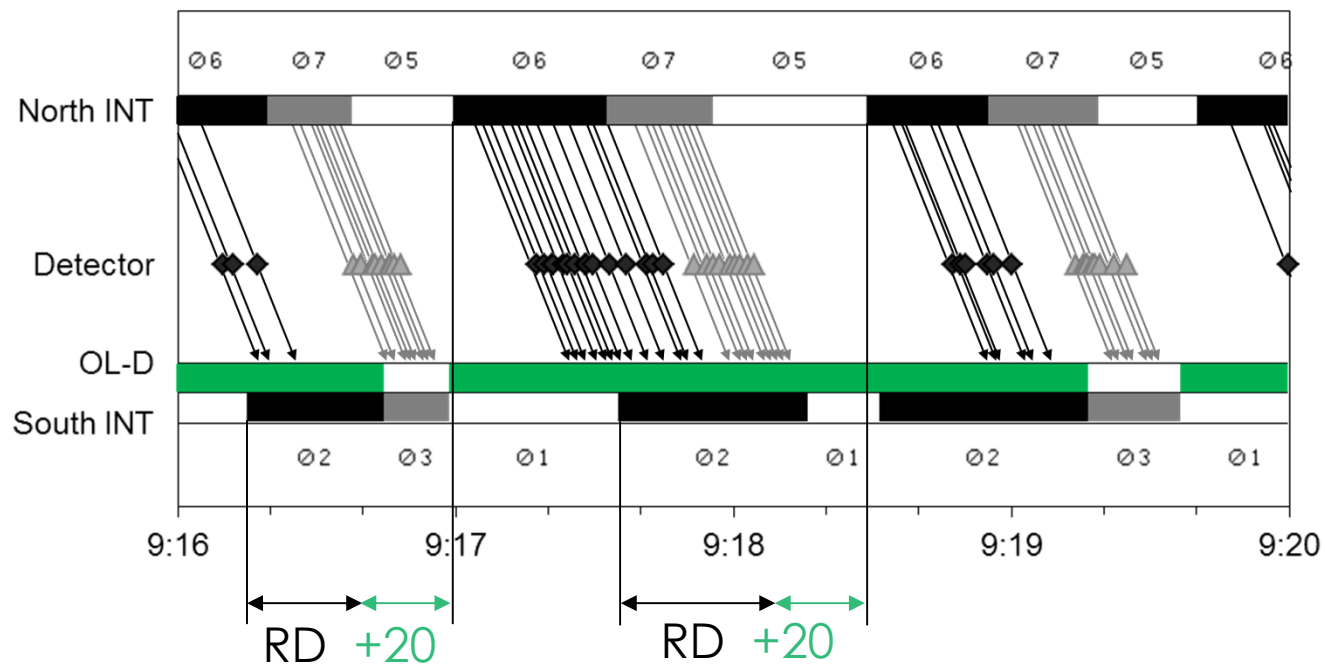
# Ring Displacement **+10 Seconds**

*What effect would it have?*



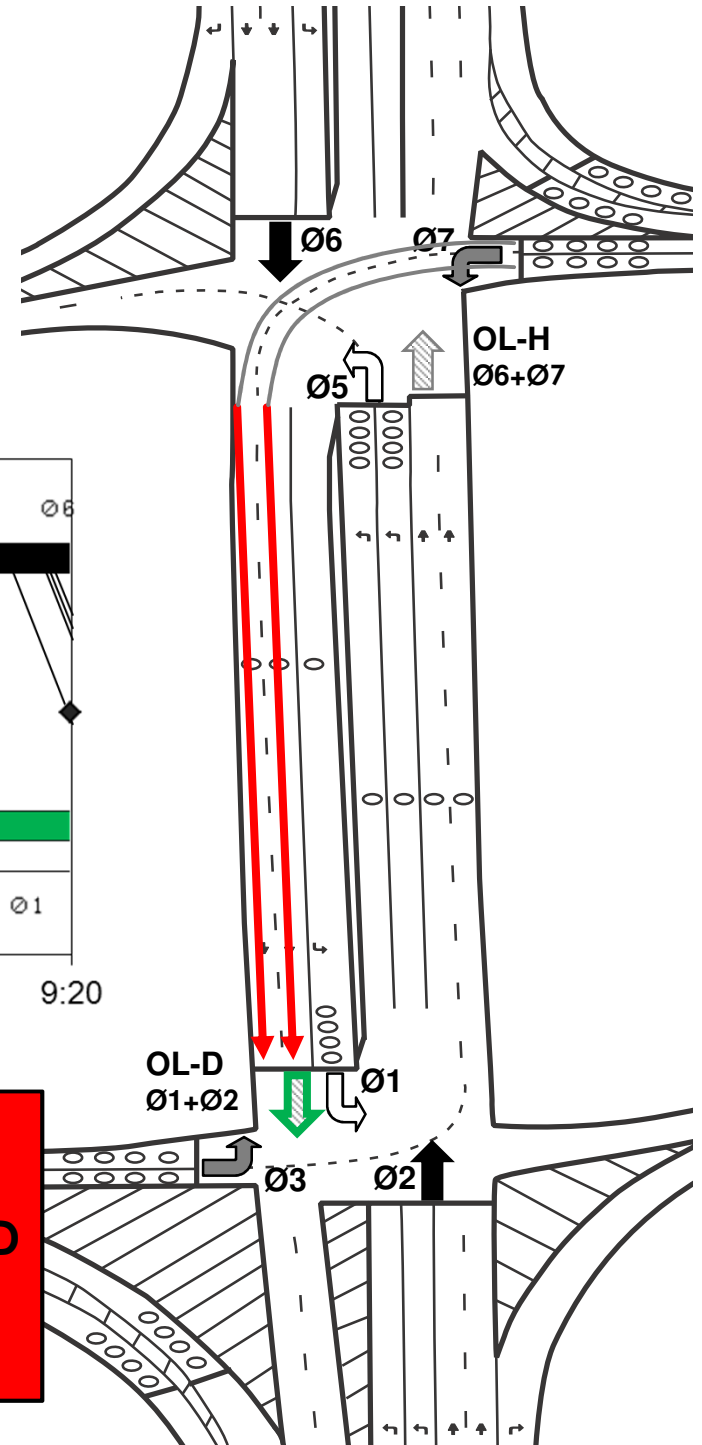
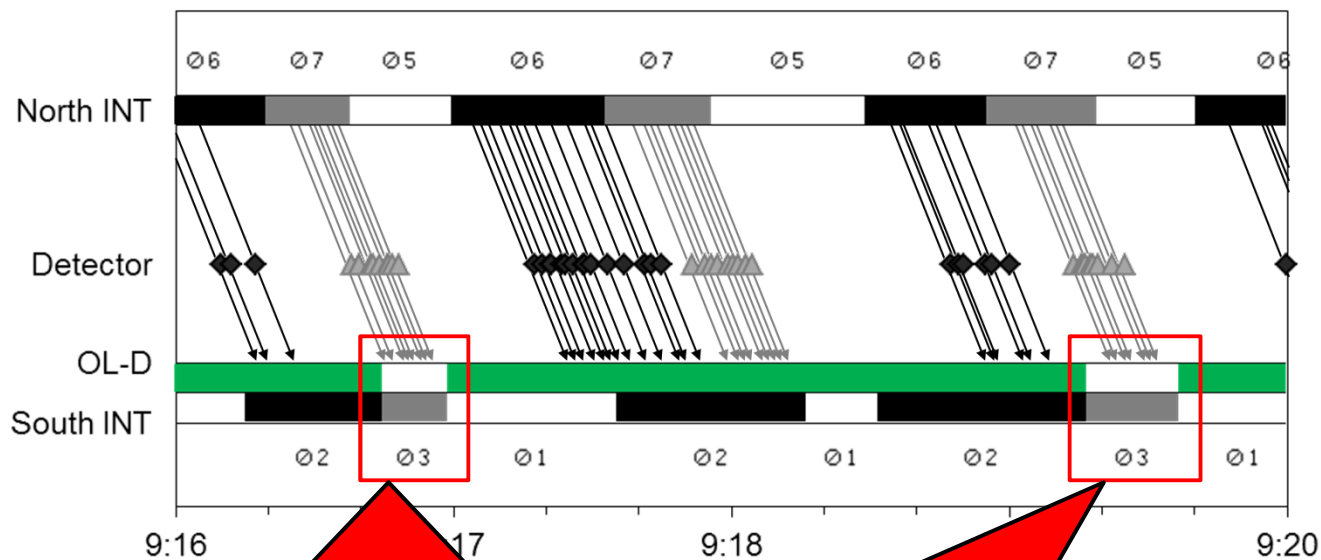
# Ring Displacement **+20 Seconds**

*Vehicles from upstream arrive later*



# Ring Displacement +20 Seconds

*Vehicles from upstream arrive later*



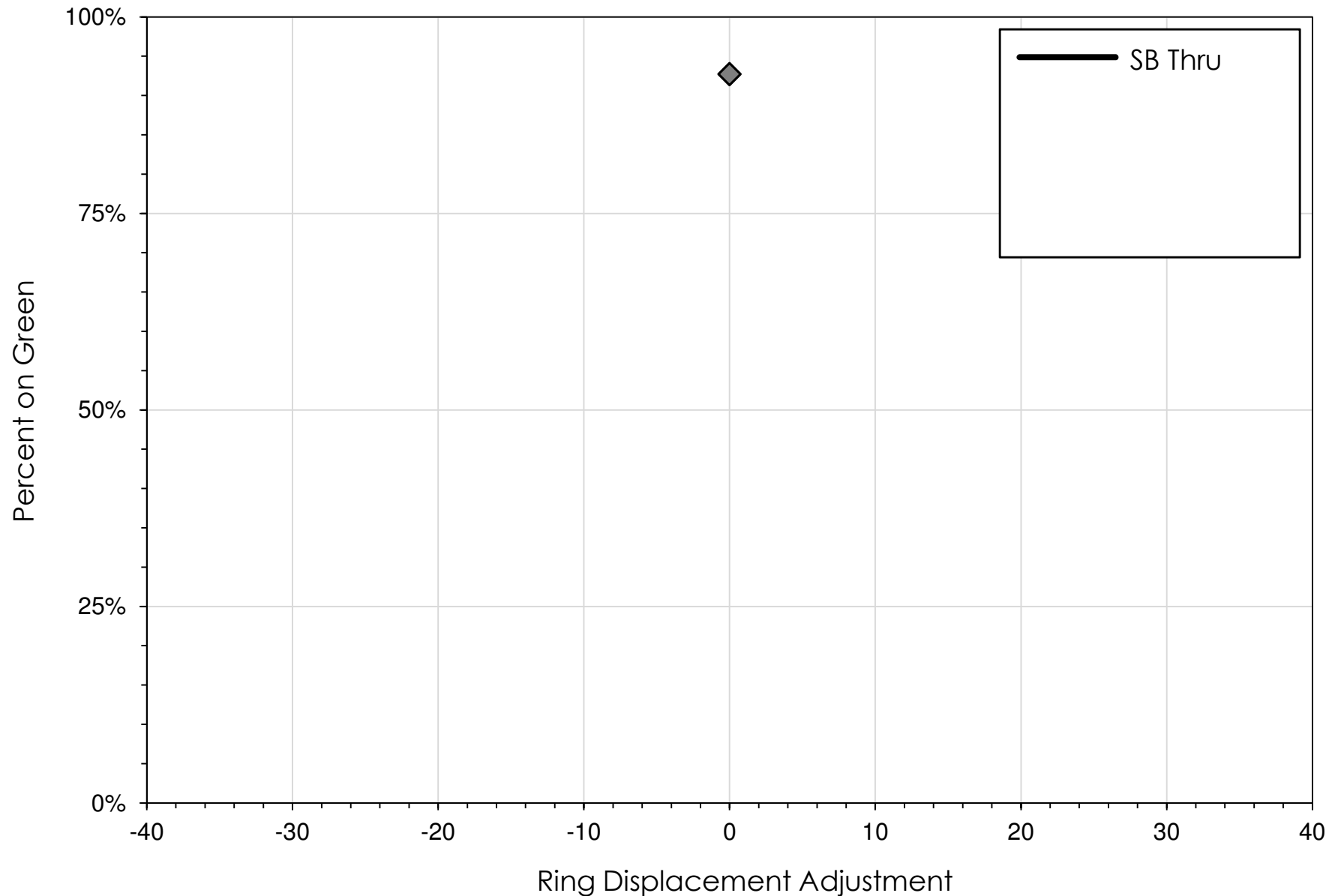
By moving the ring displacement 20 seconds forward, the lagging WBL from the north ramp movement arrives at the south intersection on OL-D red while the EBL at the south ramp is served...

**Not Good!**



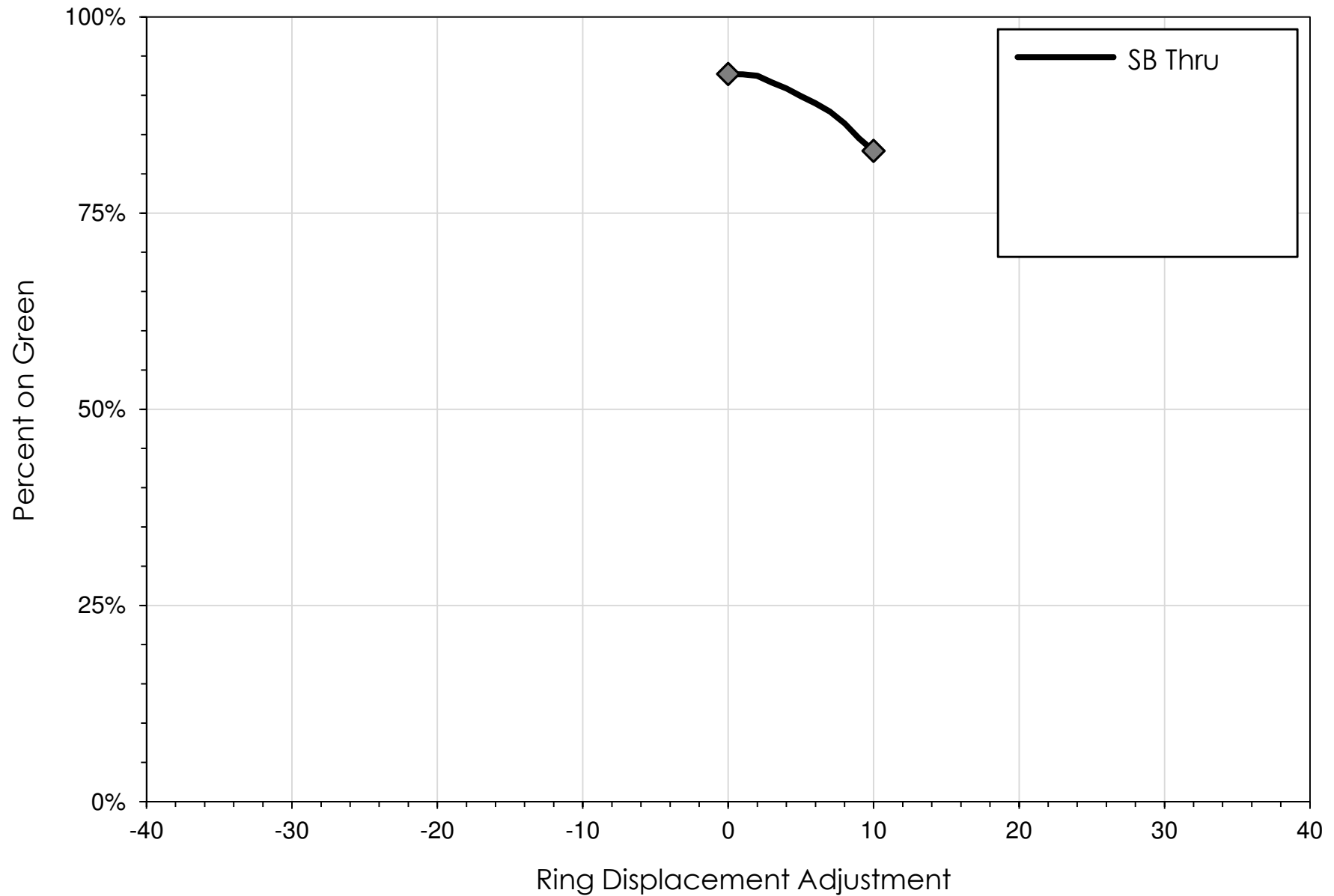
# Optimization Curves

*Let's Look at the Southbound Thru (Our +0, +10, +20 example)*



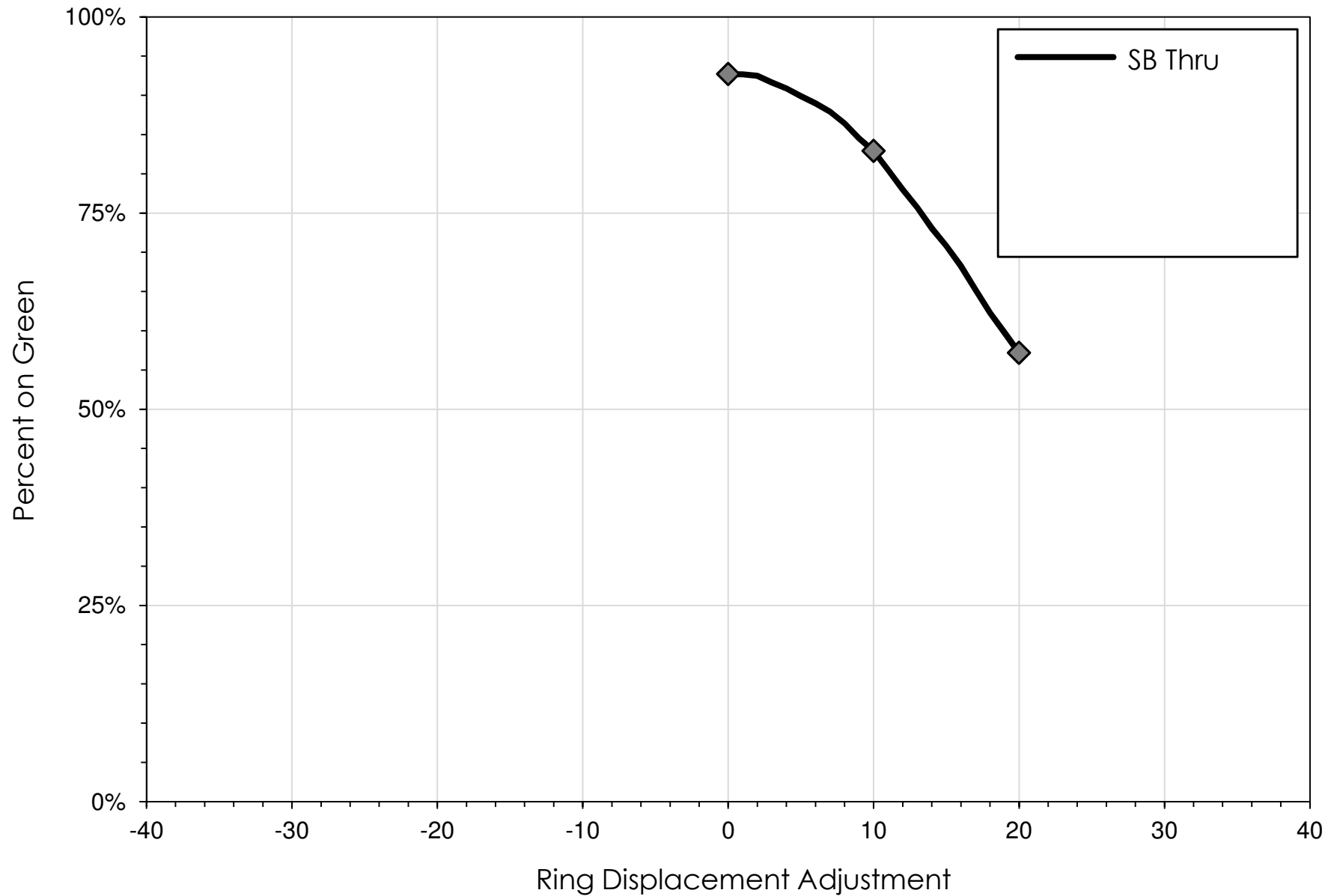
# Optimization Curves

*Southbound Thru +10*



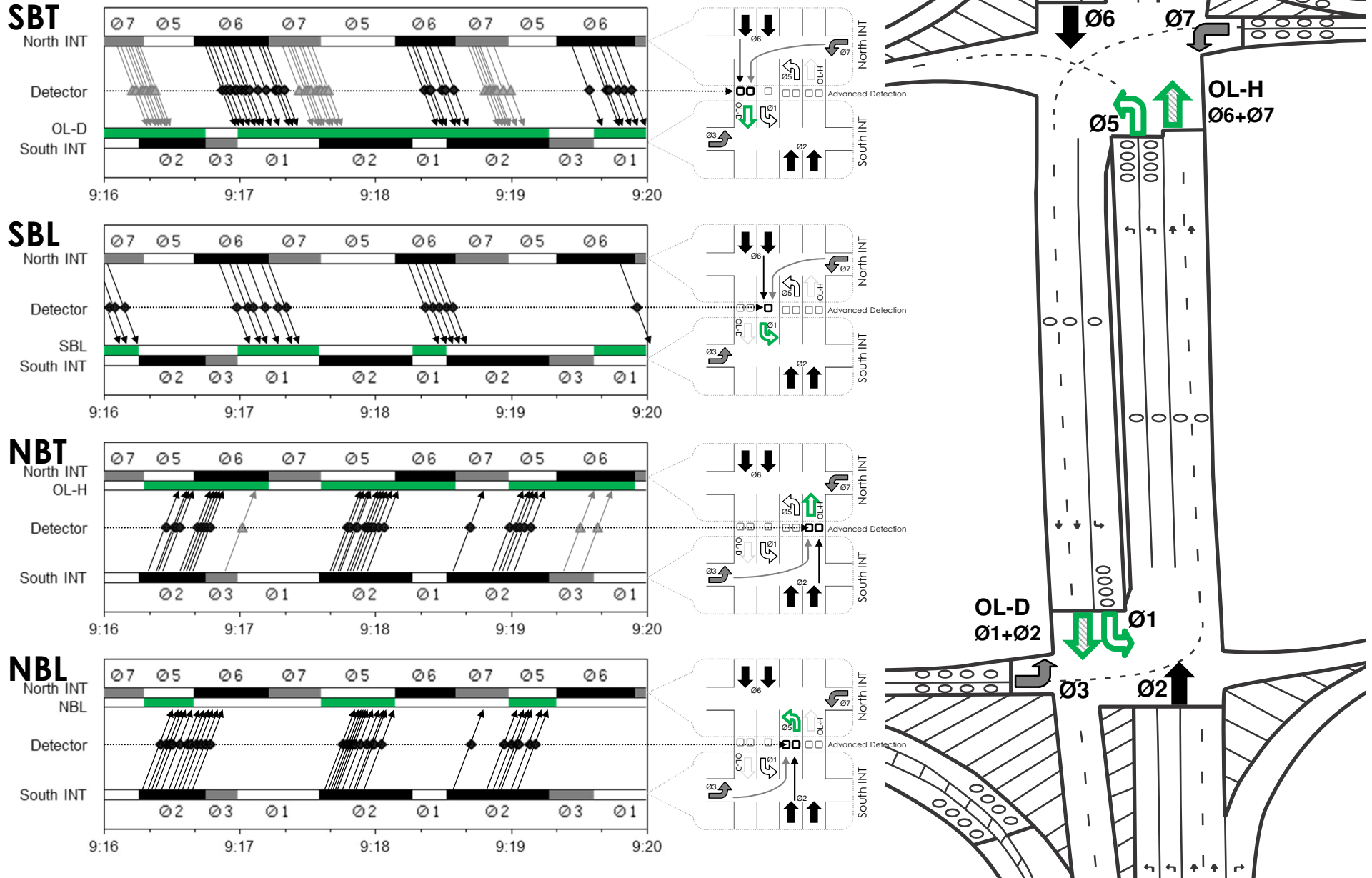
# Optimization Curves

*Southbound Thru +20*



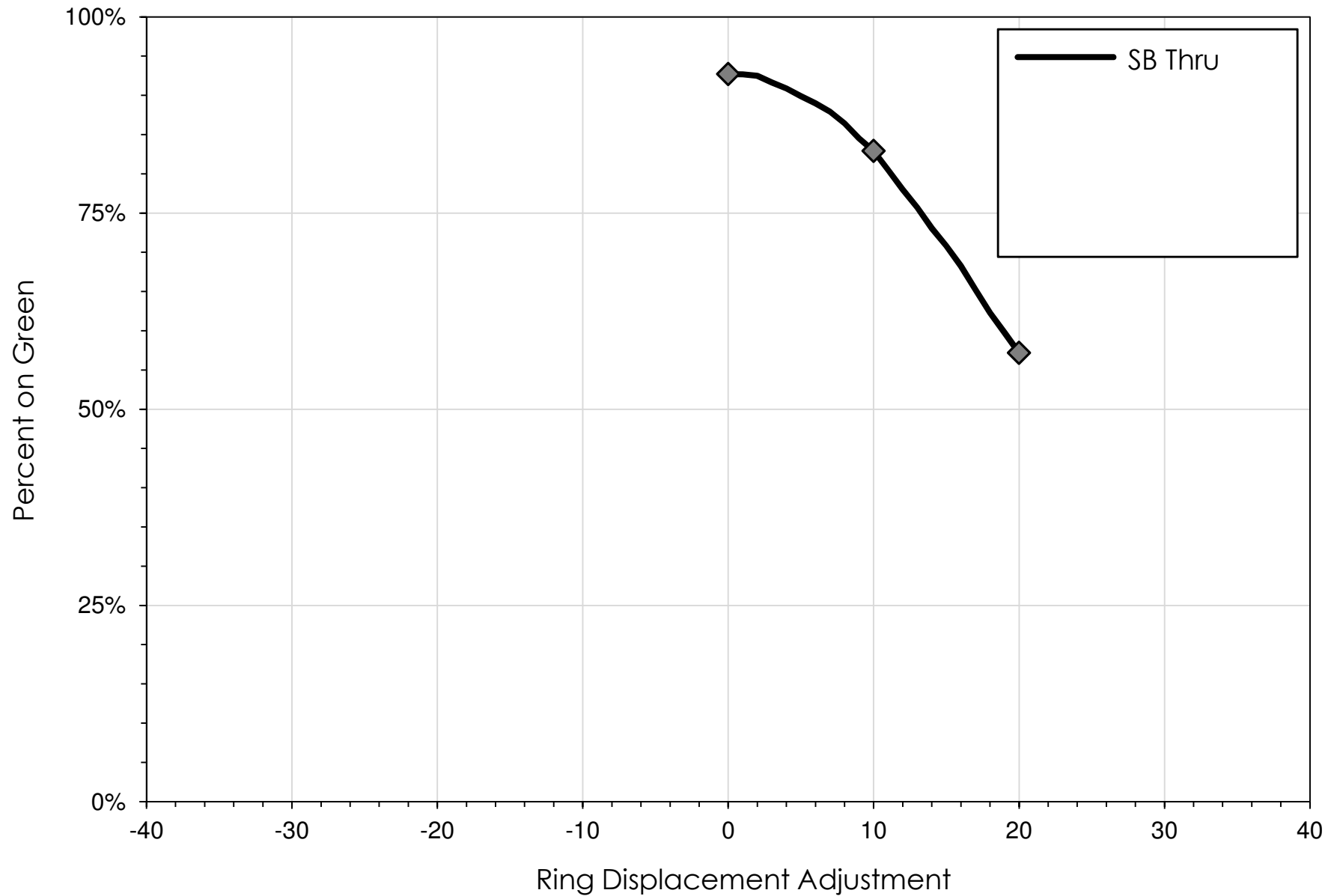
# Optimization Consideration

## *Consider All 4 Movements Simultaneously*



# Optimization Curves

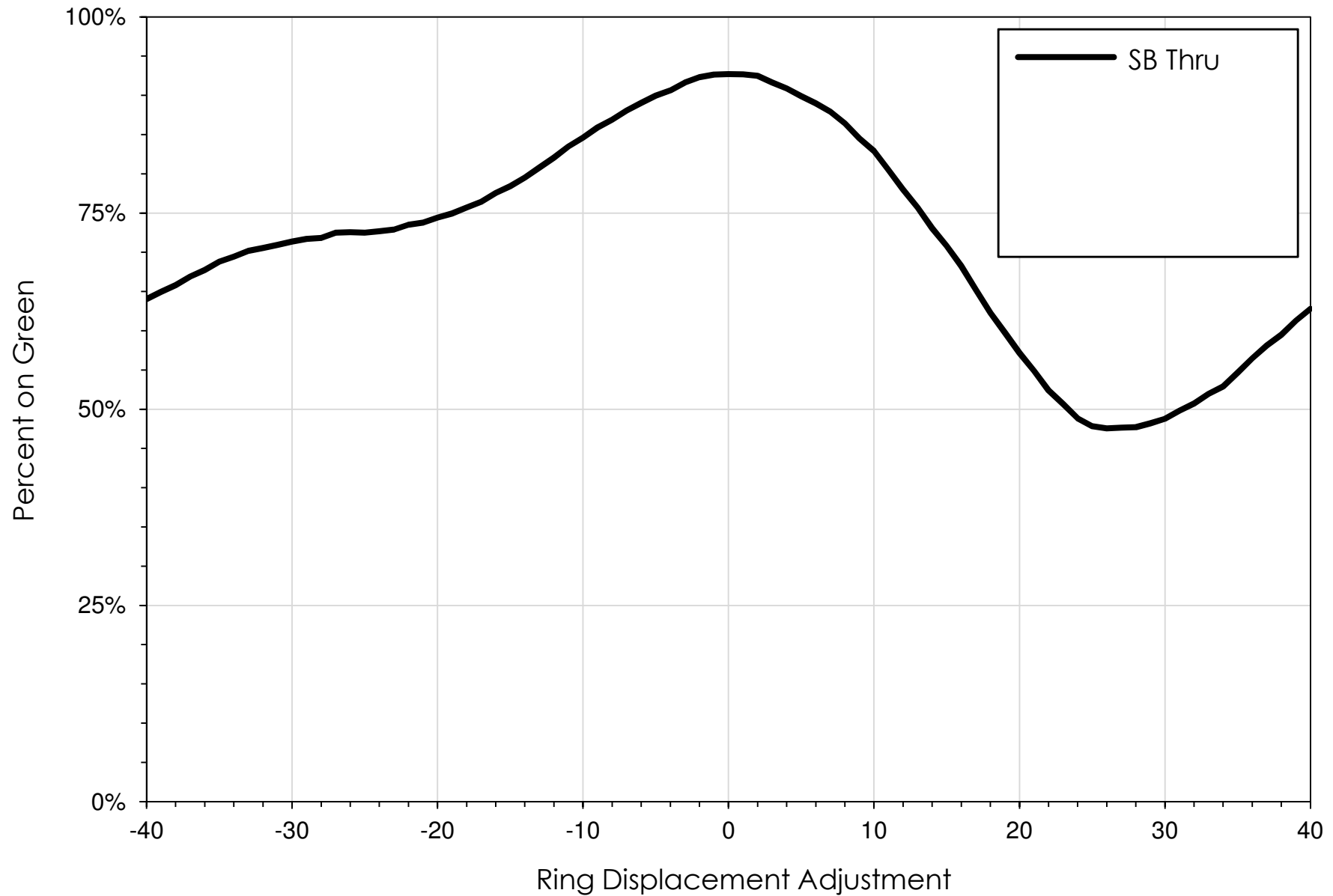
*Southbound Thru +20*





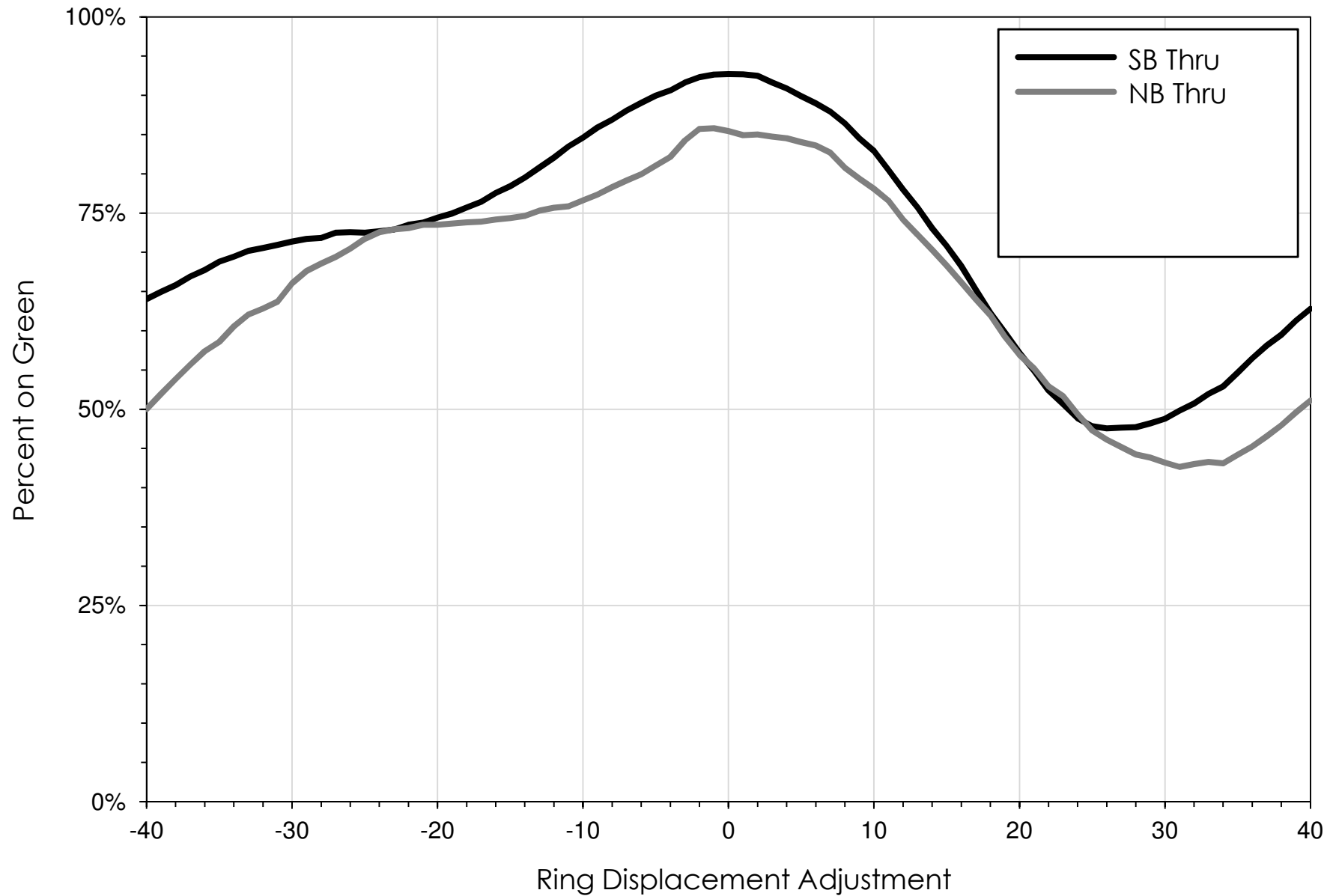
# Optimization Curves

*Southbound Thru for the Full Sweep*



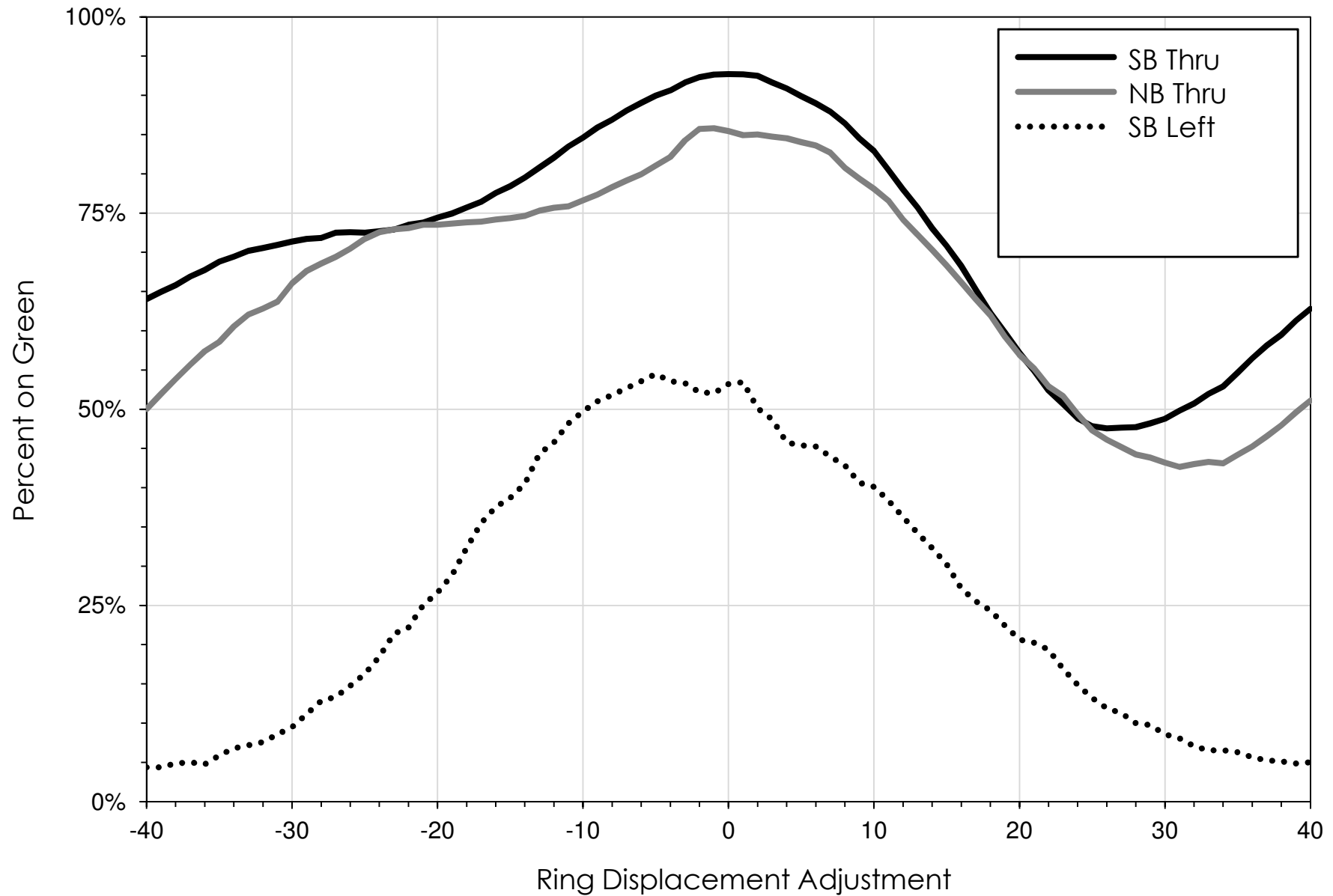
# Optimization Curves

## *Northbound Thru*



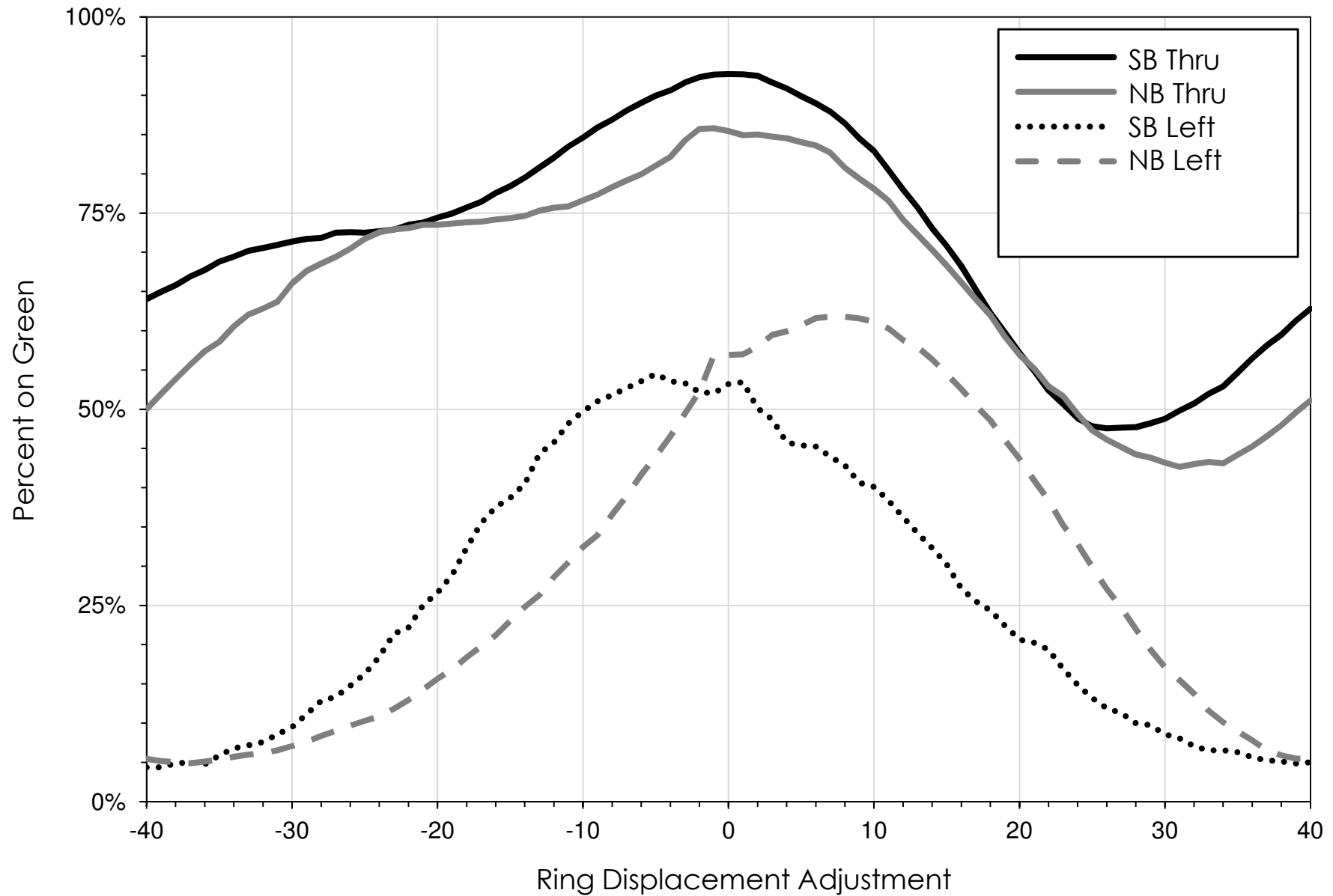
# Optimization Curves

## *Southbound Left*



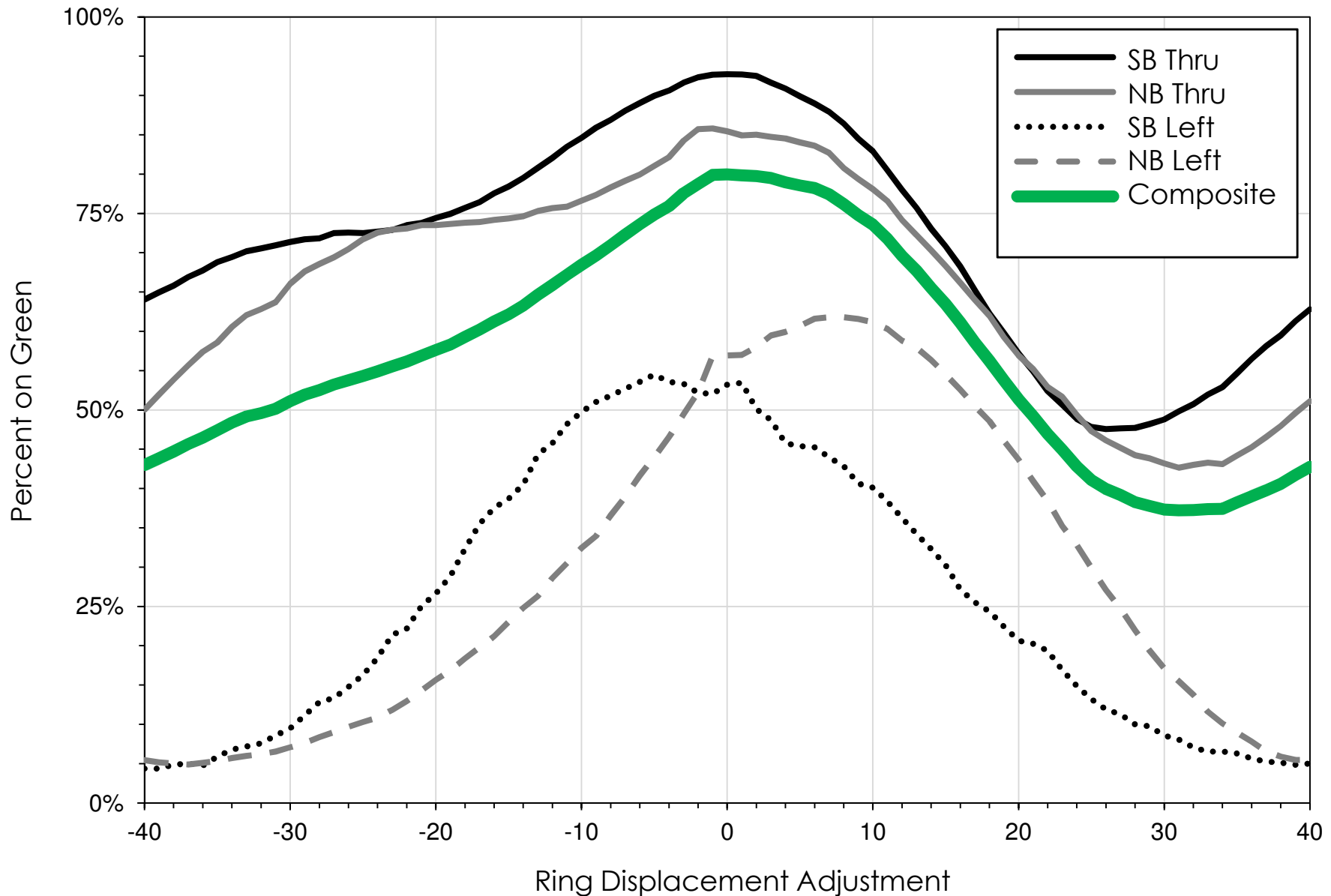
# Optimization Curves

*Northbound Left*



# Composite Interchange Sweep

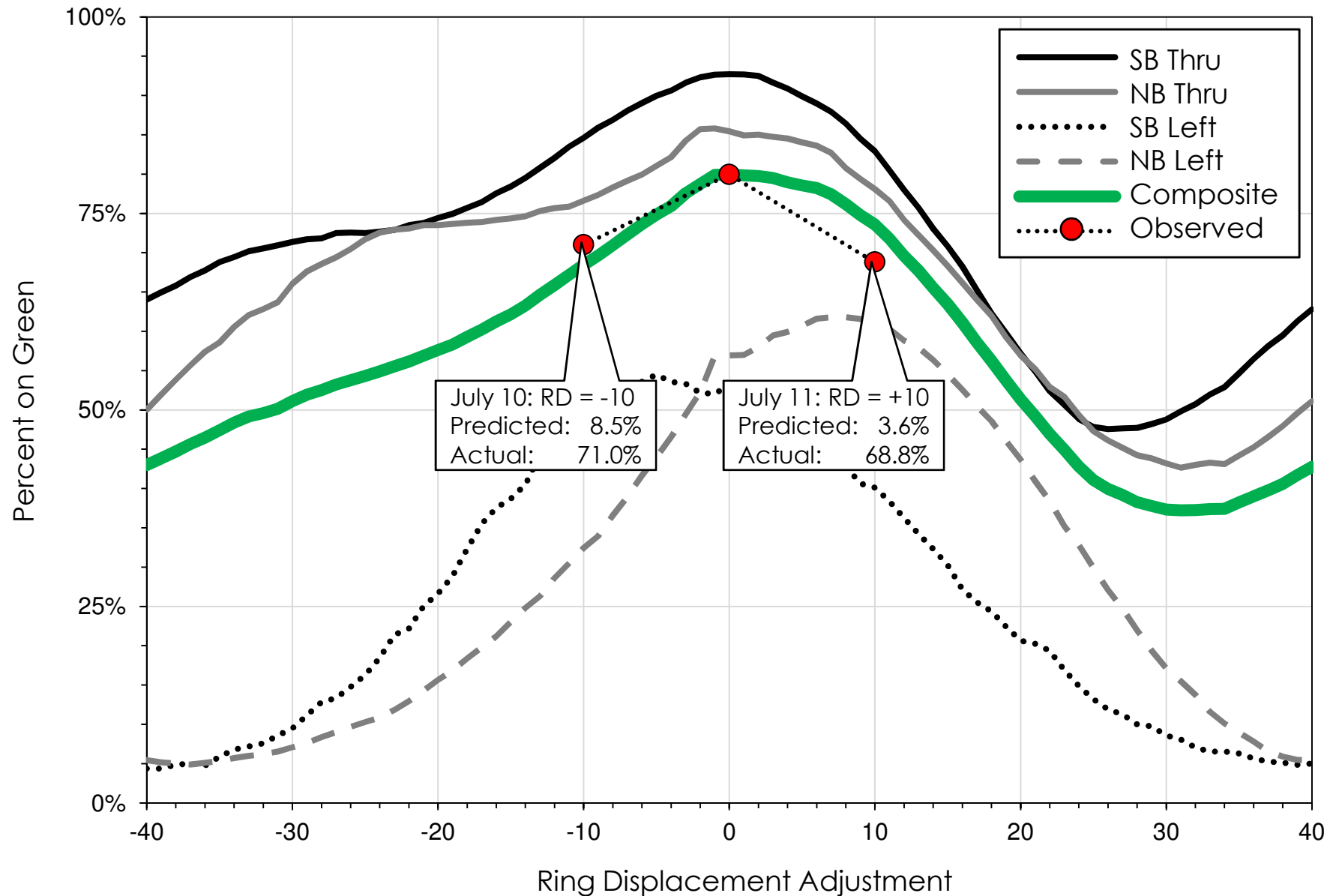
*This is where all four movements are considered simultaneously,*





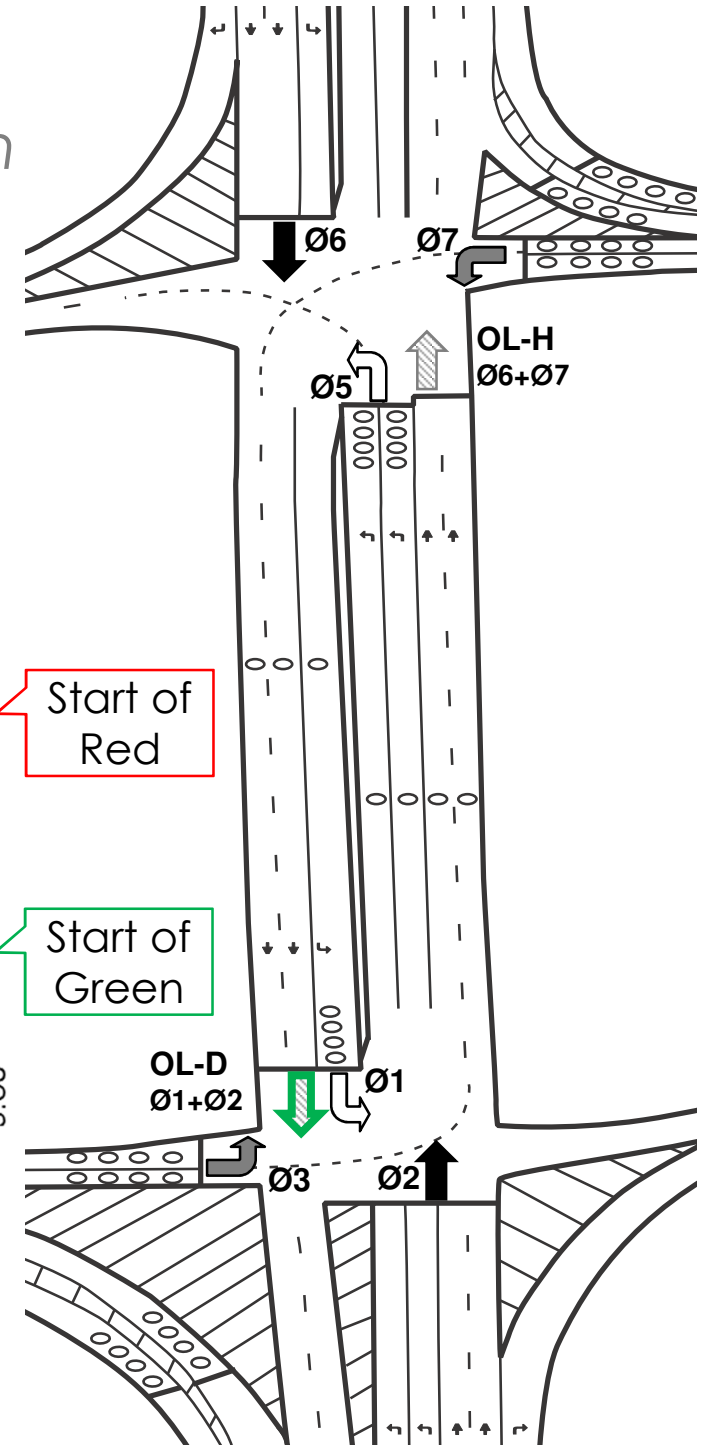
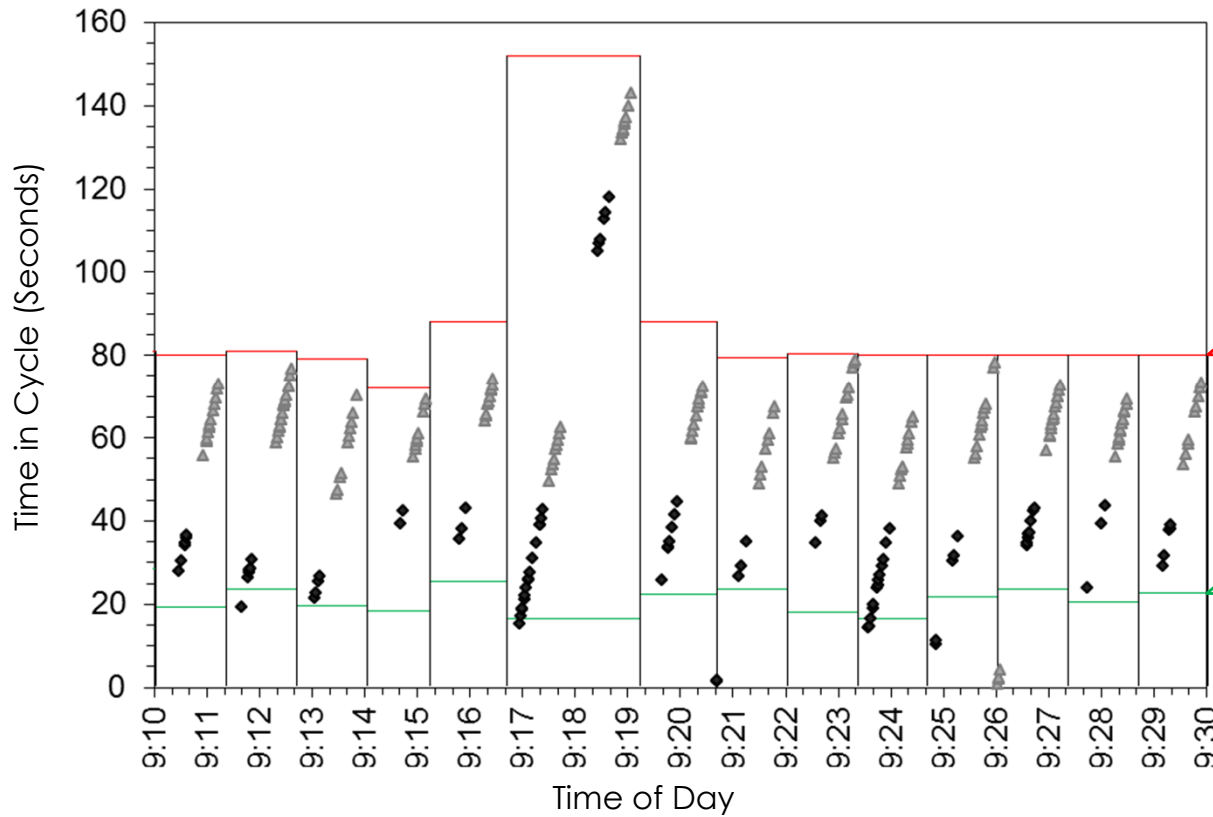
# Field Evaluation

*Adjust +/- 10 to see how it worked in the field*



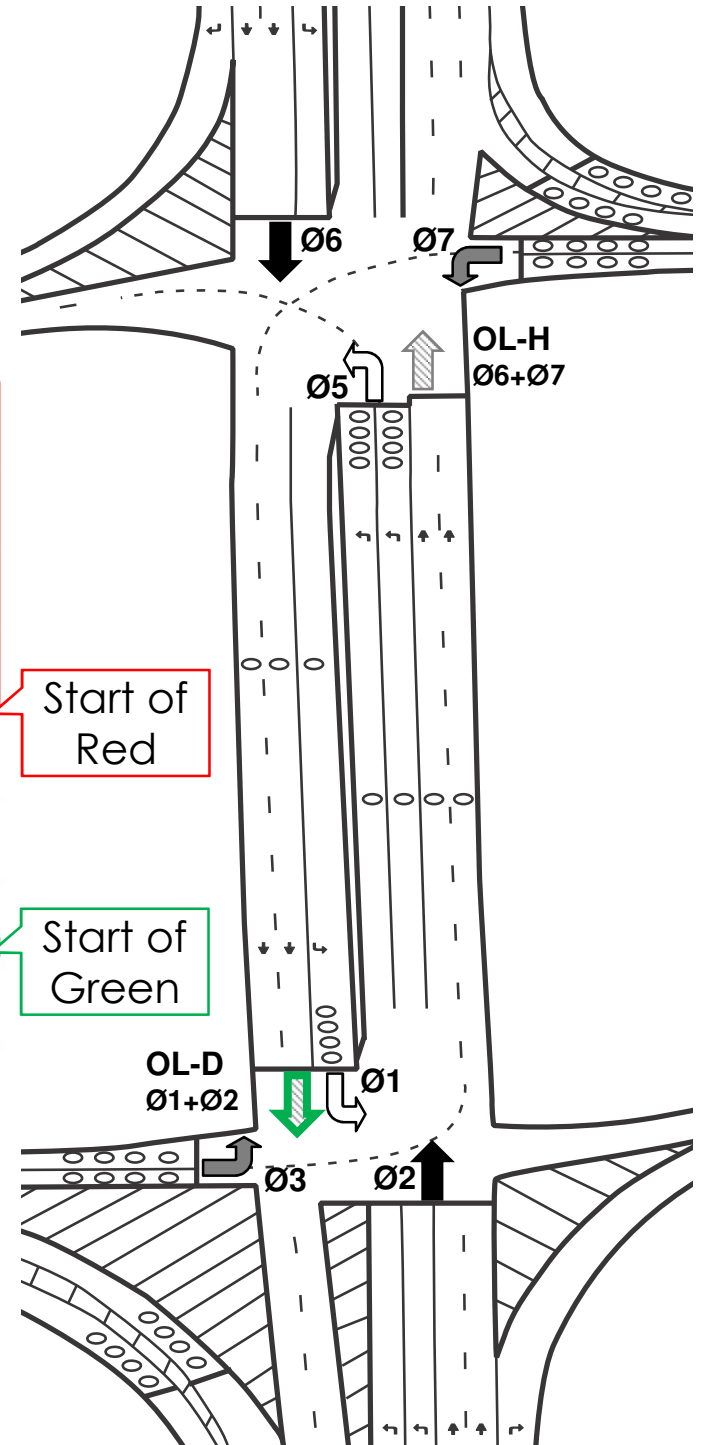
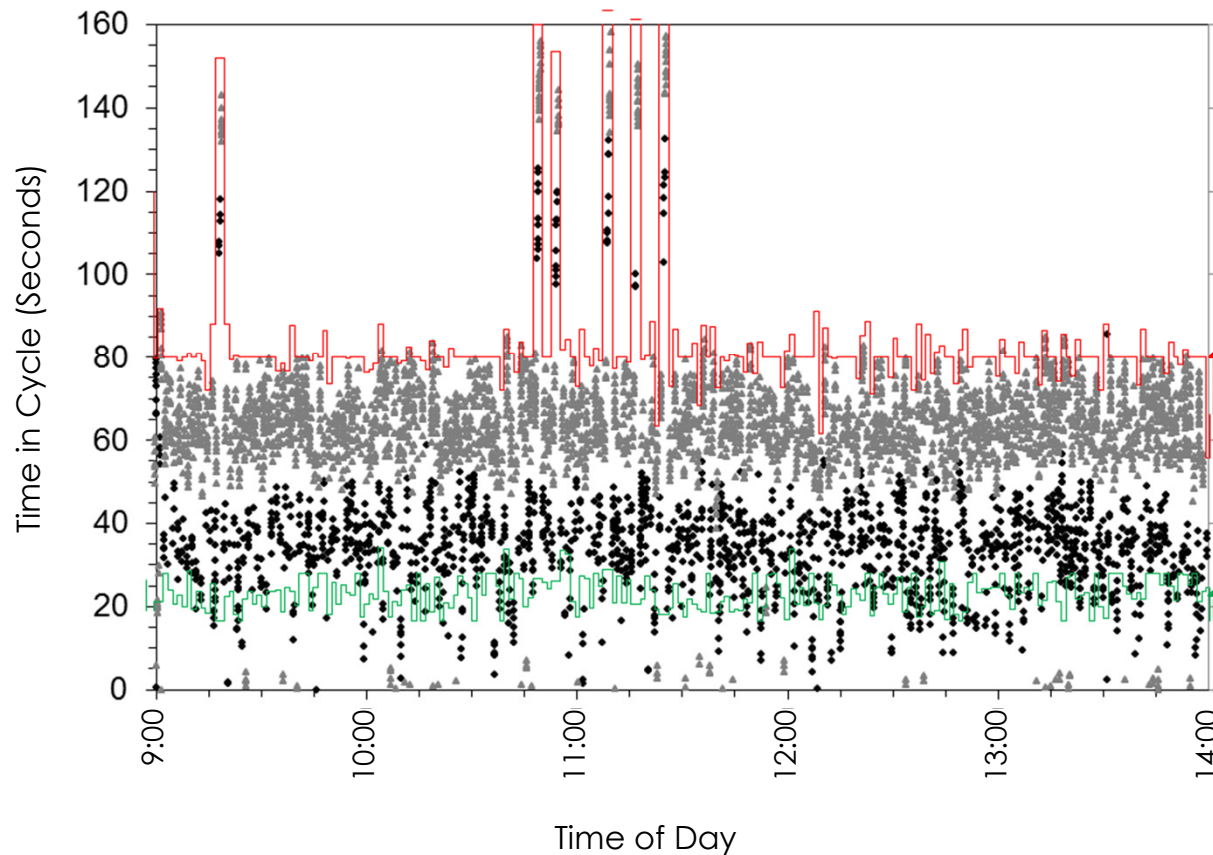
# Purdue Coordination Diagram

*Also Useful to Visualize Arrivals on Green*



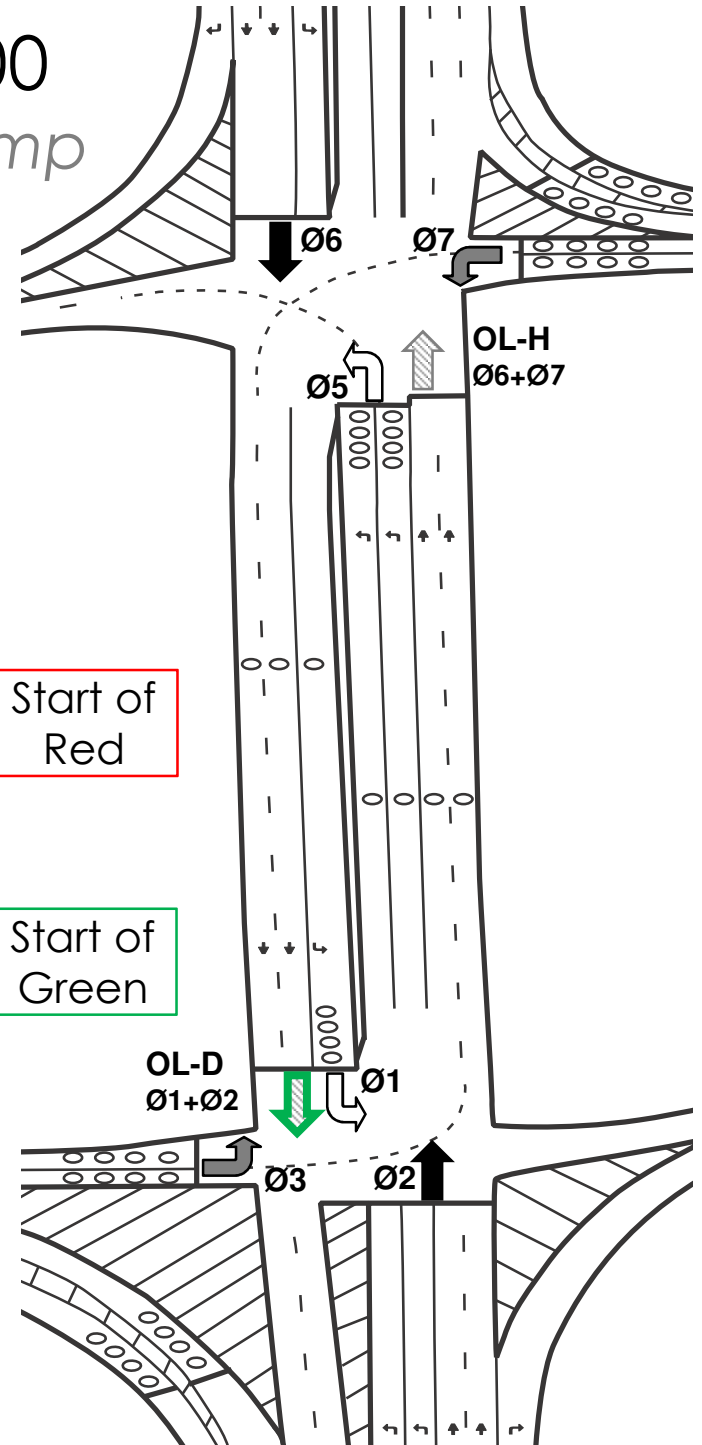
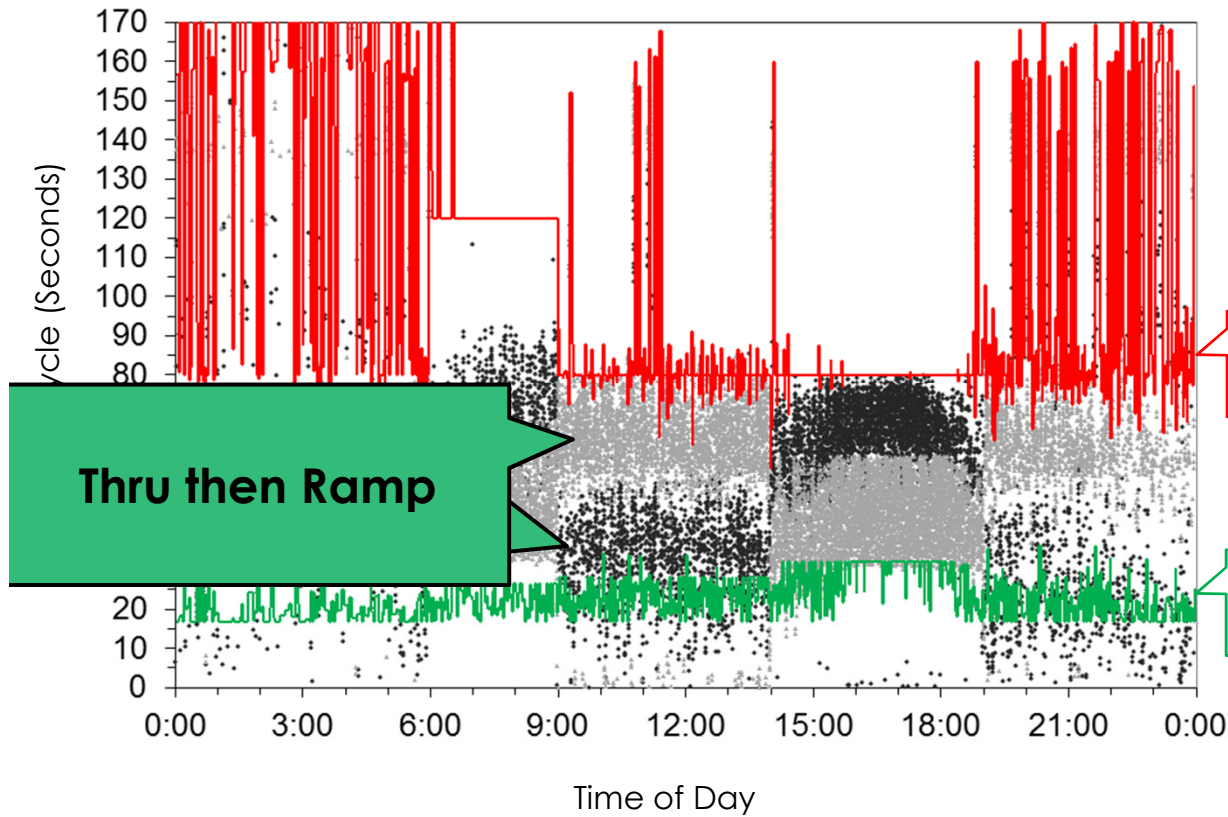
# Purdue Coordination Diagram

*Looking at an entire plan (0900-1400)*



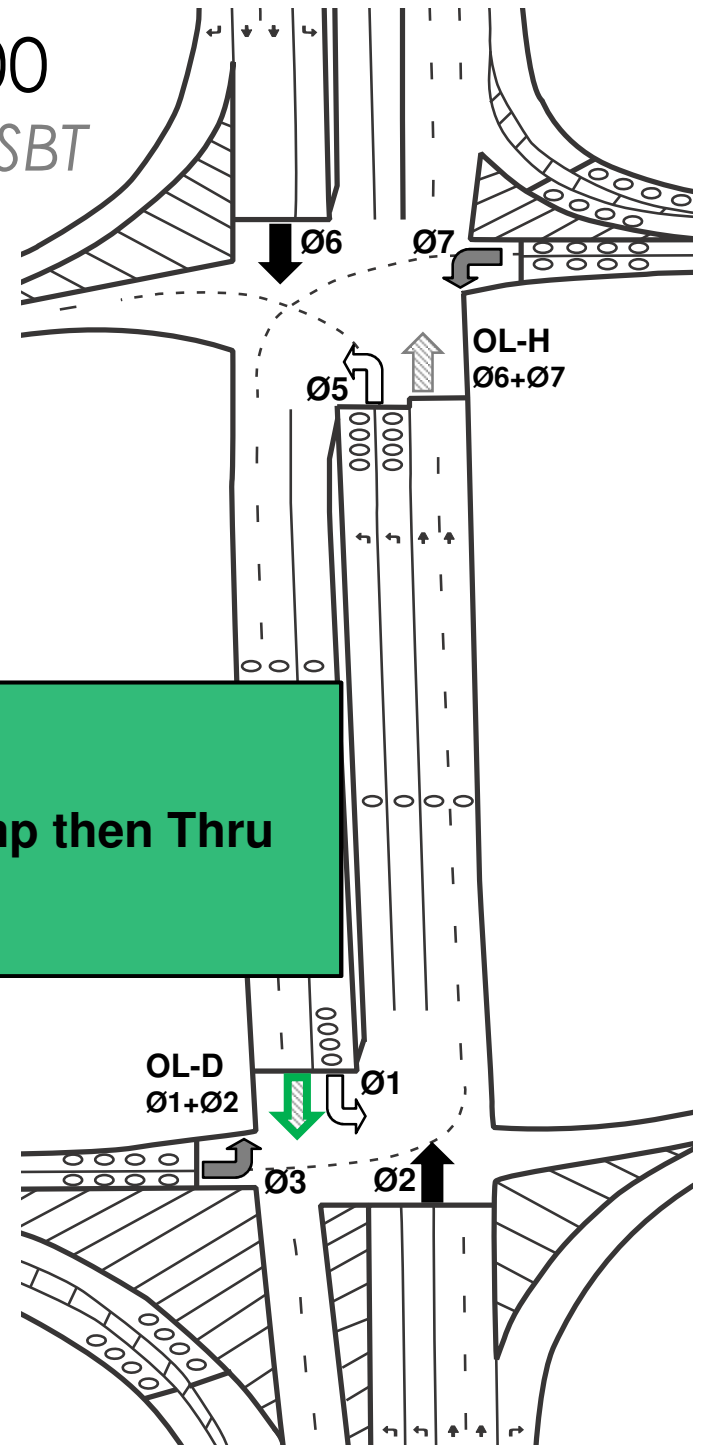
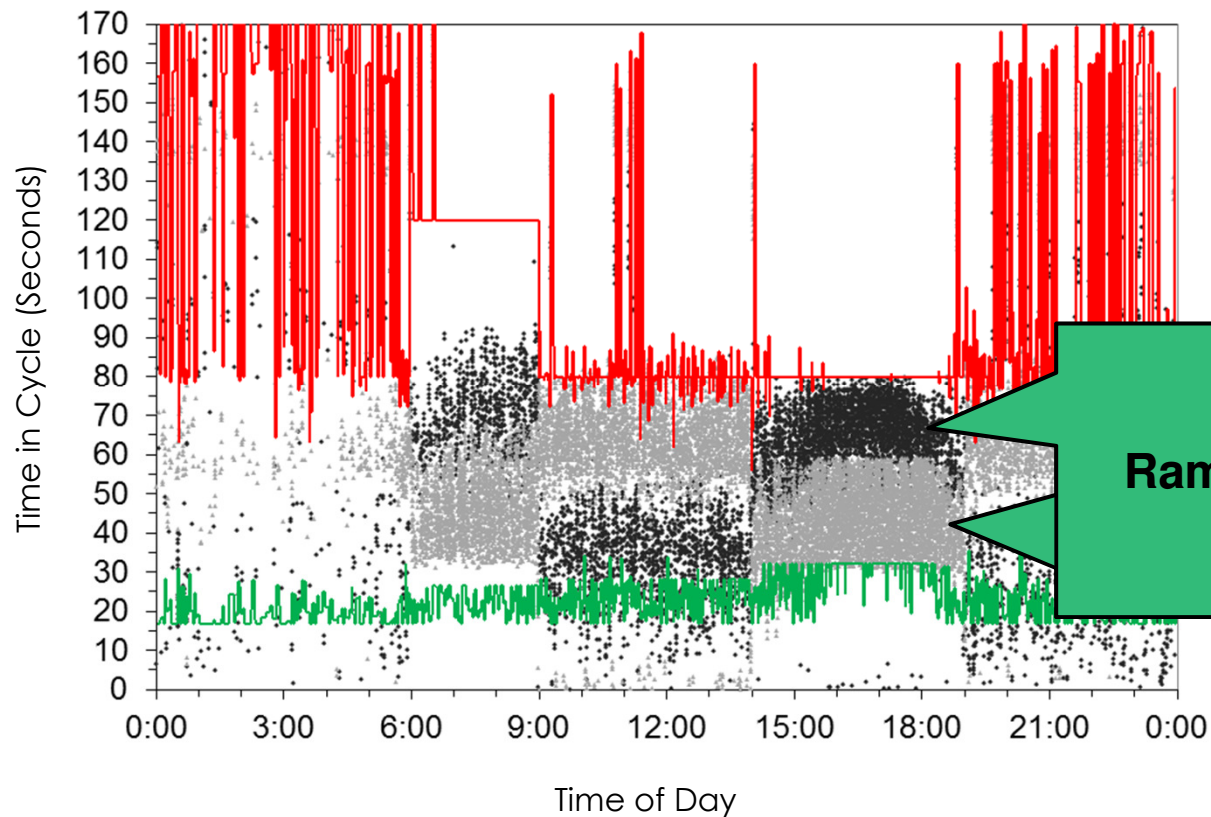
# 24HR PCD: Sequence for 0900-1400

*First is Ø6 SBT, then Ø7 WBL from the ramp*



# 24HR PCD: Sequence for 1400-1900

*First is Ø7 WBL from the ramp, then Ø6 SBT*





Conclusion: These Graphics are Useful!

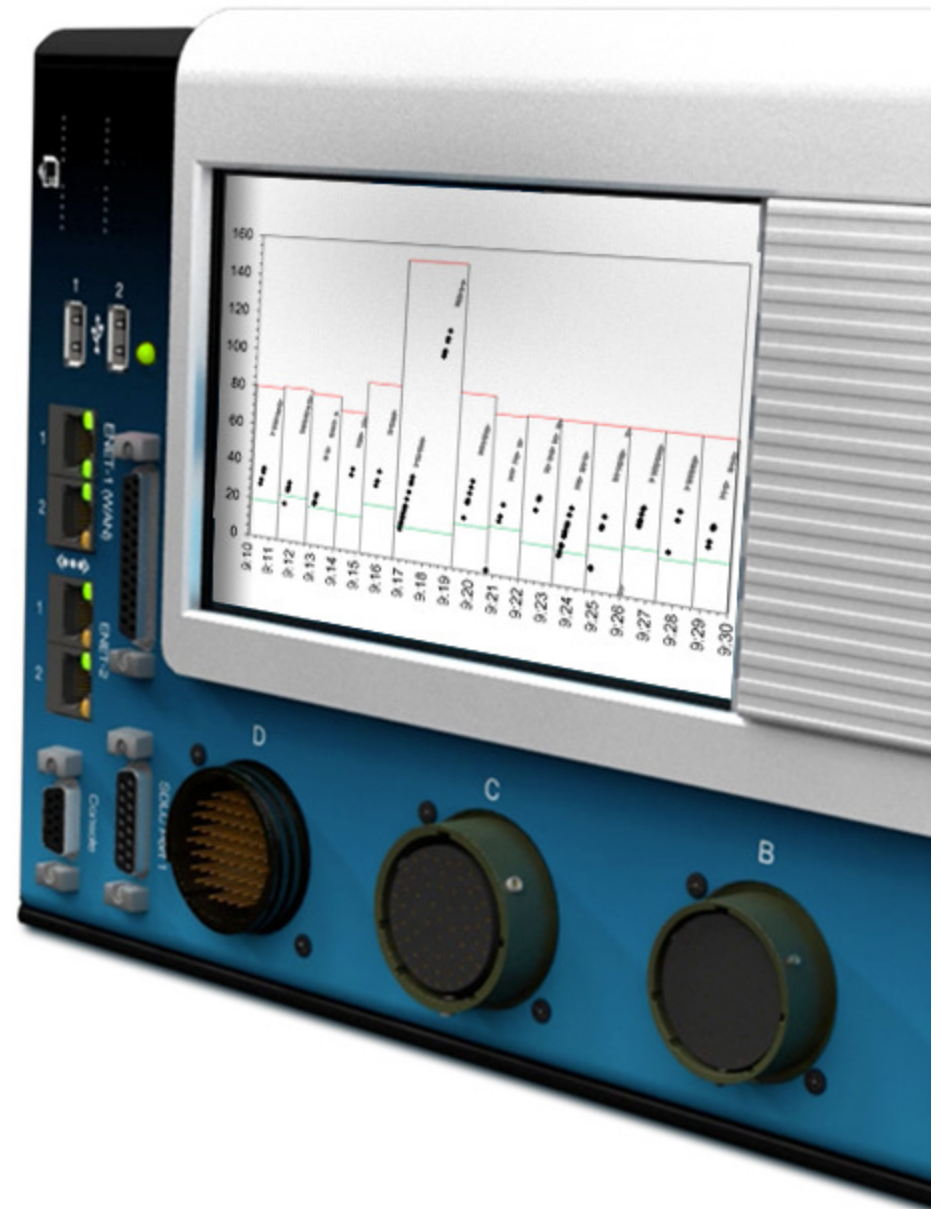
*Can they be included on newer generation traffic controllers?*





Conclusion: These Graphics are Useful!

*Can they be included on newer generation traffic controllers?*



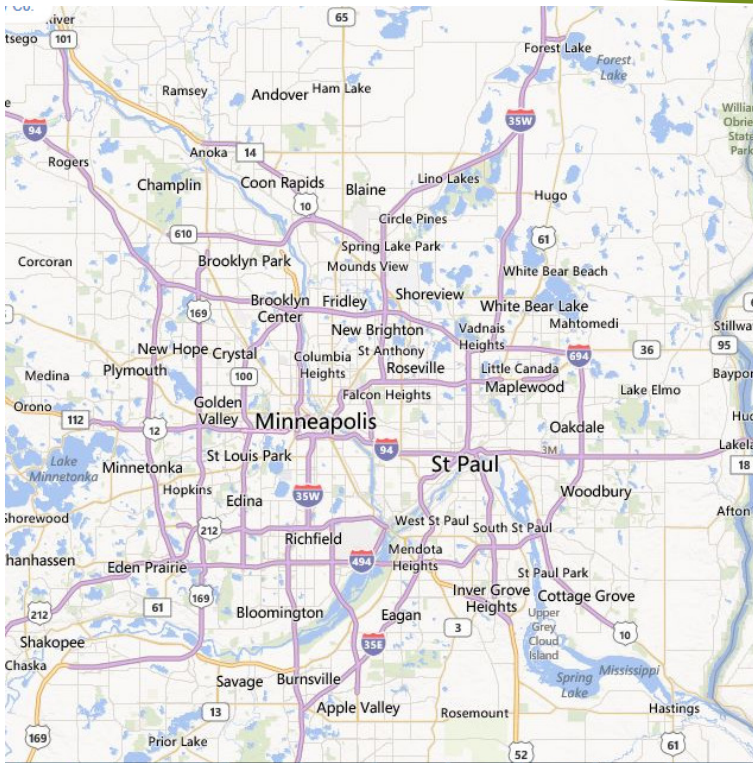
# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: MnDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014

PRESENTED BY STEVE MISGEN, MNDOT

100



- ▶ Operates about 700 signals (Mpls/St. Paul Metro area)
  - ▶ 250 signal on i2 central system
  - ▶ 450 on ARIES dial-up
- ▶ Econolite ASC2/ASC2S or ASC3 controllers
- ▶ Signal Performance Measure
  - ▶ 83 on Smart Signal
  - ▶ 21 on Utah SPM

# Smart Signal

- ▶ University of Minnesota
  - ▶ Henry Liu
- ▶ Minnesota Department of Transportation
- ▶ <http://dotapp7.dot.state.mn.us>
  - ▶ iMonitor – “Real-time” Level of Service
  - ▶ iMeasure – Data extraction tool



# Smart Signal



iMonitor™ / iMeasure™

System Overview

System Check

Site Access

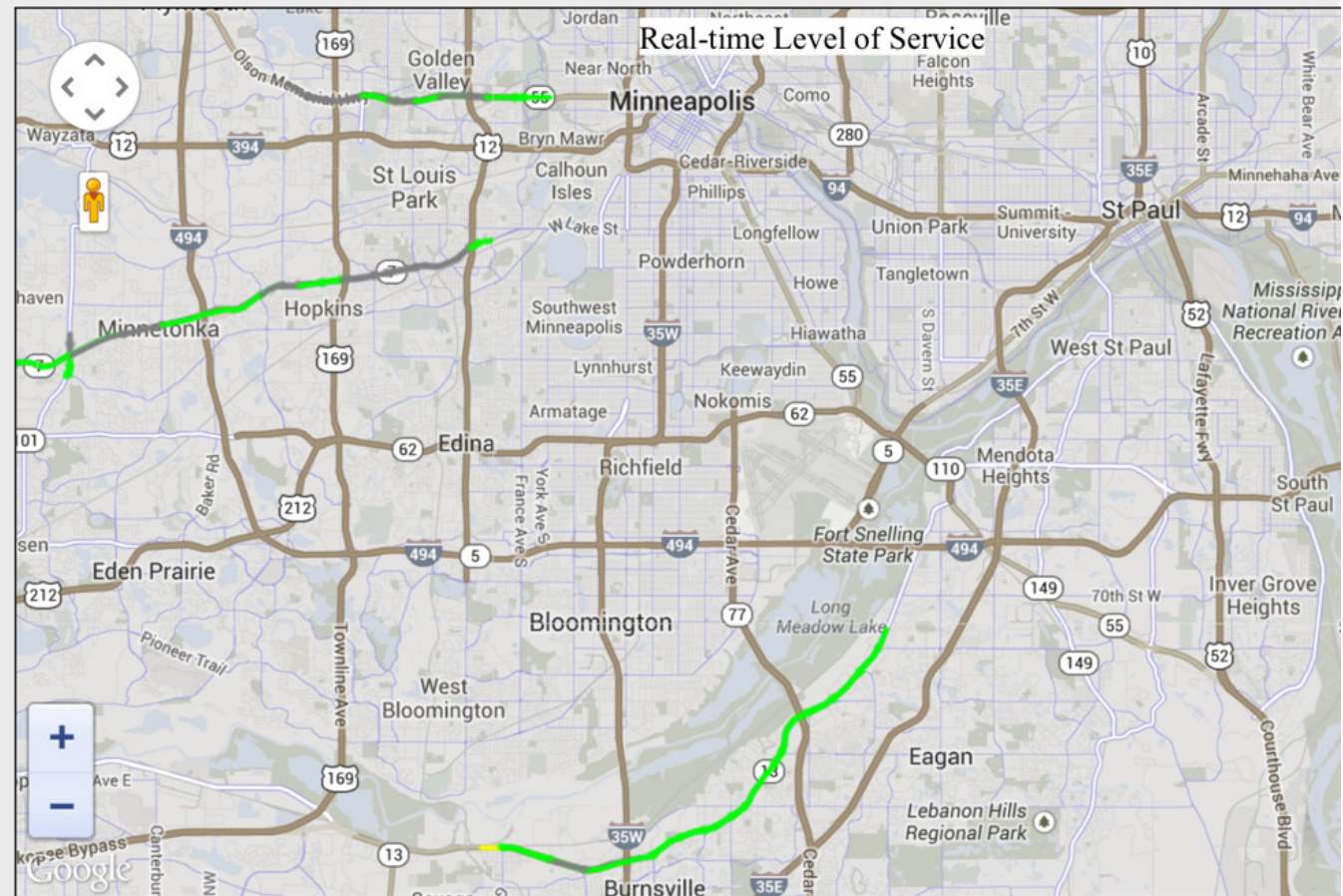
Help

LOS Legend:

- A&B
- C&D
- E
- F
- Real time data not available

Link Delay Legend:

- < 20 Sec./Veh.
- Between 20 and 55 Sec./Veh.
- Between 55 and 80 Sec./Veh.
- > 80 Sec./Veh.
- Real time data not available

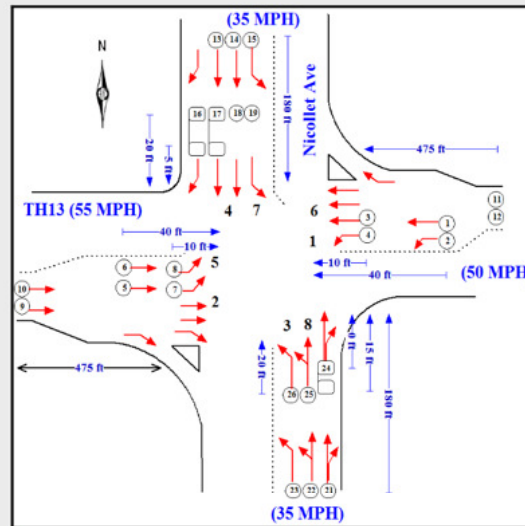


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# Smart Signal

- Performance Assessment
- Optimization Preparation
- Fine-tuning Analysis
- Performance Comparison
- Retiming Benefits
- Periodic Report
- Help

## Volume Output



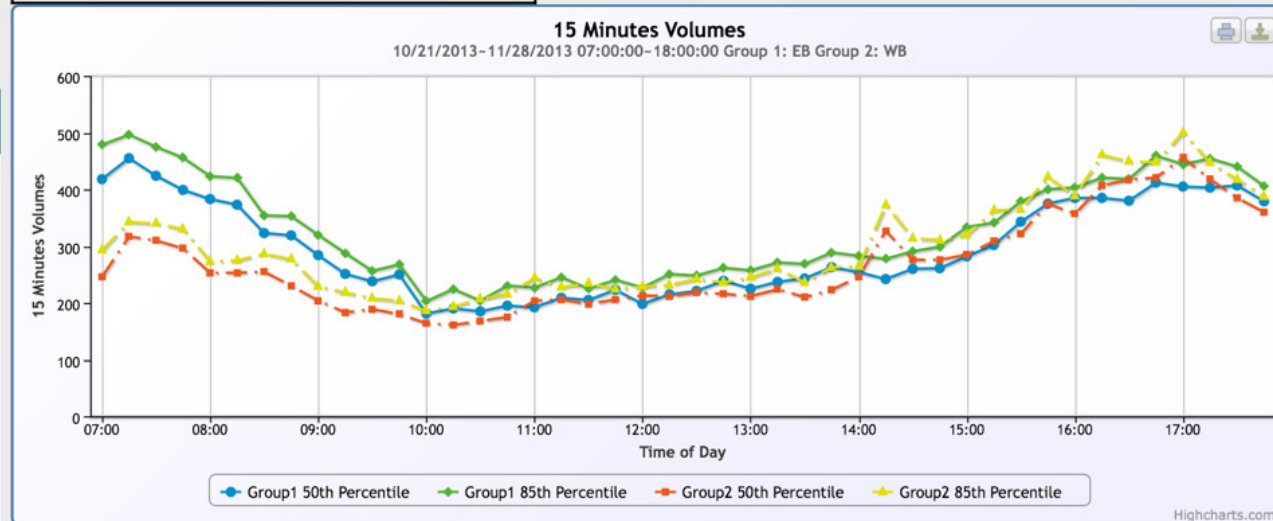
Intersection: TH13/Nicollet Approach Selection Mode: ☒ Normal ☐ Expert

Approaches (Group 1): Select Approaches (Group 2): Select

Start Date: 10/21/2013 End Date: 11/28/2013 Day of Week: Select Days

Start Time: 07:00:00 End Time: 18:00:00 Interval: 15 Minutes

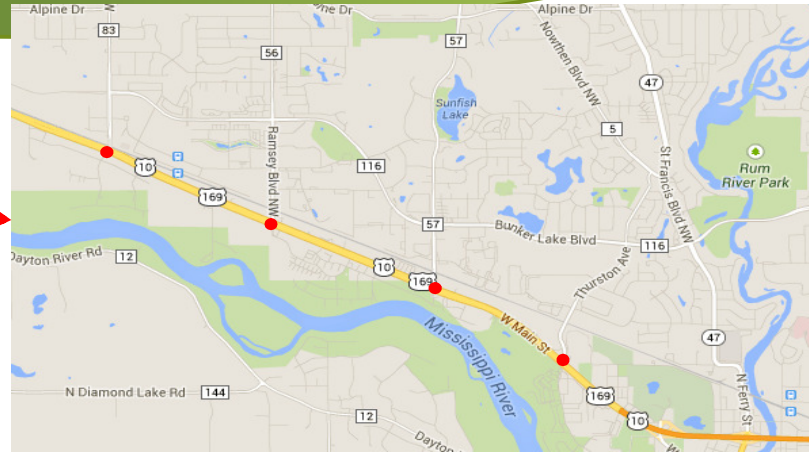
Plot Save Data





## Develop New Timing Using High Resolution Data collected from SmartSignal

## Develop New Timing Using High Resolution Data collected from SmartSignal



- ▶ 4 fully-actuated signals
- ▶ High speed 60-65 mph posted
- ▶ 33,000-68,000 AADT
- ▶ 7 TOD plans
- ▶ Last retimed 2009

# Signal Timing Development

## Standard Method

- Data Collection
  - Manual Turning Movement Count – 12 hour
  - System Detectors
- Synchro – approximation of splits & cycle lengths
- Implementation & fine turning completed by time space diagram and field observations
- Before/After Comparison using Travel Time Studies

## Improved Method

- Data Collection
  - Automated collection averaged over Sept-Oct for each movement (M-Th, F, S & S)
- Synchro - Time-space diagram for best two-way progression
- Implementation & fine turning completed by time-space diagram and field observations
- Smart Signal – monitor and make adjustments to insure efficiency
- Before/After Comparison using signal performance metrics

# Volumes

September/October 2013 85th % Weekday Volumes - TH 10 at Thurston Avenue



# Before/After Performance Comparison

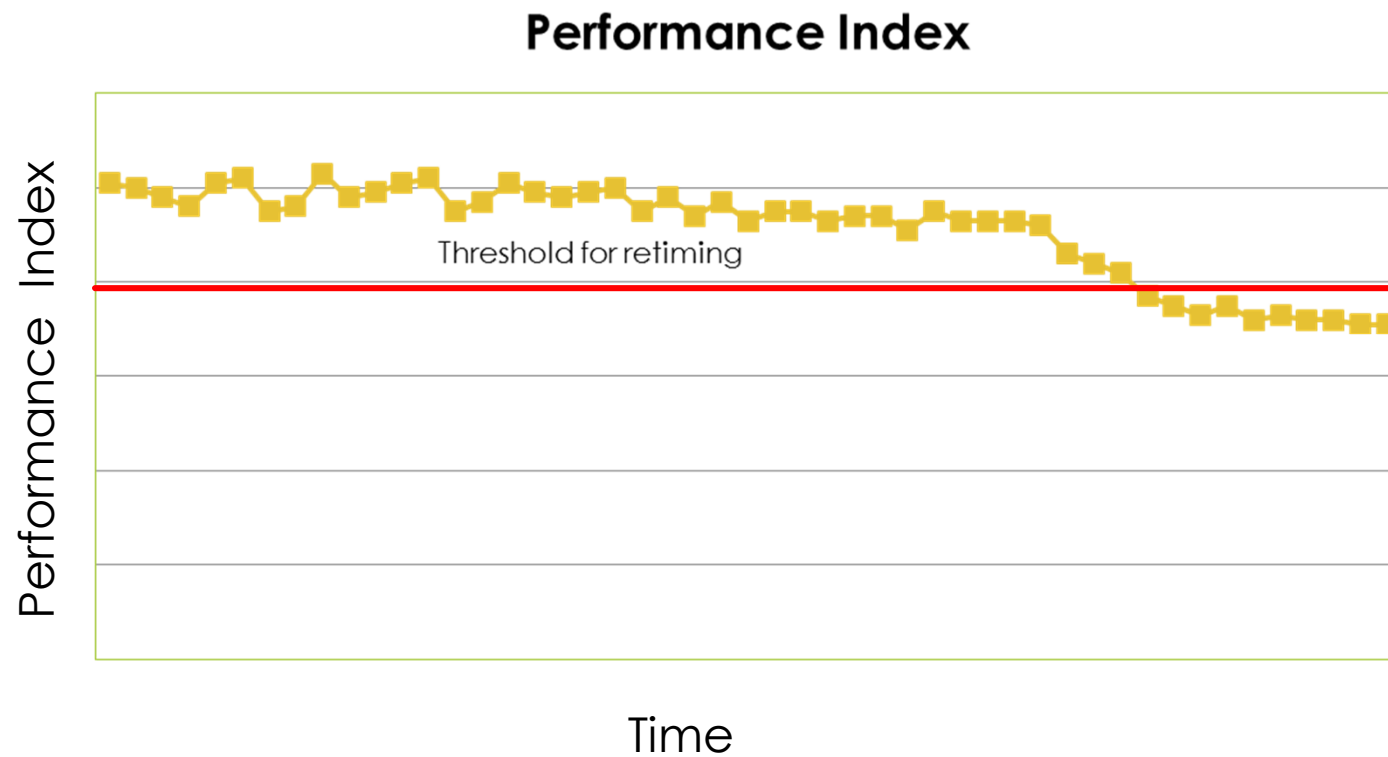
Performance Comparison - Peak Hours (Total Intersection)												
TH 10 at Sunfish Blvd	Volume (# of vehicles)		Total Delay (Hours)		Number of Stops		Maximum Queue (Feet)		Saturation Level		% of Vehicles Arriving On Green	
	Total Intersection		Total Intersection		Total Intersection		Total Intersection		Total Intersection		Total Intersection	
Time of Day	Before <sup>1</sup>	After <sup>2</sup>	Before <sup>1</sup>	After <sup>2</sup>	Before <sup>1</sup>	After <sup>2</sup>	Before <sup>1</sup>	After <sup>2</sup>	Before <sup>1</sup>	After <sup>2</sup>	Before <sup>1</sup>	After <sup>2</sup>
AM Peak Hour 7:00 am to 8:00 am	3426	2906	30.15	21.9	2545	1484	613	121	0.74	0.54	0.7	0.84
Mid-Day Peak Hour 1:30 pm to 2:30 pm	2882	1982	14.42	11.27	1281	773	226	68	0.64	0.38	0.68	0.9
PM Peak Hour 4:30 pm to 5:30 pm	4082	2844	28.98	17.81	2352	1040	589	99	0.92	0.53	0.74	0.87
Total 5:00 am to 10:00 pm	46065	33607	256.41	177.01	21340	11301	261	58	0.63	0.34	0.6	0.9

# Future Plans

- ▶ Performance Index
  - ▶ based on volume, delay, number of stops, max queue length, saturation level & percent of vehicles arriving on Green
  - ▶ Calculate the PI for a given period on time (PM Peak) over a period of time (every Wednesday for the past year)
  - ▶ Track the change on performance over time
    - ▶ **When do you need to retime!**
- ▶ Time-space Diagram
  - ▶ Real-time TSD based on detector actuations
- ▶ Performance Metrics
  - ▶ Emissions – CO<sub>2</sub> fuel consumed

# Future Plans

## Performance Index Over Time





A large green shape with a rounded bottom and a tab on the right side, containing the title text.




# MnDOT Signal Performance Measures

Steve Misgen, PE, PTOE  
MnDOT – Metro District  
Traffic Engineer  
[Steve.misgen@state.mn.us](mailto:Steve.misgen@state.mn.us)

# Find out more:

<http://tig.transportation.org>



AASHTO TIG	TIG Home					
<ul style="list-style-type: none"><li>● TIG Home</li><li>● About TIG ▶</li><li>● Focus Technologies</li><li>● Executive Committee ▶</li><li>● Feedback</li><li>● Additionally Selected Technologies</li><li>● TIG-Solicitation</li><li>● Lead States Team Guidance ▶</li></ul>	<p>AASHTO &gt; AASHTO Technology Implementation Group &gt; TIG Home</p> <hr/> <p>AASHTO's Technology Implementation Group — or TIG — scans the horizon for outstanding technology and invests time and money to accelerate their adoption by agencies nationwide.</p> <p>Each year, TIG selects a highly valuable, but largely unrecognized procedure, process, software that has been adopted by at least one agency, is market ready and is available for use by other agencies.</p> <p>Guided by the vision of "a culture where rapid advancement and implementation of high payoff, expectation of the transportation community," TIG's objective is to share information with AASHTO member agencies, and their industry partners to improve the Nation's transportation system.</p> <p>Recently selected technologies with links to additional information are listed below. Also, you may find <a href="#">Additionally Selected Technologies</a> categorized by AASHTO subcommittee interest area.</p> <table border="1"><thead><tr><th>Lead States Team Focus Technologies</th><th>Additionally Selected Technologies</th></tr></thead><tbody><tr><td><p><b>2013 Focus Technologies</b></p><div></div><ul style="list-style-type: none"><li>• <a href="#">Automated Traffic Signal Performance Measures</a></li><li>• <a href="#">UPlan Phase II</a></li></ul><p><b>Prior Four Years Focus Technologies</b></p><ul style="list-style-type: none"><li>• <a href="#">Embedded Data Collector</a></li><li>• <a href="#">Environmental Planning GIS Tools</a></li></ul></td><td><p><b>2013 ASTs</b></p><ul style="list-style-type: none"><li>• <a href="#">Double Crossover Diagonal</a></li></ul><p><b>Prior Four Years ASTs</b></p><ul style="list-style-type: none"><li>• <a href="#">Anonymous Wireless Time Data Collection</a></li><li>• <a href="#">Curvature Extension</a></li></ul></td></tr></tbody></table>		Lead States Team Focus Technologies	Additionally Selected Technologies	<p><b>2013 Focus Technologies</b></p> <div></div> <ul style="list-style-type: none"><li>• <a href="#">Automated Traffic Signal Performance Measures</a></li><li>• <a href="#">UPlan Phase II</a></li></ul> <p><b>Prior Four Years Focus Technologies</b></p> <ul style="list-style-type: none"><li>• <a href="#">Embedded Data Collector</a></li><li>• <a href="#">Environmental Planning GIS Tools</a></li></ul>	<p><b>2013 ASTs</b></p> <ul style="list-style-type: none"><li>• <a href="#">Double Crossover Diagonal</a></li></ul> <p><b>Prior Four Years ASTs</b></p> <ul style="list-style-type: none"><li>• <a href="#">Anonymous Wireless Time Data Collection</a></li><li>• <a href="#">Curvature Extension</a></li></ul>
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<p><b>2013 Focus Technologies</b></p> <div></div> <ul style="list-style-type: none"><li>• <a href="#">Automated Traffic Signal Performance Measures</a></li><li>• <a href="#">UPlan Phase II</a></li></ul> <p><b>Prior Four Years Focus Technologies</b></p> <ul style="list-style-type: none"><li>• <a href="#">Embedded Data Collector</a></li><li>• <a href="#">Environmental Planning GIS Tools</a></li></ul>	<p><b>2013 ASTs</b></p> <ul style="list-style-type: none"><li>• <a href="#">Double Crossover Diagonal</a></li></ul> <p><b>Prior Four Years ASTs</b></p> <ul style="list-style-type: none"><li>• <a href="#">Anonymous Wireless Time Data Collection</a></li><li>• <a href="#">Curvature Extension</a></li></ul>					

# ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs  
April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies  
May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ Critical Infrastructure Elements for SPMs  
June 11, 2014, 12:00 pm to 1:30 pm. Eastern



Jamie Mackey  
UDOT



Amanda Stevens  
INDOT



Alex Hainen  
Purdue



Steve Misgen  
MnDOT

# Thank you.

## QUESTIONS?

<http://tig.transportation.org>



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